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WHAT IS CAMAC?

CAMAC is the designation of rules for the design and use of modular electronic data-handling equipment. The rules offer a standard scheme for interfacing computers to data transducers and actuators in on-line systems. The aim is to encourage common practice and compatibility between products (both hardware and software) from different sources.

CAMAC was originally defined by the ESONE Committee, a multi-national inter-laboratory organisation of data-processing experts from nuclear institutes. However, CAMAC is concerned with data-handling problems that are not specific to nuclear research and is being applied already in many other fields. Working groups of the ESONE Committee are considering further hardware and software aspects of systems for measurement and control, and maintain close liaison with similar working groups of the USAEC-NIM Committee and also with the International Electrotechnical Commission.

CAMAC is a non-proprietary specification which can be adopted and used free of charge by any organisation and without any form of permission, registration or licence action.

The CAMAC Bulletin, a publication of the ESONE Committee, disseminates information on CAMAC activities, commercially available equipment, applications, extensions and explanations of the rules.

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 Decimal Classification of CAMAC Instrumentation. O.Ph. Nicolaysen.

CONTRIBUTIONS TO FUTURE ISSUES'

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New Products and Manufacturer News:

Product Guide:

Bibliography and any ESONE News Items, etc.:

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On the cover: View of Capitolium in Rome where in 1957 the first six Members of the European Communities signed the "Treaty of Rome". The ESONE Committee held its Annual General Assembly at Rome in 1968.

CAMAC

bulletin

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KOMMISSION

DER EUROPÄISCHEN GEMEINSCHAFTEN

RALF DAHRENDORF MITGLIED DER KOMMISSION

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Liebe Leser.

Die Kommission der Europäischen Gemeinschaften fördert seit langer Zeit die Tätigkeit des ESONE Komitees. Mit Befriedigung kann sie heute feststellen, dass diese Entscheidung richtig war. Die CAMAC-Vereinbarungen - wichtigste Initiative des ESONE Komitees in den letzten Jahren - sind weithin bekannt und werden in vielen Anwendungsbereichen mit Erfolg berücksichtigt. Diese Entwicklung wurde in den letzten drei Jahren nicht unwesentlich beeinflusst durch die Herausgabe des CAMAC-Bulletins, welches das ESONE Komitee mit Unterstützung der Kommission der Europäischen Gemeinschaften veröffentlicht.

Als das für Forschung, Wissenschaft und Bildung verantwortliche Kommissionsmitglied begrüsse ich das Ziel, welches mit der Herausgabe des CAMAC-Bulletins verfolgt wird:

Verbreitung der für die Anwendung in Kernforschungszentren erarbeiteten Methoden zur Automatisierung von Mess-, Steuerungs- und Regelvorgängen, um sie in anderen Bereichen der wissenschaftlichen Forschung, in der Industrie und für öffentliche Dienste nutzbar zu machen.

Dieses Ziel steht in Einklang mit den entschiedenen Bemühungen der Kommission, im Rahmen ihrer Wissenschafts- und Technologiepolitik alle Möglichkeiten der Informationsverbreitung auszuschöpfen.

Wichtige weitere Voraussetzungen für einen erfolgreichen weltweiten Informationsaustausch sind nach meiner Überzeugung Gedankenaustausch und persönliche Kontakte auf übernatio-naler Basis. Das gilt auch für die Verbreitung von CAMAC. Ein erster Schritt in diese Richtung ist das "First International Symposium on CAMAC in Real-Time Computer Applications" , welches die Kommission der Europäischen Gemeinschaften in Zusammenarbeit mit dem ESONE Komitee vom 4. -6. Dezember 1973 in Luxemburg veranstaltet.

Ich wünsche der Veranstaltung einen erfolgreichen Verlauf und kann Ihnen versichern, dass die Kommission auch weiterhin bemüht sein wird, Initiativen zur Förderung von CAMAC wirkungsvoll zu unterstützen.

Rael Jawe MJ.

Ralf Dahrendorf Mitglied der Kommission

Dear Reader.

For some time now the Commission of the European Communities has supported the activities of the ESONE Committee. It is with satisfaction that the Commission is now able to conclude that the decision to do this was right. The CAMAC Standard—the most important development and work of the ESONE Committee during recent years— is now well known far and wide and successfully used in many areas of application. This expansion has been directly influenced during the last 3 years by the CAMAC Bulletin, a publication of the ESONE Committee supported by the Commission.

Inducted autring the tast 3 years by the CAMAC builtin, a publication of the ESONE Committee supported by the Commission. As the Member of the Commission responsible for Research, Science and Education, I welcome the aims of the Bulletin, which are to diffuse into other areas methods for the automation of measurement and control that were developed for applications in the Nuclear Research Centres and to promote useful applications in scientific research, industry and in public services. These aims are in agreement with the policies of the Commission in science and technology and its determination to use all possible methods for dissemination of information. I believe that another important condition for a successful world-wide exchange of information is based on the exchange of ideas and personal contacts between people from many nations. This certainly applies to the promotion of CAMAC and a first step of this kind is the 1st International Symposium on CAMAC in Real-Time Computer-Applications which is being organised by the Commission, in collaboration with the ESONE Committee, for 4-6 Decem-ber 1973 in Luxembourg. I wish this conference to be a great success and I assure you that the Commission will be anxious to further support initiatives for the promotion of CAMAC.

Ralf Dahrendorf Member of the Commission

Ralf Dahrendorf

Ralf Dahrendorf BIOGRAPHICAL NOTE Born 1929. Studied philosophy and classical philology. Degrees of Doctor of Philosophy (Hamburg) and Ph.D. (London). Ordinary Professor for Sociology at the Universities of Hamburg, Tübingen and Konstanz.

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INTRODUCTION TO CAMAC

MODULARITY AND CAMAC

by

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Received August 1973

SUMMARY The instrumentation associated with nuclear sciences has always taken advantage of new dataprocessing techniques. The early introduction of the modular concept and its continuous development led to the CAMAC Standard. The modular concept is described and the advantages of CAMAC are examined.

INTRODUCTION

A long accepted practice of electronic engineers has been to break down large measurement and control systems into small self-contained units for ease of specification, development, production, system fault-diagnosis and physical convenience. As in many other areas (building construction, furniture, etc.) the term 'modular' has been applied to equipment units whose physical size is, in one respect or another, a multiple of a basic dimension. A selection of these modular units can be combined in a standard framework for operational convenience, lower costs or just general tidiness. A classical example is the 19" international standard instrument-panel and rack¹. Rectangular panels, all of horizontal dimensions 19" but of heights $n_0 U$ (where U = 1.75 inches), can be fitted across the front aperture of a standard rack. Chassis of given maximum horizontal and vertical dimensions can be fitted behind these front panels to contain the circuit components.

A more recent concept is to design units as unifunctional modules that are physically and operationally compatible and inter-changeable and can therefore be used as the basis of many systems² both simple and complex. This concept began to develop during the late '50s and early '60s, when transistors made it possible to have relatively small unifunctional modules which could be fitted into a framework within a 19" front-panel chassis. With a wide selection of these unifunctional modules (e.g. amplifiers, filters, drivers, registers, etc.) to choose from, practically any measurement or control system could be assembled in these frameworks, and mounted in racks^{3, 4}.

PHYSICAL COMPATIBILITY

Such a framework (shelf, bin, crate or drawer) provides a volume whose height (H) is less than n_0U (to allow for horizontal tie-bars), whose width (W) is less than the clearance in the standard 19" rack (to allow for vertical tie-bars) and whose depth (D) is limited only by what is physically reasonable. This volume (V) can be sub-divided into equal subvolumes of $V/(n_h.n_d.n_w)$, where n_h , n_d , n_w are the dividing factors, and each sub-volume can be occupied by an electronic unit. However, for ease of access, etc., these sub-volumes are usually created by sub-division of the horizontal dimension (W) only, and the modules thereby have front aspects of horizontal width W/n_w , height n_0U and any depth (D). For any self-compatible set of modules, the values and tolerances of W, D, n_0 and n_w have to be fixed.

The design of every modular unit scheme defines the physical dimensions of the sub-units and the framework into which these units can be assembled to form systems. Schemes that have plug-in units also define the physical location and features of electrical mating parts, and the guidance and fixing of modules into the framework.

A comprehensive modular unit scheme specifies other characteristics in addition to physical dimensions. These additional levels of compatibility are listed below in decreasing order of occurrence in existing modular schemes.

Power Supplies

This specification defines the voltage, ripple, impedance and other characteristics of the power supplies that a unit can expect to find available in a system. It includes the allocation of pins on mating connectors of plug-in units to specific power lines, and also their interconnection to satisfy specified losses, common-earth coupling, etc.

Signals and Connectors

The interconnections between functional modules that can be combined in various ways to make up different systems need more careful standardisation than interconnections between equipment specific to only one system. Signal outputs from one unit must drive inputs of another unit via an inter-connecting cable or network having defined characteristics, without the need for interposed buffers. Otherwise the flexibility of a modular system can be much reduced.

Data Transfer Characteristics

When digital information has to be transferred from one unit to another in an assembly of units, there must be defined procedures for doing this, if the highest degree of compatibility is to be achieved. These procedures can involve, for example, specific codes for addressing and commanding units, the allocation of significance to bit order, and the timing of transfer cycles.

Ergonomic Features

The front-panels of units are often an interface between the operator and the measurement/control system. They are fitted with control-knobs, switches, displays, lamps, meters, indicators, etc. Each such item needs to be labelled, to show its function, and positioned where it can be seen and used conveniently. This can be achieved by rules covering frontpanel layout and by a glossary of terms and abbreviations. The glossary prevents the use of the same word on two different units to mean different things or different words on different units to mean the same.

ADVANTAGES OF MODULARITY

The degree to which a particular scheme can claim the following advantages depends on the levels of compatibility specified in the scheme.

- Modularity provides flexibility in system size and configuration.
- Interchangeability permits rapid replacement of faulty units and this in turn leads to short "down-times".
- Compatibility of characteristics of units enables a rationalisation of documentation and test procedures giving low-cost diagnostics and maintenance.
- The use of the same types of units in different systems enables stocks of units and spares to be kept small, thus giving a high utilisation of capital investment. By concentrating the demand on fewer types it allows quality control on batch production of units.
- Existing systems can be expanded or up-dated at only marginal cost.
- New facilities in the range of units can be added quickly and for low development costs.
- Valuable and costly design effort need not be wasted on problems that are already solved by the scheme (chassis size, power supply, methods of data transfer, etc.).
- Possible solutions to a particular measurement or control problem can be evaluated rapidly by using a basic range of units.
- Technical and maintenance staff who are familiar with the scheme can be interchanged between projects.

DISADVANTAGES OF MODULARITY

A fully comprehensive modular scheme has also these disadvantages:

- The development of the compatibility rules for a scheme can be costly and prolonged.
- Extreme difficulty can be experienced in up-dating or modifying the compatibility rules, as technologies change or develop, without rendering earlier units obsolete.
- Units will contain features which, though relevant in the total applications context, may not be necessary for a specific application, thereby increasing cost and unreliability.
- Acceptance of a particular scheme involves commitment to that scheme thereafter.

CAMAC

The CAMAC specifications cover all important aspects of compatibility and bring the advantages of comprehensive modularity. The disadvantages also apply, but their effect has been made small either by the design principles of CAMAC or by its multinational acceptance, as the following examples show.

Although CAMAC has taken, so far, about seven years, and an estimated \$5M (equivalent) to develop, it is now a proven standard and can be used free of charge by anyone.

Commitment to CAMAC is not restrictive since equipment and expertise is available from many sources throughout the world. The CAMAC standard is not tied to a particular manufacturer of computers or peripherals, and is multinational in origin. The independence that CAMAC gives to a user is a tremendous benefit, far outweighing the disadvantages which normally arise from commitment to a standard.

Some features of CAMAC give redundancy in certain applications. For example, the CAMAC highway is capable of 24-bit parallel transmission, and appears somewhat excessive for an 8-bit parallel requirement. However, CAMAC does not specify that systems must use all 24 bits. A system employing modules and controllers with only an 8-bit capability can be totally CAMAC-compatible. The only redundancy would be edge-connector contacts and Dataway wiring in the crate, and Dataway connector pins on the module. The cost of this redundancy per station would be less than 2% of the cost of a typical CAMAC module. Clearly, the use of a 24-bit crate and a controller with 24-bit capability in a system employing 8-bit modules involves greater redundancy, but even this could be economically attractive if the controller is already available, compared with designing a specific controller for a single requirement.

Finally, design features of CAMAC such as the address, demand handling and data-width, allow advantage to be taken of new technologies, such as large-scale integration, and low-cost large-capacity storage. Therefore it should be possible, for some time to come, to accommodate within the CAMAC standard any evolution of electronic data-processing relevant to the real-time, on-line applications for which CAMAC provides a powerful multiplexing interface.

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by

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SUMMARY Advance information is given on a new CAMAC serial highway, complementing the existing parallel Branch Highway (EUR 4600 e). This serial highway can be used, either alone or in conjunction with modems, over longer distances and in noisy environments. It can be connected to standard communications interfaces available on most computers.

INTRODUCTION

The CAMAC Serial Highway described in this paper is the result of work carried out jointly by the NIM-CAMAC Dataway Working Group (Chairman, F.A. Kirsten) and its Serial Subgroup (Chairman D.R. Machen), and the ESONE Dataway Working Group (Chairman, H. Klessmann) and its Serial Subgroup. This paper is published with the permission of the chairmen of the Working Groups.

The existing parallel Branch Highway (EUR 4600e) has proved to be a successful basis for interconnections in compact multicrate systems. There are Branch Highway interfaces for many popular minicomputers, and this has done much to encourage widespread use of the highway. On the other hand, use of the Branch Highway in simple systems and with less popular computers has undoubtedly been hindered by the need to have such an interface. Branch Highway systems can work over distances of a few kilometres using balanced-signal extenders, but the cost and installation of 65-pair cable are limitations.

The Serial Highway primarily provides much simpler interconnections than the 65 signals of the parallel Branch. It allows multicrate systems to use readily-available communications facilities, and provides protection against transmission errors. However, each CAMAC operation involves transmitting a sequence of messages, and generally takes longer than operations on the parallel Branch. Thus it does not supersede the parallel Branch, but is complementary to it in applications where simple interconnections are of major importance.

The Serial Highway can be connected to a computer through an interface unit (serial driver) that organises some or all of the message sequence by hardware. However, the message format is such that the highway can also be connected through a simple adapter to low-cost communications interfaces that are available on most computers. In this case the message sequence is organised by software in the computer. The Serial Highway is thus useful as a simple means of connecting a computer to one or more CAMAC crates, even when these are not remote.

ORGANISATION

Each serial crate controller (SCC) and serial driver (SD) is connected to the highway through two D (Defined) ports for input and output, respectively.



Fig. 1 Serial Highway: Unidirectional Open Loop SCC = Serial Crate Controller SD = Serial Driver

The crate controllers are connected in a chain, looped between the two ports of the serial driver (Fig. 1). The same unidirectional route is used for all messages. Each crate controller monitors all messages received at its input port, and retransmits at its output port all those that are not addressed to it. Thus, command messages are passed from the output port of SD through intervening crate controllers to the input port of the addressed SCC. Similarly, reply messages are passed from the output port of the addressed SCC through intervening crate controllers to the input port of SD. Demand messages may be generated at appropriate times by any SCC, and are also passed to the input port of SD.

All messages are structured as sequences of 8-bit bytes, consisting of six bits of information, one delimiter bit for message synchronisation, and one parity bit for error detection. Each message includes a SUM byte with a checksum of the information bits in the preceding bytes. The two-coordinate combination of parity and checksum is a powerful means of error detection. In the END byte of each message the delimiter bit forces all SCC's to await the beginning of a new message. Between messages the SD transmits WAIT bytes.

Each CAMAC operation involves a command message of 6 or 10 bytes (C, N, A, F, W1-4 if required, SUM and END), and a reply message of 7 or 3 bytes (C, STATUS, R1-4 if required, and ENDSUM).

The ports have provision for bit-serial or byteserial mode. In bit-serial mode the 8 bits of a byte are transmitted serially, with a start bit and 1 or 2 stop bits making up a frame of 10 or 11 bits. There is a bit-rate clock signal at the ports, and each SCC derives a byte-rate clock from the framing bits. In byte-serial mode the 8 bits of each byte are transmitted in parallel, and there is a byte-rate clock signal at the ports.

In all other respects, such as message structure and signal standards, the two modes are identical.

INTERCONNECTIONS

The D ports on SCC have separate balanced current-mode circuits for information and clock. These can be connected directly to the next SCC in the chain over moderate distances, using dedicated twisted pair cables. Alternatively, any section of the highway may include communications terminals, such as modems to operate over longer distances and public telephone networks. Between modems the information and clock may be combined into one unidirectional channel. The Serial Highway loop may be folded back on itself in order to use duplex channels and modems (Fig. 2). There may





be a mixture of various communications channels and direct connections, depending on the needs of different sections of the highway. However, the clock rate is determined by SD or the communications equipment, and must be uniform throughout the loop.

Other options are available to bypass individual crate controllers or parts of the loop, so that the remainder of the system can continue to operate when equipment is faulty or withdrawn from service. The bypass switching can be controlled remotely from SD.

DEMAND HANDLING

A crate controller whose demands have been enabled by SD responds to a Dataway LAM by generating a 3-byte demand message (C, GL, ENDSUM). The crate number indicates the source of the demand. In simple systems this may merely initiate a poll of LAM sources in the crate. The GL byte is derived from an SGL Encoder via a connector on the SCC, and its significance is a function of the Encoder or patching on the connector. For example, it could indicate the GL number of the highest-level demand in the crate.

The SCC interposes the 3-byte demand message between two messages in the incoming stream and then removes three WAIT bytes from the same, or some later, point in the stream. In the meantime, incoming messages are diverted through a 3-byte delay and the SCC cannot generate another demand.

There is a risk that demand messages may be corrupted and lost. Hence, SCC includes a timer to detect unserviced demands and initiate a high-level demand message.

PERFORMANCE

The time to implement a CAMAC operation depends on factors such as

- The clock rate. This can be 5 MHZ for direct connections between the D ports, but is typically much less when using public telephone channels.
- The signal propagation time around the loop. This will usually be dominated by the delay of one clock period (one bit or one byte) in each SCC needed to allow the information signals to be sampled and reconstituted.
- The number of 3-byte demand delays that are temporarily present in the loop.

An efficient directly connected byte-serial system with few crates can implement a command in about 5μ s, similar to the parallel Branch. A directly connected bit-serial system with the maximum number of crates takes about 50 µs. A system operating over telephone speech circuits is much slower.

CONCLUSION

The CAMAC Serial Highway uses a sequence of serial byte-organised signals in place of the many parallel signals of the Branch Highway. It therefore has a complementary role where 65-pair cable cannot be installed, or where the CAMAC system can be controlled by a software-driven interface on the computer.

The Serial Highway is fully compatible with the basic CAMAC specification, EUR 4100e (1972), and can implement the full range of CAMAC operations. It is based on the same concepts as the Branch Highway, but has a 6-bit crate address, implements demand handling in a different way, and provides for error detection and recovery.

Workers on other serial systems ^{1,2}, which are significantly different, have made valuable contributions to this work.

A detailed description of the serial system organisation is being prepared. This will include a recommended set of features for a fully interchangeable crate controller (Serial Crate Controller Type L). A formal specification of the serial system and SCC-L will be issued later.

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APPLICATION NOTES

A DATA ACQUISITION SYSTEM BASED ON CAMAC AND SUPPORTED BY BASIC AND FORTRAN

by

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Received 7th May 1973

SUMMARY A 12k minicomputer has been used with CAMAC and NIM equipment in an intermediate-energy nuclear scattering data acquisition system. The system is programmed in BASIC or FORTRAN, with sub-routines for input/output via CAMAC. The version with BASIC is most useful to experimenters, except where higher data rates require the use of FORTRAN.

INTRODUCTION

This paper describes the data acquisition system (DAS) developed for a 50 MeV π^+ d differential cross section scattering experiment using a NOVA1200 computer. An incident pion beam strikes a liquid deuterium target and scattered particles are detected in a stopping plastic scintillator. The pion trajectory is determined by spark chamber arrays. The data acquisition program was initially developed using the BASIC interpreter. This commonly known interactive language allowed the experimenters to edit and expand the DAS easily. When a final configuration was reached for production running, the system language was changed to FORTRAN to speed up the data logging.

SYSTEM DESCRIPTION

The system was built with the idea of incorporating an easy-to-use, flexible programming language with the CAMAC specification. High level languages familiar to most scientists were used. The system speed is limited by the CAMAC cycle time, by details of the operating system, and, most important, by the program language speed. The two distinct portions of an experiment, debugging and full scale data acquisition, have different program requirements. Initially, ease of program editing is the most important consideration. Later, speed of event handling replaces it. These changes have been met by using two different programming languages, BASIC and FORTRAN.

System Hardware Interfacing

Two system interfaces are required, one to translate a fast NIM coincidence signal into a computer interrupt to signal an event, the other the standard CAMAC interface. In principle, the standard CA-MAC interface with an interrupt feature is capable of event interrupting 1 and has been used in other applications. 2

The NOVA-NIM Interrupt Unit is daisy-chained onto the NOVA I/O cable before the Branch Highway Driver, BHD. The "event definition" pulse is input to it, causing this device to request servicing. The service routine initiates transfer of experimental data from CAMAC to the NOVA. During the transfer, the interrupt unit outputs a NIM pulse, used to inhibit NIM unit responses to new events.

Branch Highway Driver

The Master Branch Highway Driver is designed to interface a NOVA computer to a CAMAC system. It can drive up to seven crates directly. It can also drive three Slave BHD's which in turn drive seven crates, bringing twenty-eight CAMAC crates under the control of the Master BHD.¹ This is a non-standard CAMAC feature and necessitates a Branch Highway code in each command as well as the standard CNA.

To initiate a command to the CAMAC system, the three sixteen-bit buffers of the BHD must be loaded from core. A command requires specification of a three-bit crate number C (1 to 7), a five-bit station number N (1 to 24) and a four-bit sub-address A. A five-bit function code F is also necessary. A four-bit branch code must be specified if the Master/Slave configuration is used.

With the buffers loaded in the above manner a start pulse from the computer will initiate a CAMAC cycle. An error flag is returned indicating the success or failure of the CAMAC cycle.

BASIC

BASIC was the programming language chosen for use during system installation and commissioning. BASIC is interactive. Programs can be halted, edited, and restarted from a teletype at any time during execution without otherwise affecting them. Since BASIC is an interpretive system, storing the teletype code program line-by-line, it is slow. Assembler language subroutines for CAMAC operations were added to the BASIC system using a special CALL feature of DATAGEN BASIC.*

^{*} DATAGEN of CANADA, Ltd. Hull, Quebec. Copywrite 1970.

CALL 1, (C), (N), (A), (F), D, E executes a CA-MAC read operation. The user enters decimal numbers for C, N, A, and F to read or to read-and-clear a module. Data is returned as variable D. A zero is returned in E for a successful CAMAC operation or a CAMAC error code is returned in E for an unsuccessful operation. CALL 2, (C), (N), (A), (F), (D), E is used analogously to write data into a module. Either operation takes about 10 msec although only 30μ sec of that is the actual CAMAC operation.

Single CAMAC read or write instructions are used to check the operation of modules. Even during commissioning, however, the execution times of single CAMAC instructions have been excessive. Sequences of CAMAC instructions can be defined by CALL 4711, J, I, C, N, A, F, D, where J is one of five allowed sequences and I is one of 10 allowed sequence elements. CNAF bear the usual CAMAC significance. CALL 3, J, Z(J, 1), E allows the execution of the CAMAC sequence J with the resulting data returned to row J of array Z. A zero returned for E indicates a successful sequence execution while other E values indicate errors during the sequence execution. The execution speed is much shorter (about 1 msec per CAMAC instruction) than single CAMAC instructions, since an assembled program is used when the sequence is being executed. The time difference between this and the CAMAC operation time (40 μ sec) is due to data conversion to the BASIC floating point format.

BASIC responds only to teletype interrupts. CALL 4 is used for program access when event interrupts are expected. It takes program control from BASIC and puts the system into a loop awaiting the arrival of an event interrupt. Program control is returned to BASIC when an event interrupt occurs. CAMAC sequence calls are then executed to gather data associated with that event.

One additional feature is associated with CALL 4. Data acquisition may be stopped at a known point in the program. The CALL 4 loop checks front panel switches expecting to find only Switch 14 up. If the user puts it down, a crate inhibit command is sent to CAMAC, suspending CAMAC operation until the switch is again returned to an up position.

A magnetic tape handler was incorporated into a separate subroutine, CALL 9. It is used primarily to write raw data from the Z array onto tape for later analysis, but is capable of any tape handling operation. Free format for recorded data is used. Writing onto tape considerably increases the time needed to analyze an event. From start to completion, a tape write operation requires about 50 msec. Consequently, data from 12 events are stored in the computer before the data is logged as a single record on magnetic tape. This reduces the net writing time to about 5 msec per event.

To speed up event analysis, assembler subroutines (CALL 21 and CALL 22) were developed to interpret the hodoscope reading and the spark chamber data for each event. CALL 22 is a bit-examining routine to see if just one hodoscope element, or possibly two adjacent elements, fired. Any other result is interpreted as an error. Either a multiple passage of particles through the hodoscope or a failure of the equipment is possible. CALL 21 checks proper operation of all 8 spark planes, including correct fiducial marks and multiple sparking.

The execution speed achieved by assembler-coding these two program segments is condiderable. CALL 21 requires 130_8 instructions and executes in about $100\,\mu$ sec. It is equivalent to ten lines of BASIC, which would execute in 100 msec. CALL 22 requires 53_8 instructions and executes in about $50\,\mu$ sec. It is equivalent to about 25 lines of BASIC, executing in 250 msec. The speed increase is over three orders of magnitude.

To date, the most rapid acquisition program used with the BASIC/CAMAC system accepts data from CAMAC with sequence-reads, performs CALL 21 and CALL 22 operations, and records the data on magnetic tape, requiring about 200 msec per event. This is about the speed limit on this form of BASIC/ CAMAC data acquisition. Appendix A contains a simple BASIC data acquisition program.

FORTRAN

Several advantages are gained by a change to FORTRAN as the DAS language. Primarily, the increased speed of event handling justifies the change. FORTRAN-CAMAC sequence-reads offer a time saving of up to an order of magnitude over BASIC/ CAMAC sequence-reads. Since single precision (16 bit) integer format can be specified for all variables in the main FORTRAN program, no time is wasted in conversion between fixed and floating formats. An added advantage is that magnetic tapes written with free-formatted binary integers are easy to read, so that translation software for data analysis is minimal.

Assembler language subroutines are simple to incorporate since the DATAGEN FORTRAN compiler accepts machine language instructions as part of a FORTRAN program. FORTRAN is not interactive, but this feature is hardly missed after a system has reached its final configuration.

FORTRAN Subroutines

Subroutines written for handling CAMAC and tape units are quite similar to their BASIC counterparts. Thus, CALL CYCLE (C, N, A, F, D, (1), n) does a single CAMAC operation, returning the low order sixteen bits to D(2) and the high order eight bits to D(1). A hardware error causes a return to line n in the main program.

Similarly, a sequence operation is effected with CALL EXEC (X(1, I), Y, n). X is a $3 \times Y$ integer array. CNA is encoded into X(1, I) as the Ith command in the sequence. F and the eight high order data bits are in X(2, I), and the sixteen low order bits are returned to X(3, 1); Y is the number of commands in the sequence and is limited only by available core.

The routine to build a sequence is similar to CALL 4711 in BASIC. An example of a FORTRAN

sequence construction is presented in Appendix B. The hodoscope and magnetic tape routines are unchanged, but spark chambers are handled with just a FORTRAN subroutine. A brief data acquisition system program in FORTRAN performing the same analysis as the BASIC program in Appendix B takes no more than 50msec per event, with most of that time used for the tape unit to write the data record. The obvious improvement to this, one incorporated in the BASIC program as well, is multiple event logging. Data for 20 events is accumulated in a large array, then written onto tape so that the time required to record each event averages less than 2.5 msec.

CONCLUSION

The approach adopted towards DAS development has been reasonably successful. A BASIS-CAMAC system certainly offers experimenters a simple way in which to reach a final configuration without much reprogramming. The system fails to be satisfactory, however, when event rates rise much above five per sec. A change to FORTRAN is the next logical step to preserve the flexibility and ease of use offered by a high level language, and increases the DAS speed. Since the equivalent FORTRAN data logging program takes only 2.5msec (200 per second), the FORTRAN DAS is not computer limited. Additional calculation can be done during the dead time of the nuclear electronics.

It has been demonstrated that a CAMAC system with a high level controlling language has wide application once the initial system has been established.

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APPENDIX A

A Brief Data Acquisition Program in BASIC

As a specific example of a data acquisition program in BASIC, the following is included, with a brief description of its operation:

```
1000
           CALL 4
           LET Z(0,10) = Z(0,10)+1
CALL 3,1,Z(1,1),E1
CALL 3,2,Z(2,1),E2
1020
1040
1041
1042
          CALL 3,3,Z(3,1),E0
          CALL 3,3,2(3,1),E0
CALL 3,4,2(4,1),E3
CALL 9,50,1,2(0,9),W1,1
CALL 22,2(2,10),H1,W4
LET H(H1) = H(H1)+1
1043
1060
1100
1101
           IF W4 < 2GOTO 1120
LET E(8) = E(8)+1
1102
1103
1104
           GOTO 1000
          GOTO 1000
LET W1 = 0
FOR I = 0 TO 7
CALL 21,W3,F(I),I+1,L(I),U(I),W4
IF W4 > 0 GOTO 1128
1120
1121
1123
1124
1125
1127
           LET S(I,W3) = S(I,W3)+1
LET W1 = 1
1128
           NEXT I
LET F8 = F8+W1
1129
           IF W1 = 1 GOTO 1000
LET S2 = Z(2,8)/25+25
1130
1140
          Let S2 = 2(2,8)/25+25

IF S2 > 0 GOTO 1143

LET S2 = 0

IF S2 < 100 GOTO 1145

LET S2 = 100

LET S2 = 100
1141
1142
1143
1144
1145
          GOTO 1000
1150
```

Line 1000 sets the system in a condition to accept an event.

Control is returned to BASIC when the event interrupt occurs, and the next four lines (1041 to 1043) are four CAMAC sequence-reads of ten commands each. These read all the data associated with a single event and store it in a 5×10 array Z.

APPENDIX B

An example of a ten element CAMAC sequence using DGC FORTRAN is included to demonstrate the use of some of the FORTRAN subroutines.

```
INTEGER D(2)
INTEGER X(3,10)
D0 20 I=1,10
ACCEPT C,N,A,F,D (1),D(2)
CALL SEQNC (X(1,1),C,N,A,F,D(1))
```

Each time the program encounters the ACCEPT statement, it pauses while the user enters C, N, A, F, and data necessary for any write commands. Data can be up to 24 bits with the low order 16 bits in D(2) and the high order 8 bits in D(1).

The following segment awaits the arrival of an event pulse (i.e. an interrupt from device 40) and then executes the entire sequence.

- 40 CALL IWAIT (DEV) IF (DEV.EQ.40) GOTO 50 45 TYPE "ERROR" PAUSE
- 50 CALL EXEC (X(L,L),L),\$45) GOTO 40

After the sequence execution, data from the Ith entry is in X(2, I) and X(3, 1) (high and low order respectively). An error in BTB or Q response causes transfer to line 45.

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10

LABORATORY REVIEWS

CAMAC APPLICATIONS IN THE CENTRAL ELECTRICITY RESEARCH LABORATORIES

by

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SUMMARY The paper reviews various applications of CAMAC in a multi-discipline research laboratory. Two autonomous systems are used for data logging and supervision. Other autonomous systems control and collect data from an electron-beam analyser and X-ray diffractometer. A computer-based system is used for data acquisition and processing.

INTRODUCTION

The Central Electricity Research Laboratories (CERL) is a multi-discipline organisation employing some 800 staff of whom some 300 are professional scientists and engineers. It is the largest of the three major laboratories of the Central Electricity Generating Board. The work of the laboratories covers Electrical Engineering, Physics, Chemistry and Biology, Engineering Sciences, Materials, and Control & Communications. Thus a very wide range of requirements exists for the instrumentation of experiments and for the acquisition of analog and digital data. In the past CERL used proprietary instrumentation systems, but in 1970 a decision was made to use CAMAC wherever possible. The development of a low level multiplexer for use with CAMAC was initiated. This multiplexer is now available as Nuclear Enterprises Type CE600 and CE601. It includes an option to provide programmable cold junction compensation for thermocouples.

The availability of such items led to a considerable use of CAMAC within CERL. The benefits of speedy reconfiguration, ease of maintenance, reliability, recoverability and the use of a standardised but non-proprietary system have been amply realised. The earlier CAMAC systems were bought complete, but all later systems have been engineered within CERL, using commercial CAMAC items.

CAMAC AT CERL

At present there are seven CAMAC systems in regular use based on CAMAC. The value of the CAMAC parts of these systems, together with spares, is about £50,000.

In the following sections the properties of some of these systems are outlined briefly in order to show the wide variety of applications.

CAMAC SUPERVISORY AND LOGGING SYSTEM

This was originally planned as a 96-channel logging and supervisory alarm system. It is used for temperature monitoring and recording, as well as automatic weighing of heated corrosion specimens. It was later extended to accommodate a further 32 channels on the same test facility. It was yet again adapted to serve a second experimental rig at a distance of some 150m which required a further 16 channels and a second teletype. The input channels of these systems comprise a mixture of thermocouple emf's and millivolt-level signals from other transducers, scanned by the multiplexers mentioned above. The multiplexers are often located near the transducers to reduce cabling requirements. The system monitors data for alarm conditions, and also prints out a log of the data at pre-determined intervals.

Fig. 1 illustrates the block diagram of this system in which the analog signals (in the range 0-110 mV) are transmitted from various locations to a common DVM. Because of the high mains electrical interference levels, and the need to measure low level analog signals to $\pm 10 \,\mu$ V, it is essential to use double



Fig. 1 CAMAC Data Logger

pole multiplexer switches and a switched "guard", together with an integrating digital voltmeter. This enables series and common mode interference in the overall system to be rejected. The sampling rate has to be more than one sample per two mains periods, namely 40mS with a 50 Hz supply. In this particular system the sampling rate is only 1 per second. The system is controlled by a Dataway controller whose programs are set up on pin-boards.

ELECTRON BEAM ANALYSER

This system provides not only for data acquisition from three digital inputs (obtained from pulse counters and from a digitised measurement of electron beam current) but for control of the sample position by stepping motor. The sample position is initially input from a manually prepared paper tape, and this tape is regenerated in an updated form for further sample positions during the course of the analysis. The data is recorded on tape and subsequently examined off-line. The system employs a Dataway controller with pin-board program stores. Fig. 2 illustrates the system.



Fig. 2 Electron Beam Analyser

DIFFRACTOMETER CONTROL SYSTEM

An X-ray diffractometer requires measurement of the X-ray intensity at fixed angular positions. The CAMAC system¹ controls the position of the diffractometer table either continuously or in discrete steps. Peak seeking facilities are incorporated so that the time required for an analysis is minimised and the equipment can very largely be left running unattended. The system is controlled from a Dataway controller with pin-board program stores.

GENERAL PURPOSE LOGGER

A version of the supervisory and logging system described above has been constructed as a transportable logging facility capable of scanning up to at least 256 analog data points. The equipment provides output to a teletypewriter or to a VDU.

CENTRAL DATA ACQUISITION AND PROCESSING SYSTEM-CDAPS

The system consists of a Computer Technology (CTL) Modular One computer interfaced via CAMAC modules to the rigs, which may be up to several hundred metres distant. The individual data points are selected under computer control by multiplexers located near the rigs. The present hardware can accommodate some 750 analog inputs distributed among many users.

The analog data, in the range 0-100 mV, are converted to digital signals centrally at 10 points per second, and transferred to the computer for processing. The results are returned to the user on his own CAMAC-driven teletype or made available in a form suitable for further off-line processing.

A suite of standard "logging" programs provides various commonly required options such as alarm limits, conversion to engineering units, print-out, etc. Users can also insert high level language programs (at present in "CORAL") to carry out more advanced calculations on their own data in real time. The CDAPS system, within the limitations imposed by available computer storage (at present 24k of core store), serves a number of users effectively simulta-enously, in a multi-programming time sharing manner.

The coupling between the MODULAR ONE computer and CAMAC was initially by means of serial teletypewriter interface modules speeded up to operate at 1000 characters per second. At a later stage a coupler between MODULAR ONE and CAMAC became available using parallel communication, and this coupler (CTL Type 1.751) has significantly improved the overall speed of the system. However, future applications will include data acquisition at higher speeds (e.g. 5-10 kHz). This would be greatly facilitated by the use of direct memory access facilities which are not available in the present coupler. The CDAPS system will be further described in a future issue.

SOFTWARE

The preparation of software is at present tedious and necessitates a specialist knowledge of CAMAC. This, together with the need to adapt programs frequently during the progress of research work, can inhibit the more general use of CAMAC. The move towards a CAMAC language is therefore welcome and should help the speedy development of programs.

SUITABILITY OF CAMAC

CAMAC has proved its value in adaptability and ability to upgrade systems as the research requirement changes. The reliability of CAMAC modules appears to be at least comparable with that of proprietary digital equipment. Such failures as have occurred have often been traced to interconnectors and pin-board storage. The multiplicity of frontpanel connections is unsatisfactory and tends to detract from the industrial suitability of the system. It is considered that there is room for an industrial version of CAMAC modules in which more attention would be paid to the reduction of panel connections and to the introduction of rigorous environmental specifications particularly with respect to temperature. The successful implementation of CA-MAC within large industries for industrial purposes, for example for process and telecontrol, would be helped by more attention to the above points. Nevertheless, CAMAC has proved to be very advantageous within CERL and its use can be expected to grow.

ACKNOWLEDGEMENTS

The work was carried out at the Central Electricity Research Laboratories and the paper is published by permission of the Central Electricity Generating Board.

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DEVELOPMENT ACTIVITIES

CAMAC BRANCH DRIVER FOR LABEN COMPUTERS

by

L. Stanchi

Euratom Joint Research Center, Ispra, Italy Received 19th June 197

SUMMARY A branch driver for use with Laben 70 and 701 computers is described. It contains features for fast handling of special LAM's, for address scans over an unknown number of registers, and for direct transfer of data between modules.

INTRODUCTION

1

CAMAC is an efficient method of interfacing computers to controlled devices. In Ispra we needed to use existing Laben computers with CAMAC systems, so we developed a dedicated branch driver in collaboration with the firm Laben. The result is a versatile branch driver, which is equipped to perform all the operations required by specification EUR 4600 and some additional operations which are peculiar to this branch driver. It can handle data with 24 or 16 bits and contains registers for memorizing them before transferring. In addition there are 32-bit registers for storing commands and for reading the status of the branch driver.

It can operate under program control, program interrupt, or direct memory access (DMA). An interface that differs only in some special respects from the standard Laben interfaces is directly inserted into the computer, and completes the connection between computer and the branch driver. If a multibranch system has to be implemented, more than one branch driver is needed, each one with its own interface. Up to eight interfaces can be allocated in the standard cabinet.

SPECIAL LAM FEATURES

A very special feature of this branch driver is the fast handling of some LAMs. The normal LAM handling based on the BD signal and graded-L operation is not described exhaustively here, but special attention is given to two means of saving time when fast data acquisition is of primary importance.

Operations on three special LAMs. The branch driver has three separate inputs directly wired to LAM sources. As the Laben computer normally allocates 4 memory locations to each peripheral the modified interface occupies two peripheral numbers in order to have 8 memory locations which can be associated with the external device operating in program interrupt or in DMA. The eight locations are used in order of increasing priority as follows: three memory cells for data, one for BD, three for special LAMs L_1 , L_2 , L_3 , and one for alarms. The three cells for data contain the input/output instruction in the first and, if required, the word counter and start address counter in the others. The branch demand signal has higher priority than the data but cannot interrupt a single transfer. The special LAMs are ranked according to priority and are serviced directly without requesting the LAM pattern. The highest priority is reserved for alarms, such as word counter overflow in succesful operation or some abnormal occurrences such as instrument not ready or X = 0, or Q = 0 when a 1 is expected, and so on.

Use of an Interrupt Vector Generator. When the special vector generator module is used the operation of the interface card is changed by substituting one patch connection. In this case the interface responds to 10_8 peripheral numbers and has the ability to access 32 memory cells of the computer directly. The first three cells are always assigned to data and the last to the high priority alarms. The other 28 cells are assigned with ranked priority to the BD signal and 27 special LAMs ordered by the Interrupt Vector Generator module.

ADDRESS SCAN WHEN THE LENGTH IS NOT KNOWN A PRIORI

This special feature results from the need to design a system with a large number of registers for memorizing a burst of neutrons at a speed unacceptable to the computer. This requires a buffer memory with sufficient registers to ensure that it is rarely overfilled. Hence, in normal operation many of the registers are empty and only a few have to be read. With the special means of handling the address scan mode (conforming fully to EUR 4100) we can choose by software between the normal operation with known length of block (word counter) and the use of a comparator for determining the end of block. In this second type of operation each register has a flag which controls the Q response. The registers are filled with incoming data in the order A0-A15, and only those that have been filled will respond with Q = 1 during the reading scan, so that station number N is incremented at the first empty register. A five bit comparator loaded by software recognizes the last module in the scan. The first empty register in this module will stop the scan. A crate number can be assigned to the last address by a patchable gate.

CONCLUSION

The details are not reported here because they are more or less conventional and can be found in any branch driver which is equipped to transfer a bidirectional flow of data having 24 bits in the CAMAC system and 16 bits in the computer word. Attention is directed to the "Executive" mode which permits this branch driver to exchange information between controlled modules without loading the computer memory. If a special command is addressed by the computer to the branch driver it stores in its register the data coming from one module and overwrites the data into another module. A 32-bit register is used for storing commands from the computer, which are sent always in double word format. The first word contains an 11-bit control field and the F function. The second contains the full address CNA. All the operations listed in EUR 4600 are possible and the branch driver is normally used with Type A1 crate controllers. Some special features for LAM handling based on the BD signal can be preset by the program. More details can be found in the references. Complete schematics are in Ref. 2, but the text is in Italian. The work of Messrs M. Bernede, G. De Grandi and J. Kalisz (on temporary leave from the center of Swierk, Poland) is greatly acknowledged. Collaboration with Messrs P. Bettini and A. Neglia of Laben led to fruitful results.

- 1. Bernede, M., *et al.*, CAMAC Branch Driver: A Particular Solution. *Nucl. Instrum. Methods*, to be published.
- 2. De Grandi, G., Thesis, Polytechnic of Milan.

NEWS

CAMAC SESSIONS AT 1973 NUCLEAR SCIENCE SYMPOSIUM NOV 14-16, 1973, SHERATON-PALACE HOTEL, SAN FRANCISCO, CALIFORNIA

Following earlier precedents, this year's symposium had two special sessions devoted to CAMAC papers and, reflecting the European-American cooperation on CAMAC, one session was in the French Parlour and the other in the California Room at the Sheraton Palace Hotel, San Francisco, November 14/16.

A more pertinent demonstration of this cooperation was that 6 of the 15 papers were from European sources. The panel discussion centred on the CA-MAC highways as a means of interconnecting crates and computers. A detailed report will be available in *CAMAC Bulletin* No. 9.

Titles and authors of presented papers are given below:

CAMAC as a Computer Peripheral Interface System — A.C. Peatfield, K. Spurling and B. Zacharov, Daresbury Nuclear Physics Laboratory, England.

Highways for CAMAC Systems: A Brief Introduction — L. Costrell, Nat'l Bureau of Stds.

The CAMAC Serial System for Long Line, Multicrate Applications — D.R. Machen, Los Alamos Scientific Laboratory.

Operational Aspects of a Serial CAMAC System — E.J. Barsotti, H.C. Lau and J.R. Simonton, National Accelerator Laboratory.

CAMAC Serial Loop with Intelligent Crate Controller — H. Halling, KFA, Julich, Germany.

An Optically-Coupled Serial CAMAC System — D.R. Heywood and B. Ozzard, TRIUMF, University of British Columbia.

CAMAC Applications in Nuclear Medicine at Vanderbilt: Present Status and Future Plans — A.B. Brill, J. Parker, J. Erickson, R. Price and J. Patton, Vanderbilt University.

CAMAC for Data and Computer Communications — B. Zacharov, Daresbury Laboratory, England.

An Introduction to CAMAC Software — I.N. Hooton, AERE, Harwell, England.

CAMAC Stand-Alone Control System (CAMSAC) — R.G. Martin, National Accelerator Labaratory.

A CAMAC System for the Automatic Testing of Photomultiplier Tubes — A. C. Burley and H. A. W. Tothill, Nuclear Entreprises, Ltd., Beenham, Reading, England.

Proportional Wire Chamber Readout System at Daresbury Nuclear Physics Laboratory — J.C. Beach, A.C. Peatfield and A.J. White, Daresbury Nuclear Physics Laboratory, England.

Fast Readout and Geometrical Reconstruction System for Proportional Wire Chambers — S. Dhawan, Yale University.

Digital Monitoring System for NAL Secondary Beam Line Instrumentation — R.G. Martin, National Accelerator Laboratory.

A CAMAC Single Crate Controller for Synchronized DMA Transfers and an ADC Interface Module — R.A. LaSalle, Florida State University.

Title Only: CAMAC Scanning DVM System — R.G. Martin and A.E. Brenner, National Accelerator Laboratory.

DEVELOPMENTS IN HARDWARE AND SOFTWARE FOR THE 7025 PROGRAMMED DATAWAY CONTROLLER

by

L. D. Ward and R. C. M. Barnes Atomic Energy Research Establishment, Harwell, England *Received June 1973*

SUMMARY Many successful CAMAC systems use the Harwell/Nuclear Enterprises 7025 Programmed Dataway Controller. The programs have mostly been written in machine code and held in 256-word read-only stores. New developments described in this paper provide assemblylevel programming facilities and a 2730-word read-write store for programs and data.

INTRODUCTION

2

The programmed Dataway Controller Type 7025¹, designed by AERE Harwell and marketed by Nuclear Enterprises, includes many of the features normally found in a mini-computer. It executes a program of instructions and CAMAC commands read from an associated store, and can perform arithmetic and control operations on data. The full range of CAMAC operations can be performed on modules in the same crate as the controller, and in up to three additional crates.

Typical applications for this controller are in selforganising CAMAC systems, generally not associated with a computer, but sometimes acting as an intelligent satellite to a computer. There are more than 100 such systems. Papers in *CAMAC Bulletin* have described systems for data logging, control of laboratory instruments, airborne data recording, and as a multiplexer for inter-computer data links.

Many characteristics of the controller give it an advantage over the conventional arrangement of a separate 12- or 16-bit computer interfaced to a CAMAC controller. For example, features such as the 24-bit word-length, and single instructions to control a CAMAC operation and conditional skip on Q, are among those recommended in a recent paper by Cohn² on CAMAC-oriented processors.

The powerful 24-bit instructions (which can include 16-bit literal data) allow surprisingly complex programs to be written within the limit of 256 words set by the instruction counter. Many systems have been installed with read-only diode-matrix stores for program, and with active registers in modules for variable data and sub-routine return addresses. More recently, specialised 256-word read-write stores have become available, with direct addressing for instruction-fetch but indirect addressing through an address register for data transfers via the Dataway (requiring two instructions in general).

This paper describes a further development by AERE Harwell, extending the store capacity for program and data to 64 kilobits, giving 2730_{10} 24-bit words, all directly addressed by the program.

Short programs for the 7025 controller have usually been written directly in 'machine code'. This requires a detailed knowledge of the field-structure of the 24-bit instructions, and the use of absolute addresses for jump instructions and CAMAC registers. For larger programs it is clearly desirable to work in an assembly-level language, allowing mnemonic instruction codes, symbolic variables and labels, and isolation of the user from the details of instructionword formats.

One such assembly language, CONCO³, is used with an assembler which runs in a larger computer (PDP-10). This has been used to develop programs for plugboard-store systems, and the print-out from the assembler therefore includes a plugboard layout diagram.

The PROCOL programmed controller language described in this paper has been implemented with an assembler that runs in a CAMAC system consisting of the 7025 controller and 64-kilobit store.

THE PROGRAMMED DATAWAY CONTROLLER

The 7025 Programmed Dataway Controller is a triple-width plug-in unit. It is interfaced to the Dataway at the control station and a normal station, to the program store and control panel via front-panel connectors, and to any Harwell 7000 Series intercrate highway drivers via a rear-mounted Control Highway connector. The rack-mounted control panel (Type 0362) provides the usual mini-computer facilities for examining and loading the contents of the main registers, for starting and stopping the program, etc.

The instruction set of the controller includes Dataway operations (with transfers to or from the 24-bit accumulator register, and simultaneous testing of the Q response), arithmetic operations on the contents of the accumulator, and control operations such as Skip and Jump. For details see Appendix I of Reference 1 or 4.

THE 64-KILOBIT STORE

This development consists of a CAMAC plug-in unit (Store Interface Type 7067-2) and an Ampex core store unit (Fig. 1). The Store Interface is a triple-width unit, with access to the Dataway at a normal station and to the core store and controller through front-panel connectors. The core store is mounted behind the control panel in a Housing Unit (Type 0719) which provides forced air-cooling.

In order to reduce system costs the core store has an 8 K by 8-bit configuration, but the Store Interface automatically organises three store-cycles per 24-bit word. The resulting 2730 24-bit locations are directly addressable for both instruction and data storage.

The Store Interface extends the instruction set of the controller to include memory-reference instructions⁴ that address any of the 2730 store locations, and are implemented partly in the controller and partly in the interface. These instructions provide for data transfers to and from the controllers' accumulator, (Store, Load, Add, Subtract, and Complement-Accumulator-and-add), for incrementing the



Fig. 1 Layout of 7025 Controller with 64-Kilobit Store, showing Store Interface 7067, Control Panel 0362, and Store Housing 0719.

contents of any location (Increment-Skip-if-Zero, Increment-Skip-if-Non-Zero) and for jumping to an instruction at any location (Jump, Clear-Accumulator-and-Jump, Jump-to-subroutine). The memoryreference instructions can have multiple levels of indirect addressing and auto-indexing of the indirect address.

Typical instruction cycle times are 33μ sec for store data transfers and 14μ sec for CAMAC Dataway operations.

SOFTWARE

The assembly language PROCOL has been developed for use with 7025/7067 CAMAC systems. The minimum software package consists of the PRO-COL Assembler to translate source code into binary, and a Binary Loader to load the resulting object tape ready for execution. Debug and Binary Punch routines are available for program testing and development, and a line-by-line Text Editor for sourcetape correction.

PROCOL provides the programmer with the usual advantages of an assembly language, including mnemonics for instruction codes (and CAMAC command parameters), labels assigned to instructions or data, the use of signed decimal or octal data and the introduction of formats and comments to assist in the layout and understanding of the program. The assembler executes a first pass of the source tape for syntax checking and label allocation, and a second pass for the output of binary tape. An optional third pass gives a full program listing.

The PROCOL assembler runs on the 7025 Programmed Dataway Controller with core store, and uses the instruction set as augmented by the 7067 Store Interface. It can assemble programs written in the augmented instruction set or the original instruction set of the 7025 controller. The software package including the assembler can therefore be used to develop programs for systems with read-only stores or 256-word read-write stores.

APPLICATIONS FOR THE 7025 CONTROLLER WITH 64-KILOBIT STORE

The combination of the 7025 Controller with the 64-kilobit core store finds typical applications in systems that are predominantly concerned with CA-MAC input/output, but involve immediate access to a volume of data.

One example is in data logging systems with many channels, each with associated parameters such as previous values, alarm and warning levels, and status related to the scanning sequence or alarm condition. Systems have been designed with 1000 channels, and with data processing facilities such as conversion from measured values to user-oriented units. A noteworthy feature of these systems is the software control of scanning sequences, based on a stored table of parameters. Separate selections of individual channels and sampling rates can be made for datalogging and alarm scans.

Another application is as a CAMAC-based multichannel analyser of great versatility (Fig. 2). The analogue-to-digital converter, display, operating controls, and data-output peripherals are all interfaced through CAMAC modules. The core store



Fig. 2 A Multi-Channel Analyser System Using the 7025 Controller with 64-Kilobit Store

holds the current values for all channels (e.g. 1024 channels) and the programs for accumulating, displaying, processing and recording the data. Apart from any alternative modes of operation that are included in the program, the system can be converted rapidly to a different mode of operation (not necessarily related to conventional multi-channel analysis) by reading in a previously-assembled program.

The important features of the system are therefore the wide-range of peripherals that are available, the ability to change the data-handling process, and the ability to create new facilities by program development using the PROCOL software package.

CONCLUSION

The hardware and software developments described in this paper convert the well-tried 7025 Programmed Dataway Controller into a mini-computer whose I/0 bus is the Dataway, and whose peripherals and on-line connections are interfaced through CAMAC modules. This mini-computer within CA-MAC is competitive with typical 12- or 16-bit computers external to CAMAC for systems where the emphasis is on input/output rather than arithmetic power or large store capacity. In such systems the direct 24-bit access to the Dataway, and the powerful 24-bit instruction, compensate for the apparently slow cycle time.

ACKNOWLEDGEMENTS

The authors are indebted to their past and present colleagues in Electronics and Applied Physics Division at AERE, in particular Mr. J. M. Richards who initiated this work and Mr. F. H. Hale who designed the multichannel analyser system.

REFERENCES

- 1. Ward L.D., Mitchell G.S.L., and Richards J. M., A Programmed Controller in the CAMAC System. AERE Harwell, England. Report AERE-R6334 (1970).
- Cohn C.E., Considerations in the Design of CAMAC-Oriented Processors. CAMAC Bulletin, No. 6 (1973) p. 30.
- Davies M. P. H., Hagan P. J., Hunt R. A., CON-CO – A CAMAC Language Assembler, CAMAC Bulletin, No. 7 (1973) p. 28.
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BULLETIN ANNOUNCEMENTS

COMPANY NEWSLETTERS

The ESONE Information Working Group is highly appreciative of the individual efforts being made by CAMAC Companies to promote CAMAC and their new products via company newsletters.

Recent arrivals on the scene include:

Jorway News, GEC CAMAC News, (GEC-Elliott Process Automation Ltd.) Kinetic System's Newsletter,

and there are other such as the 'Diary of Developments' by Nuclear Enterprises Limited.

In order to compile a comprehensive list for the next Bulletin of such newsletters that are available, perhaps companies would let Mr. O. Pl. Nicolaysen have the title of their publication.

Readers, in the meanwhile, who have not seen the above should write to the company concerned requesting a copy.

AVAILABILITY OF CAMAC GLOSSARY

All Bulletin subscribers have received together with *CAMAC Bulletin* No. 7 a copy of the Supplement of that issue 'A CAMAC GLOSSARY' by Mr. R. C. M. Barnes.

This glossary covers specialised technical terms used in connection with the CAMAC standards for modular data handling equipment. For each term there is an informal definition and translations of the term in French, German and Italian.

Additional copies of the Supplement can be obtained from:

Commission des Communautés Européennes DG XIII – CID 29, Rue Aldringer Luxembourg

and the price (including postage) is 60 BFr or the equivalent in any other currency.

NEWS

STANDARD FORTRAN SUBROUTINES (for Executive Functions, Process Input/Output, and File Handling)

The Purdue Workshop on Standardisation of Industrial Computer Languages is working on a set of standard subroutines for executive functions, process input and output, file handling and bit manipu-

lation for use with FORTRAN. To date the work

has resulted in one document, ISA-S61.1, *Industrial Computer Systems FORTRAN Procedures for Executive Functions and Process Input-Output*. Two subsequent publications are planned to define procedures for random-access file handling and communication with multitasking executive systems. ISA-S61.1 is available from Instrument Society of America, 400 Stanwyx Street, Pittsburgh, Pennsylvania, USA.

A SERIAL CRATE CONTROLLER

bv

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Received 14th June 1973

SUMMARY This paper describes a serial CAMAC crate controller for smaller systems. Each byte is a unique message, thus avoiding problems of message synchronisa-tion. There is a full-duplex link from each crate controller to the computer.

INTRODUCTION

A relatively simple serial crate controller* has been developed, which is controlled by a computer via a teletype port. The Dataway side of the controller is compatible with EUR 4100e, the I/O side is compatible with EIA RS 232 C¹, but the transmission speed may be much higher.

The CCC-2 crate controller² and a special encoding principle³ were used as a basis. For simplicity not all the possibilities offered by this principle have been used as yet.

SYSTEM CONFIGURATION

It is intended that each crate should have its own full-duplex link to the computer (if necessary, using modems). The channel from the computer to CA-MAC is called the "write channel"; the opposite one is the "read channel". The active (intelligent) part of the system is usually only the computer.

A local, short distance multiplex system, is just under construction to allow the connection of up to 7 or 15 crates at the end of one link.

GENERAL CHARACTERISTICS

Each data field, such as C, N, A, F, W, and R is uniquely associated with a different key within the same byte, i.e. in each byte the key determines how the content of the byte is interpreted. Thus the key determines which (4 or 5 bit) register should be loaded by the received byte or from which register data should be read. This feature allows the contents of one particular register, to be read or changed without disturbing the contents of any other register. Thus, it is only necessary to transmit those data fields that have to be changed or read.

ENCODING PRINCIPLE

For transmitting a CAMAC write command it is necessary to transmit at least (without check bits) about 40 bits. They must be set into the proper buffer registers. Using 3 or 4 bits in each byte as a key, it is possible to define uniquely the destination of the remaining bits, i.e. C, N, A, F or 4 bit segments of

ley Byte Nr. name		Key bit Pattern	WRITE -	Channel	Central t	O CAMAC		READ	- Channel	(CAMAC	to Centra	d)
	Bit No	8765	5	4	3	2	1	5	4	3	2	1
0	D-byte	0000		-	not to b	e used -	-		-	demand	pattern .	
1	P - 11	0001		EIP1)	parity co	ontent (Mor	dulo 8)		COD 2)	- par	ity conten	t•
2.3	N - 11	001	-		_N		-	-		- N		
.5	F - 11	010	-	-	-F		-	-		- F		
6	C- "	0110		-		c	-		-		c	
7	St- "	0111		DE 1 3)	DE 2 31	SA4)	SB 41		DC 1	DE 2	2 See Fig 2 4	
8	A - "	1000		-		A			-		Α	
9	D1- "	1001		MSB -		D1	-		-		D1	
10	D2- 11	1010		-		D2	-		-		02	
11	D3- =	1011		-		D3	-		-		D3	
12	D4- "	1100		-		D4	-				D4	
13	D5- "	11 01		-		D5					D5	
14	D6	1110		-		D6	-LSB*		-		D6	
15		1111		-		5)	-		-		51	

1. EIP Execute CAMAC operation, if parity is ok.

COD Camac operation done. Automatic 'Demand Byte' Generation enable for the whole branch with encoded (DE1, DE2) enable levels. 3.

SA, SB see Fig. 2.
 Free for individual usage.

Fig. 1 Key and-Content Assignment

the write data. Fig. 1 gives the "key-content" assignment, which is used in the crate controller.

SA and SB are decoded together. Fig. 2 shows the reaction of the crate controller to the four possible combinations of SA and SB. This method allows reading the Q or X response or setting the "S-Flip-Flop" and checking this transmission. The content of the "S-Flip-Flop" determines the reaction of the crate controller upon the receipt of a byte (key).

	WRITE-Channel READ-Channel*			MODE Flip-Flop		
	-	SA	SB	Bit 2	Bit 1	
	0	0	SA(±0)	SB (±0)		
Key 7	0	1	SA(±0)	SB(±1)	Set mode (S=1)	
'	1	0	SA(≟1)	Q	no mode change	
	1	1	SA (±1)	Х	no mode change	

* ($\underline{1}$ 0) and ($\underline{1}$ 1) means that respective bit contents '0' and '1' are a condition for errorless system operation.

Fig. 2 SA, SB Decoding Principle

If S = 1 (set mode), the content of each received byte overwrites the appropriate register, while the whole byte is echoed back to the computer (hardware disable is possible) for error checking. If S = 0(reply mode), the crate controller transmits to the computer the content of the register specified by the received key. For error checking the reply procedure may be repeated.

^{*} This crate controller differs in various important respects from the CAMAC Serial Highway scheme developed by the ESONE and NIM Committees, which is described in this issue (see p. 5).

TRANSMISSION ERROR CHECK

Two methods of error checking are provided and one or both may be used, depending on the quality of the link and the desired degree of reliability of the system.

A modulo-8 parity sum is generated independently by each transmitter and each receiver. A comparison is made in the receiver.

The CAMAC operation is executed only if no error is observed. If there is an error in the write channel, a demand byte is generated. If the computer observes an error in the read channel, it repeats the message.

The parity count recommences after each byte with the parity key (K1).

In set mode, all signals received by the crate controller are echoed to the computer and may be checked there. In reply mode, all data can be read by the computer from the crate controller as many times as desired for comparison purposes.

DEMAND GENERATION

The demand capability of each crate can be enabled by a certain CNAF. The allowed demand level is set by a combination of DE1 and DE2. A branch demand signal (BDE) is only applied to the 'transmission priority logic' if a LAM signal occurs whose priority level (assigned by a LAM grader) is higher than specified by DE1 and DE2. This causes the following bytes in the read channel to be 'demandbytes'. They consist of key 0 and a 4 bit GL pattern. (It is intended to derive this pattern from a priority logic.)

Receiver parity or framing error also cause emission of demand bytes with a certain GL level.

REACTION TO A DEMAND

In the 'demand byte' there are 4 bits available. They make it possible to transfer 15 differents levels (level 0 should indicate 'no demand') which immediately point to one of 15 servicing routines. These routines may service either a single LAM-source or may be a polling-routine to find out what to do, if more than one LAM-source has been assigned to the level. Anyway, until the servicing routine is finished, demands must be turned off at this level by changing DE1 and DE2 to a higher level.

IMPLEMENTATION OF THE CRATE CONTROLLER

A block diagram of the serial crate controller is shown in Fig. 3.



Fig. 3 Block Diagram of the Serial Crate-Controller

Transmission line interface circuits

The external signal transfers are performed at EIA RS 232 C levels in start-stop mode. Level converters and a serial-to-parallel/parallel-to-serial converter, driven by a local clock generator, provide the

conversion between external bit-serial and the internal byte-serial structure of the crate controller. Modulo-8 sum parity is generated at both, input and output terminals. A receiver 'framing error' signal is derived. A 'data received' signal starts the receiver timing.

Buffer addressing

Bits 5-8 of the received byte, the keybits, are connected to a 1-of-16 decoder (outputs 2-3 and 4-5 are ORed), which points statically to the address of the buffer register to which the remaining bits (e.g. databits) have to be sent. TP2 is generated only if the crate was addressed. The registers, except crate address and S-mode flip-flop, are only overwritten in 'set mode' (S = 1). The received keybits are echoed to the computer together with the data belonging to them. However, during demand generation the 'demand key' is produced in the crate controller and transmitted, and other signals to the 'read channel' are suppressed.

CAMAC operation

The resulting CAMAC operation is defined by the content of the N, A, and F registers, which are decoded in the 'crate function decoder'. The execution is started only if the locally counted modulo-8 parity coincides with the value received from the computer. The Dataway timing and gating is as required by EUR 4100 e.

Transmission priority logy

This circuit determines which byte will be sent next to the read channel, by controlling the gates for the key and the content. Highest priority is given to the currently transmitted byte, because it should not be interrupted. Next priority is given to a demand, as long as the BDE (enabled branch demand) is applied. The lowest priority is given to the echo of a received byte.

Example

Fig. 4 gives an example of a data transmission between a computer and a CAMAC crate equipped with the serial crate controller.

REFERENCES

1. Interface Between Data Terminal Equipment and Communication Equipment Employing Serial Binary Data Interchange. Electronic Industries Association, Washington D.C., Standard RS 232 C. (1969).

[Note: this is closely related to CCITT Recommendation V24]

- Attwenger, W., Egl, W., May, F., Patzelt, R., and others, *CAMAC Crate Control for a PDP-8*. Proc. Ispra Nuclear Electronics Symposium, EURATOM Report EUR 4289e (1969) p. 391.
- Buschbeck, F., Neuwirth, E., Proposal for a CAMAC Multicrate Serial Transmission System. SGAE Report 2138 EL-25/73 (1973).

Byte	WRITE-channel (computer to			R	EAD-channel (CAMAC
No.		Key	Content	Key	Content	
1	Sets demand level and mode (S = 1)	7	DE1, DE2, SA, SB			
2	Set C	6	C(4')	7	DE1, DE2, SA, SB	
3	Set N	2/3	N(5')	6	C(4')	
4	Set A	8	A(4')	2/3	N(5′)	
5	Set F	4/5	F(5')	8	A(4′)	
6	Set D ₁	9	D ₁ (4')	4/5	F(5')	the echo
7	Set D ₂	10	D ₂ (4')	9	D ₁ (4')	trans-
8	Set D ₃	11	D ₃ (4')	10	D ₂ (4')	to be
9	Set D ₄	12	D ₄ (4')	11	D ₃ (4')	спескец
10	Set D ₅	13	D ₅ (4')	12	D ₄ (4')	
11	Set D ₆	. 14	D ₆ (4')	13	D ₅ (4')	
12	Computer waits for echo			14	D ₆ (4')	
13	Execute CAMAC op. if parity is ok.	1	1, P _w (3')			
14				1	COD, P _R (3')	COD = 1: CAMAC operation done

Now the computer knows whether the CAMAC operation was executed properly

Fig. 4 Write Data into a Register of a Module Assumption: Initialization or previous transfer has finished without error

NEWS

ANNOUNCEMENTS BY CAMAC MANUFACTURERS

NUCLEAR ENTERPRISES LIMITED, who currently manufacture one of the largest ranges of CAMAC compatible equipment in Europe, have announced that they are shortly to commence manufacture of CAMAC equipment in the USA.

Mr. B. Payne, one of Nuclear Enterprises' senior CAMAC design engineers, is now at Nuclear Enterprises Inc. plant in San Carlos, near San Francisco, working with the management of the NEI plant to start manufacture of Nuclear Enterprises Limited designed CAMAC modules. The first units which should be available from the U.S. plant will include the new Input and Output Registers and deliveries are expected to be made during December 1973. The range of CAMAC manufactured at San Carlos will be gradually increased over the next twelve months so as to provide a complete 'in house' systems capability from U.S. manufactured modules.

CAMAC PRODUCT GUIDE

CAMAC Bulletin No. 8



CAMAC PRODUCT GUIDE

This guide consists of a list of CAMAC equipment which is believed to be offered for sale by manufacturers in Europe and the USA. The information has been taken from a CAMAC Products Reference compiled by CERN-NP-EL II from manufacturers' catalogues, advertisements and written communications available to them on 1st October 1973.

Every effort has been made to ensure the completeness and accuracy of the list, and it is hoped that most products and manufacturers have been included. Inclusion in this list does not necessarily indicate that products are fully compatible with the CAMAC specifications nor that they are recommended or approved by the ESONE Committee. Similarly, omission from this list does not indicate disapproval by the ESONE Committee. Users are advised to obtain detailed information from the manufacturers or their agents in order to check the compatibility and operational characteristics of equipment.

Products are classified according to the new decimal classification system introduced last issue. See Bulletin No. 7 for a description of the classification system.

There are about 150 new entries this time, bringing up the total to some 1050 products.

How to search for appropriate class: As a first approach use the relatively coarse classification listed below. In the Index of Products you will find a heading for each three-decimal class.

Remarks on some columns in the Index of Products

Column

N/C – N is new, C is corrected entry.

- WIDTH NA indicates other format, normally 19 inch rack mounted chassis.
 - 24 or 25 indicates number of stations available in a crate.
 - Blank, the width has no meaning.
 - 0 indicates unknown width.
- NPR Number in brackets is issue number of the Bulletin in which the item was or is described in the New Products section.

DELIV – Date on which item became or will become available.

1

CLASSIFICATION GROUPS

code	Э	page	code	9	page
1	DATA MODULES (I/O Transfers and Processing)			Crate Bus, Single-Crate Systems, Autonomous Systems)	xvi
11	Digital Serial Input Modules (Scalers, Time Interval and Bi-directional Counters, Serial Coded etc.)	Ш	22 23	Interfaces/Controllers/Drivers for Serial Highway	XIX
12	Digital Parallel Input Modules (Storing and Non-Storing Registers, Coinc. Latch, Lam, Status etc.)	 IV		(Crate Controllers, Terminations, Lam Graders, Branch/Bus extenders)	хіх
13	Digital Output Modules (Serial: Clocks,		3	TEST FOURPMENT	
	Timers, Pulse Generators, Parallel : TTL Output, Drivers)	VII	31 32	System Related Test Gear	XXI
14	Digital I/O, Peripheral and Instrumen- tation Interfacing Modules (Serial and Parallel I/O Regs, Printer-, Tape-, DVM-,		33	Displays Dataway Related Testers and Displays	XXI XXI
15	Plotter- and Analyser Interfaces, Step-Motor Drivers, Supply CTR, Displays) Digital Handling and Processing Modules	IX	34 37	tenders)	XXII XXII
	(and/or/not Gates, Fan-Outs, Digital Level and Code Converters, Buffers, Delays, Arithm.	ХШ	4	CRATES, SUPPLIES, COMPONENTS, ACCESSORIES	
16	Analogue Modules (ADC, DAC, Multi- plexers, Amplifiers, Linear Gates, Discrimi-	<u> </u>	41	Crates and Related Components/Acces- sories (Crates with/without Dataway and	
17	nators etc.)	XII	42	Supply, Blank Crates, Crate Ventilation Gear) Supplies and Related Components/Ac- cessories (Single- and Multi-Crate Supplies.	XXII
	Connected etc.)	XIII		Blank Supply Chassis, Control Panels, Supply Ventilation)	xxv
2	SYSTEM CONTROL (Computer Couplers, Controllers and Related Equipment)		43	Recommended or Standard Components/ Accessories (Branch Cables, Connectors etc.,	
21	Interfaces/Drivers and Controllers (Par- allel Mode for 4600 Branch and Other Multi-			Dataway Connectors, Boards etc., Blank Modules, Other Stnd Components)	xxvi

TYPE

MANUFACTURER

n DELIV. NF

1 DATA MODULES — I/O TRANSFERS AND PROCESSING

11 Digital Serial Input Modules — Scalers, Time Interval and Bi-directional Counters, Serial Coded etc.

111 Simple Serial Binary Registers

COUNTING REGISTER (1X24BIT,154HZ,TTL/NIM SIGNALS,EXT INHIBIT IN,CARRY DUT) 1X24 BIT BINARY BLIND SCALER (20MHZ NIM OR 10MHZ TTL I/P,EXT INHIBIT IN,OVF 0/P) MINISCALER (2X16BIT,30MHZ,SEPARATE GATES AND EXTERNAL RESET,NIM LEVELS) MINISCALER (2X16BIT;30MHZ,SEPARATE GATES AND EXTERNAL RESET,NIM LEVELS) MINISCALER (2X16BIT, 30MHZ, SEPARATE GATES AND EXT RESET, NIM LEVELS) DUAL 150 MHZ 16 BIT SCALER (ONE 50 OHMS, ONE UNTERMINATED NIM INPUT PER SCALER) DUAL 24 BIT BINARY SCALER (15MHZ, NIM OR TTL INPUTS) DUAL 24-BIT COUNTING REGISTER DUAL 10 DMHZ SCALER (2X24 BIN 3ITS OR 2X6 ECD DIGITS,DISCR LEVEL -0.5V) DJAL 150 MHZ 24 BIT SCALER (ONE 50 OHMS, ONE UNTERMINATED NIM INPUT PER SCALER) MICROSCALER (4X16BIT,2X32BIT SELECTABLE, 25MHZ,COMMON GATE,NIM LEVELS) QUAD CAMAD SCALER (4X16BIT OR 2X32BIT, 40 MHZ) TIME DIGITIZER (4X16BIT,50MHZ CLOCK,WITH CENTRE FINDER, USABLE WITH PRE-AMP 511) QUAD SCALER (4X16BIT, SELECTABLE 2X323IT, 50MHZ, COMMCN GATE, NIM LEVELS, CERN 303) QUAD 16-BIT SPARK READ-OUT REGISTER (20MHZ RATE,TTL LEVELS) SERIAL REGISTER (4X163IT,2X323IT SELECTABLE,25MHZ,COMMON GATE,NIM LEVELS) QUAD 40 MHZ SCALER (4X16BIT,2X32BIT SELECTABLE,INDIV HI-Z INHIBITS, NIM) MICROSCALER (4X16 BIT,25MHZ,CPTIMIZED INPUT,3 NSEC,GIVES TYP 80M4Z COUNTING) MICRCSCALER(4X16BIT,2X32BIT SELECTABLE, 25MHZ,COMMCN GATE,NIM LEVELS) 4X16 BIT BINARY BLIND SCALER (30 MHZ, 2X32BIT SELECTABLE,COMMON SATE,NIM/TTL) FOUR-FOLD SCALER (4X15BIT,2X323IT SELECTABLE,50MHZ,COMMON GATE,NIM LEVELS) FOUR-FOLD CAMAC SCALER (4X16BIT, 40 MHZ, ONE 50 OHMS, ONE HI-Z NIM I/P PER SCALER) TIME DIGITIZER(4X16BIT,CLOCK RATE 70/85MHZ, WITH CENTER FINDING LOGIC) TIME DIGITIZER (4X16BIT, CLOCK RATE 70/85MHZ, NIM LEVELS) SERIAL REGISTER (4X163IT,2X323IT SELECT-ABLE,100MHZ,COMMON GATE,NIM LEVELS) QUAD 100 MHZ SCALER (4X16/24BIF,-0.5V I Threshold, common ext fast inhijit, nim) I/P FOUR-FOLD SCALER(4x16BIT,2x323IT SELECT-ABLE,100MHZ,COMMON GATE,NIM LEVELS) QUAD SCALER (4X24BIT, 50MHZ, DATAWAY AND/OR EXT FAST INHIBIT, NIM LEVELS) QUAD COUNTING REGISTER(4X24 BIT, NIM INPUT TTL INHIBIT IN, TTL CARRY AND DVF OUT)

7070-1	NUCL. ENTERPRISES	1	/70	
J EB 10	SAIP/SCHLUMBERGER	1	/71	
1002	30 RER	1	/69	
0 0 2	NUCL. ENTERPRISES	1		
C 104	RDT	1	/71	
25 2024/16	SEN	1	/70	
FHC 1313	3F VERTRIEB	1	/72	
C-DS-24	WENZEL FLEKTRONIK	1	172	
8 D A	JORWAY	1	/70	(1)
		1		(1)
25 2024/24	SEN	1	170	
1003	BORER	1	/69	
1004	BORER	1	/72	
1005	BORER	1	172	
S416	EG+G	1	/71	
SR 1604	GEC-ELLIOTT	1	/71	
SR 1605	GEC-ELLIOTT	1	/71	
SR 1606	GEC-ELLIOTT	1	/71	
003-4	NUCL. ENTERPRISES	1	/71	(5)
C 102	RDT	1	/71	
J EB 20	SAIP/SCHLUMBERGER	1	/71	
4 S 2003/50	SEN	1	/69	
4 S 2004	SEN	1	/70	
TD 2031	SEN	1	172	
TD 2041	SEN	1	172	(4)
SR 1608	GEC-ELLIOTT	1	/71	
25503	LRS-LECROY	1	/70	
4 S 2003/100	SEN	1	/70	
S424S	EG+G	1		(7)
709-2	NUCL. ENTERPRISES	1	/71	

NC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR
N	SCALED (4424811- 50 MH7)	90.51			10/77	
N	QUAD SCALER (4X24BIT,150/125MHZ, DATAWAY AND/OR EXT FAST INHIBIT,NIM LEVELS)	S424B	EG+G	1	/71	
	QJAD SCALER (4X24BIT, 200MHZ,)4TAWAY AND/CR EXT FAST INHIBIT, NIM LEVELS)	S424F	EG+G	1		
N	QUAD COUNTING REGISTER (4X24BIT, 100MHZ, NIM + TTL LEVELS, TTL CARRY OJF, BINARY)	300	HYTEC	1	12/73	
c	QUAD SCALER (4X24BIT, 125MHZ,INTERRUPT Structure, individual inhibits)	S1	J O E RGE R	1	/72	(5)
N	QUAD SCALER (4X24BIT, 200MHZ,INTERRUPT Structure, individual inhibits)	S1-1	JOERGER	1	05/73	
	QUAD 100MHZ SCALER (4(24BIT,DISCR LEVEL -0.5V,TIME-INTERVAL APPL,NIM INHIB I/P)	84	JORWAY	1	/71	(2)
	HEX TTL/NIM 50 MHZ SCALER	3610	KINETIC SYSTEMS	1	01/73	
	HEX NIM 100 MHZ SCALER	3615	KINETIC SYSTEMS	1	04/73	(8)
	OCTAL SCALER (12BITS,8 INPJTS,50MHZ,EACH SCALER GIVES EXT INHIBIT,NIM LEVELS)	S812	EG+G	1	/71	
	112 Simple Serial Decade Re	egisters				
	1X6 BCD DECADE SCALER (25 MHZ, BUILT-IN DISPLAY)	J EA 20	SAIP/SCHLUMBERGER	1	04/73	
	DUAL 24 BIT BCD SCALER (15MHZ, NIM OR TTL INPUTS)	FHC 1311	BF VERTRIEB	1	172	
	DJAL 100 MHZ-6 DECADE BCD SCALER	C 350	INFORMATEK	1	02/73	
	2X6 BCD DECADE SCALER - 100 M4Z WITH REMOTE DISPLAY	J EA 10	SAIP/SCHLUMBERGER	1	/71	
	QUAD SIX-DECADE COUNTER WITH VARIABLE THRESHOLD AND INPUT FILTER, SLOW	1007	BORER	1	/72	(4)
C	QUAD BCD SCALER (4X6 DECADES,30MHZ)	9021	NUCL. ENTERPRISES	1	/71	
N	QUAD COUNTING REGISTER (4X24BIT, 100MHZ, NIM + TTL LEVELS, TTL CARRY OVF, BCD)	301	1YTEC	1	12/73	
	113 Preset Serial Binary Reg	isters				
	15 BIT PRESETTABLE INTERVAL COJNTER	2201	JI RA SYSTEMS	1	04/73	
	PRESET COUNTING REGISTER (16BIT,10MHZ, NIM/TTL I/P,TTL INHIB + 0/P,CATAWAY SET)	7039-1	NUCL. ENTERPRISES	1	/70	
	24 BIT PRESETTABLE INTERVAL COUNTER	2202	BI RA SYSTEMS	1	04/73	
	PRESET SCALER(24BIT,30MHZ,JATAWAY PRESET CJUNT/TIME,INPUT GATEJ,NIM LEVELS)	1001	BORER	1	/71	(1)
	PRESET COUNTING REGISTER (24BIT,10MHZ, DATAWAY SET,NIM/TTL INPUT,TTL 3/P+INHI3)	703-1	NUCL. ENTERPRISES	1	/71	
	PRESETTABLE COUNTER (24BIT)	420	POLON	1	10/73	
	SCALER 50 MHZ (12/16/18/24BIT, PRESET WITH OVF LINE, CONSTANT DEADTIME)	C 72451-A3-A1	SIEMENS	1	172	
	PRESETTABLE SCALER (24BIT)	C-PS-24	NENZEL ELEKTRONIK	1	/72	
	SCALER 300 MHZ (12/16/18/24BIT,PRESET WITH OVF LINE,CONSTANT DEADTIME)	C 72451-A11-A1	SIEMENS	1	172	
N	DUAL PRESET COUNTING REGISTER(15BIT BIN)	2204	BI RA SYSTEMS	1		
N	DUAL 50 MHZ SCALER-TIMER (24 3ITS)	2101	JI RA SYSTEMS	2		
	2X24 3IT PRESET SCALER (103MHZ COJNTING)	J EP 30	SAIP/SCHLUMBERGER	1	04/73	
N	QUAD COUNTING REGISTER (4X24BIT, 500MHZ,	310	HYTEC	1	12/73	

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	REAL TIME CLOCK (3.8 JSEC TO 13.2 HRS, PRESET-TIME AND PRESET-COUNT MODES)	RTC 2014	SEN	1	/71
	24 BIT BCD PRESET-SCALER (12 MHZ, NIM OR TTL INPUTS, MANUAL OR DATAWAY PRESET)	FHC 1301	BF VERTRIEB	2	/71 (1)
	24 BIT BCD PRESET-SCALER (12MHZ, NIM OR TTL INPUTS, DATAWAY PRESET)	FHC 1302	BF VERTRIEB	1	/71 (1)
	6 BCD DECADE SCALER (MANUAL AND DATAWAY PRESET,1 MHZ, START/STOP OUTPJT)	J EP 20	SAIP/SCHLUMBERGER	2	/71
	PRESET SCALER (20MHZ,8DECADE 300,7 SEGM LED INDICATES CONTENTS AND PRESET NO)	PSR 0801	GEC-ELLIOTT	1	/72 (7)
	PRESET SCALER(10MHZ,8 DECADE 3CD,DISPLAY OF 2 SIGNIF NUMBERS+EXP,MAN PRESET,NIM)	C 103	RDT	3	/71
N	DUAL PRESET COUNTING REGISTE (+ DECADES)	2204	3 I RA SY STEMS	1	
N	QJAD COUNTING REGISTER (4X24BIT, 500MHZ, NIM + TTL LEVELS, TTL CARRY OVF, BCD)	311	HYTEC	1	12/73

117 Other Digital Serial Input Modules (Bi-Directional Sequential, Shift Types)

				10.0			
N	DEAD TIME COUNTER	2203	BI RA SYSTEMS		1		
С	UP/DCWN PRESETTABLE COUNTER(243IT,10MHZ, GATE AND PULSE BURST OUTPJTS)	S2	JOERGER		1	172	(5)
N	UP/DOWN PRESETTABLE COUNTER(6 BCD DIGITS 10 MHZ, MANUAL AND DAT4WAY PRESET)	S2-1	JOERGER		1	05/73	
N	QUAD PRESETTABLE UP-DOWN COUNTER	3640	KINETIC SYSTEMS		1	10/73	
	SEQUENTIAL INPUT REGISTER(16 BBIT BYTES, STORES CODED NIM PULSES,0=40,1=150NSEC)	SIRE	SAIP/SCHLUMBERGER		1	/71	
	DJAL INCREMENTAL POSITION ENCODER (2X20 BIT X-Y DIGITIZATION 3Y UP-DOAN COUNTER)	2IPE 2019	SEN		1	/71	

12 Digital Parallel Input Modules — Storing and Non-storing Registers, Coinc. Latch, Lam, Status etc.

121 Non-Storing Registers (Gates)

	INPUT GATE	320	POLCN	1	09/73	
	DYNAMIC DIGITAL INPUT, TTL	C 76451-A17-A1	SIEMENS	0		(6)
	DYNAMIC DIGITAL INPUT, POT. FREE	C 76451-A17-A2	SIEMENS	0		(6)
N	PARALLEL INPUT GATE (1X16BIT, TTL)	2411	BI RA SYSTEMS	1		
N	PARALLEL INPUT GATE (1X243IT, TTL)	2421	31 RA SYSTEMS	1		
N	INPUT GATE (24BIT, SOURCE SELECTION BY 68IT OUTPUT, DATAWAY SEN STROBE OUT)	J 007	JORWAY	0		(8)
	INPUT GATE 24-BIT	3420	KINETIC SYSTEMS	1	/71	(4)
	PARALLEL INPUT GATE (24BIT STATIC DATA, INTEGRATED FOR 1 USEC,TTL LEVELS)	7059-1	NUCL. ENTERPRISES	1	/70	
	PARALLEL INPUT GATE (22BIT STATIC DATA, 500 NSEC INTEGRATION,STROBE SETS L,TTL)	7060-1	NUCL. ENTERPRISES	1	/70	
N	24-BIT ISOLATED INPUT GATE	3471	VINETIC SYSTEMS	1	/73	
М	PARALLEL INPUT GATE (2X16BIT, TTL)	2412	31 RA SYSTEMS	1		
	DUAL 24 BIT PARALLEL INPUT SATE (TTL)	2422	31 RA SYSTEMS	1	04/73	
	DJAL PARALLEL STROBED INPUT GATE(2X243IT HANDS4AKE MODE TRANSFER TO DATAWAY,TTL)	ô1	JORWAY	1	/70	
	DUAL PARALLEL INPUT GATE (2X243IT,NON- INTERLOCK CONTRCL TRANSF TO DATAWAY,TT_)	61-1	J O R WAY	1	/70	
	INPUT GATE DUAL 24 BIT	3472	KINETIC SYSTEMS	1		
С	DUAL 24 BIT PARALLEL INPUT GATE (WITH LED DISPLAY OPTION)	PG-604	STND ENGINEERING	1	/72	(6)
	PARALLEL INPUT GATE (3X16BIT INPUT FR)M ISOLATING CONTACTS)	10 61	BORER	1	172	(4)
N	3×16-BIT INPUT GATE (INPUTS ISCLATED BY OPTO-CJUPLERS)	1063	BORER	1	05/73	(8)
	DIGITALES EINGANGSREGISTER MIT OPTOKOPP-	00 200-2003	DORNIER	1	172	
	(WITH FRONT PANEL CONNECTOR)	DO 200-2203		1	172	

NC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR
	PARALLEL INPUT GATE (15X16BIT, TL, 1=LO4)	IG 25601	GEC-ELLIOTT	2	/72	
	128 BIT RECEIVER (ADDRESSABLE AS 8 16BIT WORDS OR 128 1-BIT WORDS)	C 341	INFORMATEK	1	03/73	
	DIGITALES EINGANGSREGISTERISXBBIT PARALL	00 200-2001	DORNIER	1	/71	
N	(WITH FRONT PANEL CONNECTOR) (WITHOUT WIRING BOARD)	DO 200-2201 DD 200-2000		1 1	/72 12/73	
	DIGITALES EINGANGSREGISTER(5X8BIT PARALL	DO 200-2002	DORNIER	1	/72	
	(WITH FRONT PANEL CONNECTOR)	00 200-2202		1	/72	
	122 Storing Registers					
	PARALLEL-INPUT-REGISTER (SINGLE 16/243IT OPTION, READY SIGNALS, I/O TTL, 4 DC APPL)	MS PI 1 1230/1	AEG-TELEFUNKEN	1	/70	(1)
	PARALLEL-INPUT-REGISTER (SINGLE 13/243IT OPT, READY SIGNALS, I/O TTL, CONTROL BUS)	MS PI 2 1230/1	4EG-TELEFUNKEN	1	/70	(1)
N	PARALLEL INPUT REGISTER (1X163IT, TTL)	2311	BI RA SYSTEMS	1		
	PARALLEL INPUT REGISTER (16 BIT, CONTINU- OUS OR STROBED MODES CONTROLLED BY REG)	7014-1	NUCL. ENTERPRISES	1	/70	
	DIGITAL INPUT 16 BIT POT. FREE	C 76451-A8-A2	SIEMENS	0		(6)
	STATIC DIGITAL INPUT, TTL	C 76451-A8-A1	SIEMENS	0		(6)
	INPUT REGISTER (24BIT, SPEC CONN, 8 BIT Also VIA LEMO,LAM ON NON-ZERO DR STROJE)	FHC 1308	3F VERTRIEB	1	/71	
N	PARALLEL INPUT REGISTER (1x243IT, TTL)	2321	31 RA SYSTEMS	1		
	INPUT REGISTER 24-BIT	3470	(INETIC SYSTEMS	1	/71	(4)
	BALANCED INPUT REGISTER WITH ADDRESSING	3430	<inetic systems<="" td=""><td>1</td><td>172</td><td>(8)</td></inetic>	1	172	(8)
N	PARALLEL INPUT REGISTER (2x163IT, TTL)	2312	BI RA SYSTEMS	1		
	DUAL INPUT REGISTER (2X16BIT WITH LAM AND STROBE FOR EACH CHANNEL)	PR 1610 SERIES	GEC-ELLIOTT	1	05/73	
	32 BIT INPUT REGISTER	C 343	INFORMATEK	1	05/73	
	DUAL INPUT REGISTER (2X16BIT)	301	POLCN	1	09/73	
	DUAL 16 BIT INPUT REGISTER (TTL LEVELS, CERN SPECS 07?)	2IR 2002	SEN	1	/72	
	DUAL 16 BIT INPUT REGISTER(EXT STROBE OR DATAWAY COMMAND STORES DATA,TTL LEVELS)	2IR 2010	SEN	1	/70	
	DJAL 24 BIT PARALLEL INPUT REGISTER(TIL)	2322	BI RA SYSTEMS	1	04/73	
N	DUAL 24 BIT PARALLEL INPUT REGISTER(TTL)	2322A	BI RA SYSTEMS	1		
	DUAL 24 BIT INPUT REGISTER (TTL, HANDSHAKE)	RI-224	EG+G	1	172	
	DUAL INPUT REGISTER (2X249IT #ITH LAM AND STROBE FOR EACH CHANNEL)	PR 2400 SERIES	GEC-ELLIOTT	1	05/73	
N	DUAL INPUT REGISTER (2X24BIT, INPUT INTEG TTL INPUT, +AND- LOGIC)	221	HYTEC	1	11/73	
	DUAL PARALLEL INPUT REGISTER(2X24BIT,EXT LOAD REQUEST,4 OPER MODES,TTL LEVELS)	60	JORWAY	1	/70	
	24-BIT DUAL PARALLEL INPUT REJISTER (A HAS LO-Z, B HAS UNTERMINATED INPUT)	90414/9041B	NUCL. ENTERPRISES	1	/72	(7)
	DUAL INPUT REGISTER (2X24BIT)	302	POLON	2	09/73	
	PARALLEL INPUT REGISTER (2K24 3ITS)	J RE 10	SAIP/SCHLUMBERGER	1	04/73	(7)
C	DUAL 24 BIT PARALLEL INPUT REJISTER (WITH LED DISPLAY OPTION)	PR-604	STND ENGINEERING	1	/72	
N	DUAL INPUT REGISTER (2X24BIT,INPUT INTEG TTL SCHMITT TRIG I/P, +AND- L)3IC)	220 .	HYTEC	1	11/73	
N	INPUT REGISTER (2X24BIT, HIGH IMPEDANCE I/P, LED DISPLAY, 2X63IT O/P REG OPTION)	IR	JOERGER	1	/72	(7)
	DIGITALES EINGANGSREGISTER, EXT STROBE (4x8eit input latches, 1x83it set lam)	00 200-2004	DORNIER	1	04/73	
	(SAME WITH FRONT PANEL CONNECTOR)	00 200-2204		1	04/73	

123 Terminated Signal Input Registers (Coinc. Latch, Pattern etc.)

	COINCIDENCE LATCH (24 NIM INFUTS WITH Common strobe, ext reset, 2nsec overlap)	C1 24	EG+G	2		
	12 BIT PARALLEL INPUT REGISTER (NIM)	2351	31 RA SYSTEMS	1	04/73	
N	8-BIT INPUT REGISTER (NIM)	3473	KINETIC SYSTEMS	1	01/74	
	STROBED INPUT REGISTER (123IT COINC AND LATCH,NIM LEVELS,PATTERN AND L-REQ APPL)	SIR 2026	SEN	1	/70	
	FAST COINCIDENCE LATCH(16BIT,DISCR I/P, MIN 2 NSEC STROBE-SIGNAL DVERLAP)	64	JORWAY	1	/71	(1)
	16 FOLD DOR(I/P DISCR,STRO3E-INPUT OVER- LAP 2NSE6,CH1-8 AND C19-16 SUM D/P,NIM)	23408	LRS-LECROY	2	/71	(6)
С	16-CH COINCIDENCE REGISTER (STROBE I/P, 2NS OVERLAP,FAST SUM J/P AND CLEAR,NIM)	2341	LRS-LECROY	2	/71	(4)
	PATTERN UNIT (16 INDIV NIM INPUTS,COMMON NIM GATE)	021	NUCL. ENTERPRISES	2	/71	(5)
	PATTERN UNIT(16BIT,I/P STROBE) WITH Common gate,10 nSec overlap,nim levels)	C 101	RDT	2	/71	
	15 BIT PATTERN UNIT (NIM I/P AND GATE)	J PU 10	SA IP/SCHLUMBERGER	1	172	
	PATTERN UNIT 16 BIT (16 INDIVIDUAL NIM Inputs, common nim gate, cern specs (21)	16P 2007	SEN	2	/70	
	16 BIT PATTERN UNIT (CERN SPECS 071, 16 Individual nim inputs,common nim gate)	16P 2047	SEN	1	/72	(6)
	COINCIDENCE BUFFER (2X12BIT,ONE STROJE PER 12BITS,MIN 2NS OVERLAP,NIM INPUTS)	C212	EG+G	2	/71	
	DUAL 16 BIT FAST LATCH(FAST NIM/ECL I/>, Strobe for each channel, 5 NSEC overla>)	PR 1605	GEC-ELLIOTT	1	05/73	
	124 Manual Input Modules (V	Vord Generators Parar	neter Units)			
			inter sinter			

	PARAMETER UNIT 12 BIT (PROVIDES 12 BIT Communication, push button L-Request)	P 2005	SEN	1	/70	
N	MANUAL INPUT REGISTER (INPJTS & HAND-SET 16-BIT WORD, MANUAL AND ELECTR LAM I/P)	1041	BORER	1	06/73	(8)
	DATA SWITCHES (16/24 BITS,READABLE + CONTENF ADDR)	C 322	INFORMATEK	1	/72	
N	24 BIT PARAMETER UNIT	2 501	BI RA SYSTEMS	1		
	WORD SENERATOR (240IT WORD MANUALLY SET BY SWITCHES)	WG 2401	GEC-ELLIOTT	1	/71	
N	24-BIT MANUAL INPUT	3460	KINETIC SYSTEMS	1	/73	
	WORD GENERATOR (24 BITS OF BINARY DATA, Switch selected)	9020	NUCL. ENTERPRISES	1	/71	(2)
C	24 BIT WORD GENERATOR , WITH LAM	WG R-241	STND ENGINEERING	1	08/73	
	PARAMETER UNIT (QUAD 4-DECADE BCD Parameters manually set)	022	NUCL. ENTERPRISES	4	/71	(2)
	PARAMETER UNIT (QUAD & DECADE BCD PARAMETERS MANUALLY SET)	C 105	RDT	4	/71	

127 Other Parallel Input Modules (Incl. Lam and Status Registers, see 232 for Lam Grader)

	24-BIT INTERRUPT REGISTER (STATUS COMPARED,CHANGE GIVES LAM)	1051	BORER	1	172	(3)
	PRIORITY INPUT REGISTER(123ITS DRED TO LAM,FAST CCINC LATCH APPL,NIM LEVELS)	63	JORWAY	2	/70	
	INTERRUPT REQUEST REGISTER (8BIT, TTL INPUTS TO REGISTER, ANY INPJT SIVES LAM.	7013-1	NUCL. ENTERPRISES	1	/70	
C	INTERRUPT REQUEST REGISTER	EC 218	NUCL. ENTERPRISES	1		
	REQUIRE REGISTER	300	POLON	1		

MANUFACTURER

13

Digital Output Modules — Serial: Clocks, Timers, Pulse Generators, Parallel: TTL Output, Drivers

131 Serial Output Modules (Clocks, Timers, Pulse GEN)

٧	TIMER MODULE	3655	KINETIC SYSTEMS	1	10/73	
	CRYSTAL CLOCK GENERATOR (7 TTL OUTPUTS FOR 1HZ TO 1MHZ FREQUENCY DECADES)	FHC 1303	BF VERTRIEB	1	/71	(1)
	CLOCK/TIMER (0.001S TO 10 HRS TIME INTER/AL,REAL-TIME OUTPUT)	1411	BORER	1	172	(3)
	CRYSTAL CONTROLLED PULSE GENERATOR (7 DE- CADES-1HZ TO 1MHZ-500NS PUUSES OUT, TTL)	PG 0001	GEC-ELLIOTT	1	/71	
	REAL TIME CLOCK (4SEC CLOCK/5MSEC STOP WATCH)	C 320	INFORMATEK	1	/72	
	CLOCK GENERATOR (INT 10MHZ, EXT 50MHZ, 8 DECADE STEPS,PLUS PROGRAMMABLE OUTPUT)	CG	JOERGER	1	172	(7)
	REAL TIME CLOCK (COUNTS .1 SEC TO 999 DAYS, DISPLAYS HRS/MIN/SEC, 50/60HZ GEN)	RTC	J O E RGE R	2	01/73	(7)
	CLOCK PULSE GENERATOR (7 OUTPJTS-1HZ T) 1MHZ-IN DECADE STEPS,10MHZ EXT IN, TTL)	7019-1	NUCL. ENTERPRISES	1	/70	
	CLOCK PULSE GENERATOR	730	POLCN	1	10/73	
	ASTRCNOMICAL TIME CLOCK	731	POLON	1	11/73	
	QUARZ CLOCK		POLCN	0	10/73	
	CLOCK PULSE GENERATOR(7 DECADES-1HZ T) 1MHZ-500 NSEC PULSES OUT,TTL 4ND NIM)	C 109	ч D T	1	/71	
	1 HZ - 1 MHZ QUARTZ CLOCK (7 0/P - 1HZ TO 1MHZ-200 TO 800 NSEC WIDTH, TTL LEVEL)	J HQ 10	SAIP/SCHLUMBERGER	1	/71	
	REAL TIME CLOCK (3.8 USEC TO 18.2 HRS, PRESET-TIME AND PRESET-COUNT MODES)	RTC 2014	SEN	1	/71	
	CL OC K/T IME R	C 76451-A14-A1	SIEMENS	1	/72	
	CAMAC-CLOCK-GENERATOR(7 DECADES-10 MHZ TO 1HZ,50/500 NSEC 0/P PULSES,2.8V/50 OHMS)	C-CG-10	MENZEL ELEKTRONIK	1	/71	
	TIME BASE (10 TO 100MHZ IN INCREMENTS OF 10MHZ, USED WITH TO 2031/TO 2041)	TB 2032	SEN	1	/71	
	TIMER	C 76451-A12-A1	SIEMENS	0		(6)
	TEST PJLSE GENERATOR (5 TO 50 NSEC NI4 O/P PULSE DERIVED FROM S1.F(25) OR EXT)	TPG 0202	GEC-ELLIOTT	1	/71	
	DJAL PROGRAMMED PULSE GENERATOR(50HZ/ 2KHZ/5MHZ PULSE TRAIN,LENGIH BY COMMAND)	2PPG 2016	SEN	1	/71	
	MJLTIPULSER (0.5-300 MHZ BURSTS,NIM SIGNAL,TTL TRIGGER,NIM OUT,600PSEC RISE)	C 72454-A1450-A1	SIEMENS	2	/72	
	SEQUENTIAL OUTPUT REGISTER (SERIAL-CODED NIM FULSES OUT,LOGIC 0=40NSEC,1=150NSEC)	SOR	SAIP/SCHLUMBERGER	1	/71	

132 Parallel Output Registers (TTL, HTL, NIM etc.)

	12 BIT PARALLEL OUTPUT REGISTER (NIM)	3251	BI RA SYSTEMS	1	04/73	
	12 BIT OUTPUT REGISTER(DC OP PULSE O/P, UPDATING STROBE OUTPUT,NIM LEVELS)	41	JOR WAY	1	/71	(2)
	OUTPUT REGISTER (128IT, NIM PULSES OR LEVELS OUT)	OR 2027	SEN	1	/70	
N	15 BIT PARALLEL OUTPUT REGISTER (TTL)	3211	BI RA SYSTEMS	1		
	DIFFERENTIAL OUTPUT REGISTER	3030	KINETIC SYSTEMS	1	172	(8)
	OUTPUT REGISTER (16BIT)	360	POLCN	1	09/73	
N	PARALLEL OUTPUT REGISTER (16BIT)	C-08-16	MENZEL ELEKTRONIK	0		
	OUTPUT REGISTER (24BIT TTL VIA SPEC CONN 8BIT ALSO VIA FRONT PANEL LEMD)	FHC 1309	3F VERTRIEB	1	172	
N	24 BIT OUTPUT REGISTER (TTL)	3221	JI RA SYSTEMS	1		
	PARALLEL DUTPUT REGISTER (24BIT TTL OUTPUT VIA 25-WAY CONVECTOR)	7054-3	NUCL. ENTERPRISES	1	/70	
	OUTPLT REGISTER (24BIT)	351	POLCN	1	09/73	
N	DUAL 16 BIT PARALLEL OJTPUT REGISTER(TTL)	3212	3 I RA SYSTEMS	1		
	OUTPUT REGISTER (2×1631T)	352	POLCN	1	09/73	

NC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR
	OUTPUT REGISTER (2X163IT VIA ISOLATING Contacts)	1082	BORER	1	172	
	DUAL 24 BIT PARALLEL OUTPUT RESISTER	3222	31 RA SYSTEMS	1	04/73	
	OUTPUT REGISTER (2X24BIT DATA OUT,DATA- READY + BUSY FORM HANDSHAKE, TTL)	R0-224	EG+G	1	/72	
	OUTPUT REGISTER (2X24BIT OR 6X8BIT, LED DISPLAY)	0 R	J O ERGE R	1	/72	(7)
C	24-BIT DUAL OUTPUT REGISTER	9042	NUCL. ENTERPRISES	1	172	(7)
С	DUAL OJTPUT REGISTER (2×243IT, DATAWAY	90 4 3 A	NUCL. ENTERPRISES	1		(7)
С	READ AND WRITE, HANDSTAKE SONTROL, LO-Z) DUAL OUTPUT REGISTER (2X24BIT, JATAMAY READ AND #RITE, HANDSHAKE SONTROL, HI-Z)	90433		1		(7)
	OUTPUT REGISTER (2X24BIT)	353	° O L ON	2	09/73	
	PARALLEL OUTPUT REGISTER (2×24 3ITS)	J RS 10	SAIP/SCHLUMBERGER	1	04/73	(7)
C	DUAL 24 BIT PARALLEL DUTPUT REGISTER (WITH LED DISPLAY OPTION)	PR-612	STND ENGINEERING	1	/71	(6)
	DIGITALES AUSGANGSREGISTER(4X8BIT PARALL	00 200-2501	DORNIER	1	/71	
	(WITH FRONT PANEL CONNECTOR)	00 200-2701		1	/72	
N	(WITHOUT WIRING BOARD)	00 200-2500		1	12/73	
Ν	DIGITALES AUSGANGSREGISTER(4X3BIT PARALL OUPTPUT REGISTER, HLL 12V)	DO 200-2505	DORNIER	1	12/73	
N	(WITH FRONT PANEL CONNECTOR)	DO 200-2705		1	12/73	
N	OUPTPUT REGISTER, HLL 12V, INVERTING)	00 200-2506		1	12//3	
N	(WITH FRONT PANEL CONNECTOR)	DO 200-2706		1	12/73	
N	OUPTPJT REGISTER, HLL 24V)	00 200-2507		1	12//3	
N	(WITH FRONT PANEL CONNECTOR) L	DO 200-2707		1	12/73	
ы	OUPTPUT REGISTER, HLL 24V, INVERTING)	00 200-2508		1	12/73	
N	(WITH FRONT PANEL CONNECTOR)	00 200-2708		1	12/73	
	OUTPUT REGISTER (32X16BIT, EX. ADDRESS)	101	1YTEC	1		
	128 BIT OUTPUT REGISTER (ADDRESSABLE AS 8 16BIT OR 128 1-BIT WORDS)	C 342	INFORMATEK	1	04/73	
	OUTPUT REGISTER (32X24BIT, EX. ADDRESS)	104	HYTEC	1		
h	OUTPUT REGISTER (16X24BIT, EX. ADDRESS)	105		1	06/77	
N	UUIFUI REJISIER (290A24811) EX AUURESS)			1	00//3	
	133 Parallel Output Drivers (Op	oen Coll., Relay, etc.)				

	12-BIT OUTPUT REGISTER (WITH OPTICAL ISOLATION, OPEN COLL O'P, MAX 30V/100MA)	3082	KINETIC SYSTEMS	1		
	12-BIT OUTPUT REGISTER WITH ISOLATED RELAY	3087	KINETIC SYSTEMS	1	/71	(4)
	8 BIT TRIAC OUTPUT REGISTER	3080	KINETIC SYSTEMS	1	05/73	
	SWITCH (12BIT DATAWAY CONTROL ED RELAY Register for switching and multiplexing)	7066-1	NUCL. ENTERPRISES	1	/71	
	DRIVER (16 BIT, OPEN COLLECTOR DJTPJT VIA Multiway connector, Max 150ma/line)	9002	NUCL. ENTERPRISES	1	/71	
	DIGITAL OJTPUT 16 BIT POT 244	C 76451-A9-A1	SIEMENS	0		(6)
N	PARALLEL OUTPUT REGISTER (16BIT)	C-0A-16	WENZEL ELEKTRONIK	0		,
Ν	RELAY DRIVER (16 WAY RELAY OUTPUT)	J RD 10	SAIP/SCHLUMBERGER	1	06/73	(8)
	DIGITAL OUTPUT 16 BIT RELAYS	C 76451-A9-A2	SIEMENS	0		(6)
	DRIVER (24BIT OUTPUT REGISTER,SET AND READ BY COMMAND,24BIT I/P DATA ACCEPTED)	9013	NUCL. ENTERPRISES	1	/71	
	DRIVER (24BIT OUTPUT REGISTER, SET AND READ BY COMMAND,24BIT I/P JATA ACCEPTED)	9017	NUCL. ENTERPRISES	1	/71	(1)
	OJTPUT DRIVER (2X16 BIT, 40MA SINKING,	OD 1613	GEC-ELLIOTT	1	/72	
	(SAME, 1=HI)	OD 1614		1	/72	
	OUTPUT DRIVER (2X16 BIF, 125 MA SINKING,	0D 1617	GEC-ELLIOTT	1	172	
	(SAME, 1=4I)	OD 1618		1	/72	
	OUTPUT DRIVER (2X16BIT, TOTEMPOLE FOR 30 TTL LOADS, WITH READ VIA DATAWAY)	OD 1620	GEC-ELLIOTT	1	/72	
	DUAL 16 BIT OUTPUT REGISTER (ITL LEVELS, OPEN COLL OUTPUTS VIA CABLE)	20R 2008	SEN	1	/70	
	PARALLEL-OLTPUT-REGISTER (DUAL 24BIT, OR QUAD 12 BIT, OPEN COLLECTOR QUTPUT)	MS P0 1 1230/1	AEG-TELEFUNKEN	1	/70	(1)

VIII

NC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR
	PARALLEL-OUTPUT REGISTER (24BIT, OPEN COLLECTOR OUTPUT, HANDSHAKE FACILITY)	MS PO 2 1230/1	AEG-TELE FUNKEN	1	/72 (4)
	OUTPUT DRIVER (2X24BIT, 40MA SINKING, WITH READ VIA DATAWAY, 1=L0)	OD 2403	GEC-ELLIOTT	1	/72	
	(SAME, 1=4I)	OD 2404		1	/72	
	OUTPUT DRIVER (2X24BIT, 125MA SINKING WITH READ VIA DATAWAY, 1=L0)	OD 2407	GEC-ELLIOTT	1	172	
	(SAME, 1=HI)	OD 2408		1	/72	
	OUTPUT DRIVER (2X24BIT, TOTEMPDLE FOR 30 TTL LOADS, WITH READ VIA DATAWAY)	OD 2410	GEC-ELLIOTT	1	/72	
N	DUAL OUTPUT REGISTER (2X243IT, OPEN 00 OUTPUTS, 150MA/50V, DATAWAY READ)	LL 200	HYTEC	1 1	0/73	
Ν	OUTPUT REGISTER (2X243IT OR 6X33IT, 250MA SINKING, DIODE CLAMPED)	0 R - 1	J O E RGE R	1 0	7/73	
	DUAL 24 BIT OUTPUT RESISTER (DC OR PULS O/P, UPD ATING O/P STROBE, TTL OPEN COLL)	E 40	JORWAY	1	/71 (2)
	DJAL 24-BIT OUTPUT RESISTER (DPEN COLL DRIVERS, MAX 24V OR 250M4, REAR OUTPUT	3072 S)	VINETIC SYSTEMS	1		
	DIGITALES AUSGANGSREGISTER(4X33IT PARA OUTPUT REGISTER, NO L. OPEN COLL O/P, 1=H	LL DO 200-2502	JORNIER	1	/72	
	(WITH FRONT PANEL CONNECTOR)	00 200-2702		1	/72	
	DIGITALES AUSGANGSREGISTER(4X33IT PARA OUTPUT REGISTER,NO L,OPEN COL. 0/9,1=L	LL DO 200-2503	DORNIER	1	/72	
	(WITH FRONT PANEL CONNECTOR)	DO 200-2703		1	172	
	DIGITALES AUSGANGSREGISTER MIT REED- RELAIS(4X8BIT OUTPUT REG, DPEN CONTACT=	DO 200-2504	DORNIER	1	/71	
	(WITH FRONT PANEL CONNECTOR)	JO 200-270+		1	/71	
	and Parallel I/O and Analyser Int 142 Parallel I/O Registe	Regs, Printer-, Tape-, erfaces, Step-Motor I ers (General Purpose)	DVM-, Plotter- Drivers, Supply CTR,	Displays		
	UNIVERSAL INPUT/OUTPUT REGISTER (36BIT DATA+RANGE IN,12BIT REG O/P FOR CONTRJ	1031	BORER	1	/72 (3)
ç	PARALLEL I/O REGISTER (32X24BIT)	100	HYTEC	1		
N	PARALLEL I/O REGISTER (32X16BIT) PARALLEL I/O REGISTER (16X24BIT)	101 102		1	172	
N	DJAL INPUT DUAL OUTPUT REGISTER (1681) TTL IN. OPEN COLL TTL OUT, MAX 40MA,3J	112 , C110	2 D T	1	172	
۵	INPUT/OUTPUT REGISTER (2X24BIT IN,2X53 O/P, HI-Z INPUT, LED DISPLAY)	IIT IR-1	JOERGER	1	/72 (7)
	143 Peripheral Interfaci	ng Modules (For TTY, Ta	ape etc.)			
	DESK CALCJLATOR CTRL (DIEHL INTERFACE FHC 1301/02/11 AND FHC 1309)	TO FHC 1312	3F VERTRIEB	1	172	
	TYPEWRITER DRIVE UNIT	TD 0301	SEC-ELLIOTT	2 0	6/73 (1)
	TYPEWRITER DRIVER FOR OPTIMA 527	501	POLCN	0 0	9/73	
	TELETYPE 0/P CTRL (10 FHC 1301/02/11 4 FHC 1309 VIA SPEC CONN,TTY MCFOR ON/OF	ND FHC 1307 F)	3F VERTRIEB	1	/71 (1)
	TELETYPE INTERFACE	θθ	JORWAY	2	/71	
	TELETYPEWRITER CRIVER (FOR ASR 33)	7043-1	NUCL. ENTERPRISES	1	/70	
	TELETY>EWRITER INTERFACE(I/O DATA TRA AND CONTROL,LAM USED AS TWO-WAY FLAG)	15F 7061-1	NUCL. ENTERPRISES	1	/70 (1)
	TELETYPEWRITER CRIVER	500	POLCN	1 (1 3 / 7 3	
	TELETYPE DRIVER	J TY 10	SA 1P/SCHLUMBERGER	1 (16/73 (8)
	TELETYPE INTERFACE	C - I - 3 3	WENZEL ELEKTRONIK	1	//2	
	VERSATEC LINE PRINTER INTERFACE	3320	KINETIC SYSTEMS	, 1	/72	
	PAPER TAPE PUNCH OUTPUT DRIVER (FOR FACIT 4070) TAPE READER INTERFACE UNIT	TP 0801	SEC-FLLIOTT	1 (16/73 (1)
	(FOR ELECTROGRAPHIC READER)					
Ν	MAGNETIC TAPE INTERFACE (TAPE DECKS OR CASSETTES)	CS 0342	NUCL. ENTERPRISES	1	/73 ((8)
	UNIVERSAL ASYNCHRONOUS TRANSMITTER/RECEIVER (129 CHAR.BUFFER)	C 317	INFORMATEK	1 (3/73	

IC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR
	B.S.INTERFACE READER (8BIT DAT& + PARITY BIT,3RITISH STANDARD)	7057-1	NUCL. ENTERPRISES	1	/71	
	B.S.INTERFACE DRIVER (8BIT DATA + PARITY BIT, BRITISH STANDARD)	7058-1	NUCL. ENTERPRISES	1	/71	(1)
	PERIFHERAL READER(8BIT PARALLEL DATA IN, NEG OR POS TTL.HANDSHAKE CONTROLS)	7064-1	NUCL. ENTERPRISES	1	/71	(1)
	PERIPHERAL DRIVER (BBIT DATA OJT, NEG OR POS TTL, HANDSHAKE CONTROLS)	7065-1	NUCL. ENTERPRISES	1	/71	(1)
	144 Display Modules, Display	and Plotter Interfacing				
	(ONE FHC 1301/02/11 VIA SPEC CONNECTOR)	FHC 1305	BF VERTRIEB	1	/71	(1)
	24 BIT NIXIE BCC DISPLAY (SELECTS ONE OF 10 FFC 1301/02/11 VIA SPEC CONNECTION)	FHC 1306	3F VERTRIEB	2	/71	(1)
	24 BIT LED BINARY DISPLAY (ONE FHC 1313 or FHC 1309 via special connection)	FHC 1315	BF VERTRIEB	1	/72	
	INDICATOR (1X16BIT OR 2X8BIT,INDICATES STATE OF REGISTER LOADED FROM DATAWAY)	9014	NUCL. ENTERPRISES	1	/71	
	SCALER DISPLAY THROUGH COMPUTER (DISPLAY OF 24BIT MOR))	J AF 15	SAIP/SCHLUMBERGER	2	/71	
	MANUAL BINARY DISPLAY (CONTENT OF A REGISTER DISPLAYED, EXT MULTIWAY CONN)	J AF 20	SAIP/SCHLUMBERGER	1	/71	
N	GRAPHIC DISPLAY DRIVER FOR HP1311/TEK502	4301	BI RA SYSTEMS	O		
	DISPLAY DRIVER (POINTPLOT CHAR GEN AND VECTCR GENERATOR)	DD 1601	GEC-ELLIOTT	2	06/73	(7)
	MEMORY OSCILLOSCOPE DISPLAY (VECTOR, CHARACTER AND HISTOGRAM SEN)	C 311	INFORMATEK	2	05/73	
	CRT DECIMAL DISPLAY SYSTEM (INCLUDING) DISPLAY DRIVER	72A 72A	JORWAY	NA 5	/71	(2)
N	DISPLAY SYSTEM COMPRISING DISPLAY SYNCHRONIZING DISPLAY TIMING DISPLAY CONTROL DISPLAY REFRESH (ALPHANUMERIC + GRAPHS) DUAL LIGHT PEN INTERFACE COLOR MONITOR	3200 3205 3210 3212 3225 RGB 1200 M	KINETIC SYSTEMS	1 1 1 1	/71 /71 /71 /71 /71 /72 /71	(4)
	STORAGE DISPLAY DRIVER	3260	KINETIC SYSTEMS	1	172	
	DISPLAY DRIVER (TWO 10BIT DAC,OJTPUT Range +5v to -5v,two operation modes)	7011-2	NUCL. ENTERPRISES	2	/70	(1)
	DECIMAL DISPLAY UNIT (ADDRESS AND 5 DATA	9007	NUCL. ENTERPRISES	NA	/71	
	DISPLAY CONTROLLER (FOR 9007, INCLUDES BIN TO DECIMAL CONVERTER)	9006		2	/71	
c	STORAGE OSCILLOSCOPE (DRIVER FOR TEKTRONIX 611 OR 601,JSED WITH 7011)	9028	NUCL. ENTERPRISES	1	/71	(2)
	SCOPE DISPLAY DRIVER Manual control of J dj 10	J DD 10 MC 10	SAIP/SCHLUMBERGER	2 N A	04/73	(7)
	EXTERNAL DISPLAY FOR J EA 10 SCALER	C AE 10	SAIP/SCHLUMBERGER	NA	04/73	
	SCOPE DISPLAY DRIVER X-Y-Z (SYSTEM) STORAGE DISPLAY DRIVER FOR TEXTRONIX 011	FDD 2012 SDD 2015	SEN	1 1	/71 /71	(1) (1)
	CHARACTER GENERATOR VECTOR GENERATOR LIGHT PEN FOR FCD 2012 OR CG 2018	CG 2018 VG 2028 LP 2035		1 1	/71 /71 /71	(1) (1)
Ν	RECORDER DRIVER	J XY.10	SAIP/SCHLUMBERGER	1	06/73	(8)
	THE WDV 3300 INTERACTIVE GRAPHICS SYSTEM COMPRISING DISPLAY UNIT LIGHT PEN GRAPHIC DATASENSOR	WDV 1855 WDV 1851 WDV 1833 G	WDV	0 0		

NC DESIGNATION + SHORT DATA

TYPE

MANUFACTURER

145 Instrumentation Interfacing Modules (DVM, Supply CTR, Stepping Motor Drivers, Pulse Analyser CTR)

	Pulse Analyser CTR)					
c	DUAL CHANNEL SERIAL OUTPUT MCDULE	3101	SI RA SYSTEMS	2	04/73	
N	DUAL CHANNEL SERIAL OUTPUT MCJULE	3102	BI RA SYSTEMS	2	04/73	
N	DUAL & CHANNEL SERIAL OUTPJT MODULE	3106	BI RA SYSTEMS	2	04/73	
N	DJAL 8 CHANNEL SERIAL OUTPUT MODULE	3107	3 I RA SYSTEMS	2	04/73	
	STEP MOTOR DRIVER (MAX 32758 STEPS,RATE, ROTATION AND START/STOP FULLY COMMANDED)	1161	BORER	1	172	(3)
	STEPPING MOTOR CONTROLLER, DUAL	3360	KINETIC SYSTEMS	1	172	(4)
N	STEPPING MOTOR CONTROLLER	3361	KINETIC SYSTEMS	1	10/73	
	STEPPING MOTOR DRIVER (USED WITH 7045)	0709	NUCL. ENTERPRISES	1	/71	
	DELAYED PULSE GENERATOR (4 TTL 3/P,0.042 HZ-40KHZ RATE,LEVEL AND DIRECTION CONTR)	7045-1	NUCL. ENTER PRISES	1	/70	
	STEPPING MOTOR DRIVER	J CP 10	SAIP/SCHLUMBERGER	1	01/73	
С	STEPPER CONTROLLER (CONTINUOUS)	C-ST-4	MENZEL ELEKTRONIK	2	/72	
С	STEPPER CONTROLLER - INCREMENTAL MOTOR	C-ST-4-I	WENZEL ELEKTRONIK	2	/72	
С	POWER SUPPLY CONTROLLER 12-BIF	3158	CINETIC SYSTEMS	1	/73	
N	CAMAC-TO-SCIPP MCA INTERFACE	2323	3 I RA SYSTEMS	2		
N	INTERFACE CAMAC-TO-LABEN 8000SERIES MULTICHANNEL ANALYZERS	5 3 8 0	LABEN	3		
C	MULTICHANNEL ANALYZER - CAMAC INTERFACE (FOR PACKARD 9000 AND 900 SERIES MCA)	9701	P A CKAR D	3		(4)
	CAMAC INTERFACE FOR CA25/CA13/097 ADC	J CCA 10	SAIP/SCHLUMBERGER	2	/71	
	DUAL INCREMENTAL POSITION ENCODER (2X20 BIT X-Y DIGITIZATION 3Y UP-DOAN COUNTER)	2IPE 2019	SEN	1	/71	
	OUTPUT REGISTER (16 OR 24 BIT TTL DRI√ER FOR FAST-ROUTING MULTIPLEXER SYSTEM)	CM 665	J AND P	1	/71	
	CAMAC COMMUNICATIONS CONTROLLER INTERFACE UNIT	MC 4036	MICRO CONSULTANTS	1	/71	(2)
	CAMAC VID-MOS INTERFACE UNIT	№C 4037	MICRO CONSULTANTS	1	/71	(2)
	CAMAC MOD 15 INTERFACE UNIT (TO IN-HOUSE PRODUCED A-D EQUIPMENT)	MC 5201	MICRO CONSULTANTS	1	/71	(2)
	INTERFACE FOR CAMAC CONTROL OF PRECISION HIGH SPEED ADCS	MC 4059	MICRO CONSULTANTS	0		(6)
	WIRE DETECTOR SCANNER(64X15BIT MEMORY STORES 13BIT POSITION+3BIT CLISTER DATA)	WCS-200	NANC SYSTEMS	1	/72	(5)
	SCANNER TEST MODULE	WCS-201		1	172	(5)
	PROPORTIONAL CHAMBER READ-DUT (USED WITH SPEC CONTROLLER TYPE COFIL OR ALONE)	REFIL	SAIP/SCHLUMBERGER	2	/71	
	SPARK CHAMBER READ OUT (POSITION AND ADDRESS CODING CF MULTIPLE SPARK SITES)	J SC 10/SCR0-041	SAIP/SCHLUMBERGER	2	/70	(6)
	SPARK CHAMBER READ OUT TERMINAL	SCRO TML-043		5	/70	
	PLUMBICON READ OUT (5 SCALERS RECORD DIGITIZED OUTPUTS FROM PLUMBICON CAMERA)	J PM 10/PLUM	SA IF/SCHLUMBERGER	1	/71	(6)
	PLUMEICON READ OUT TERMINAL	J PG 10/PUDDING		1	/71	(6)
N	ADC/CAMAC INTERFACE (FOR INHOUSE ADC3, 2x168IT O/P BUFFER,STATUS + LAM HANDL)	G-A1-2	WENZEL ELEKTRONIK	0		
	147 Other Digital I/O Modules	(Incl. Data Links)				
	START-STOP CONTROLLER(START,STOP,RESET, MANUAL OR DATAWAY CONTROL, 100HZ CLOC<)	FHC 1304	BF VERTRIEB	1	/71	(1)
Ν	FERNUEBERT RAGUNSANSCH_USS (V24/V23/V21 MODEM INTERFACE WITH AUTO-DIAL OPTION)	00 200-2911	DORNIER	1	12/73	
	SENSOR (INTER. UP TO 65.00) GROUPS OF 16/32 BITS, READS PATTERNS OR ADDRESSES)	C 347	INFORMATEK	1	04/73	
Ν	SERIAL INTERFACE (#24 SPEC)	90 45	NUCL. ENTERPRISES	1	08/73	
	TRANSMISSION LINE DRIVER		POLON	0		
	START-STOP UNIT (START, STOP CLOCK AND GATE OUTPJTS)	J AM 10	SAIP/SCHLUMBERGER	1	/71	
	FOUR FOLD BUSY CONE (START SIGNAL INITIATED BY COMMAND,OEVICE RETURNS LA4)	4BD 2021	SEN	1	/71	

XI

NC DESIGNATION + SHORT DATA

TYPE

Digital Handling and Processing Modules — and/or/not Gates, Fan-Outs, Digital Level and Code Converters, Buffers, 15 Delays, Arithm. Processors etc.

151 Fan-Outs, and/or/not-Gates

	FAN-OUT UNIT (2 ORED INPUTS PROVIDE 8 TRUE,2 COMPLEM OUTPUTS,NIM SI3NALS)	FO 0901	GEC-ELLIOTT	1	/71	
N	FAN OUT MODULE (IL2 I/P, 16 IL2 O/P)	9050	NUCL. ENTERPRISES	1	11/73	
	SIX-FOLD CONTROLLED GATE (INDIV GATING, FAN-IN AND FAN-OUT CONTROLLED BY 3 REGS)	6CG 2017	SEN	1	/71	(4)
	152 Digital Level Converters					
	6 CHANNEL TTL/NIM CONVERTER	5601	BI RA SYSTEMS	1	04/73	
	6 CHANNEL NIM/TTL CONVERTER	5602	3 I RA SYSTEMS	1	04/73	
	HEX NIM TO TTL CONVERTER	3450	KINETIC SYSTEMS	1	05/73	
	HEX ILZ TO IL1 CONVERFER (5 NIM SIGNALS IN,6 TTL SIGNALS OUT)	7051-1	NUCL. ENTERPRISES	1	/70	
	HEX IL1 TO IL2 CONVERTER (5 TTL SI3NALS IN,6 NIM SI3NALS OUT)	7052-1	NUCL. ENTERPRISES	1	/70	
	QUIN L1 TO IL1 CONVERTER(5 HARWELL STAN- DARD L1 SIGNALS IN 5 TTL SIGNALS OUT)	7053-1	NUCL. ENTERPRISES	1	/70	
	153 Code Converters			3		
	CAMAC BCD-TO-BINARY CONVERTER	LEM-52/5.7	EISENMANN	1		
	BINARY TO-BCD-CONVERTER (24BIF BIN,8 Decimal digit output via two connectors)	7068-1	NUCL. ENTERPRISES	1	/70	(2)
C	BINARY CODE CONVERTER(BIN-3CD OR 3CD-BIN Conversion, data from data4ay or front)	9044	NUCL. ENTERPRISES	1		(7)
	BINARY TO DECIMAL CODE CONVERTER	610	POLON	1	10/73	
	BINARY TO BCD-CCNVERTER(24BIT TO 8 DECA- DE,DISPLAY,CONV 4USEC,TTL LEVEL OUT,1=+)	C-3BC-24	WENZEL ELEKTRONIK	2	/71	
	154 Buffer Memories, Storage	Units				
C N	OUTPUT REGISTER (256X24BIT, RAM + 32X24 OUTPUT REGISTER (256X24BIT, RAM + 64X24 BIT ROM, EX ADDR , FOR USE WITH 7025-2)	110 110A	HYTEC	1 1		
N	A/D, 12BIT BCD, 16 WAY MULTIPLEXER, 16X24BIT STORE, 100USEC/CHANNEL UPDATE)	500	HYTEC	1	12/73	
	CAMAC 16 WORD 24 BIT MEMORY	MC 5202	MICRO CONSULTANTS	2	/72	(6)
	16 WORD STORE	CS 0003	NUCL. ENTERPRISES	1		(4)
	256 WORDS OF 24 BIT STORE MODULE	CS 0015	NUCL. ENTERPRISES	1	/72	(7)
	PROGRAMMABLE READ ONLY MEMORY	220	POLON	1		
C	BUFFER MEMORY (256 15 BIT WORDS, USE WITH J CAN 21/C/H)	J MT 20	SAIP/SCHLUMBERGER	1	/72	
	155 Logic and Arithmetic Proc	essing Modules				
	FLOATING POINT ARITHMETIC INTERFACE (FOR USE WITH M 128 HARD. FLOAT. POINT)	C 327	INFORMATEK	1	01/73	
	16 Analogue Modules —	ADC, DAC, Multip	lexers, Amplifiers,			

Analogue Modules — ADC, DAC, Multiplexers, Amplifiers, Linear Gates, Discriminators etc.
161 Analogue Input Modules (DC and Pulse ADC, TDC)

N	32 CHANNEL ANALOG DATA SYSTEM (EXPANDABLE WITH ADDITIONAL MUX MODULES)	5 30 1	BI RA SYSTEMS	2		
	ANALCSUE TO DIGITAL INTEFACE (WITH PLUG- IN CONVERTER CARDS ACC/8Q, ADS/10Q AND ADC/12Q FOR 8, 10 AND 12 BIT SONVERSION)	ADC 1201	GEC-ELLIOTT	1	/71	(1)
N	ANALCGUE TO DIGITAL CONVERTER (20MHZ)	CS 0046	NUCL. ENTERPRISES	1	10/73	
	ANALCGUE TO DIGITAL INTEGR. CONVERTER	700	POLON	1	09/73	
	VOLTAGE - FREQUENCY CONVERTER	J CTF 10	SAIP/SCHLUMBERGER	2	04/73	
	UP-DOWN SCALER/FREQUENCY METER	J EF 10		1	04/73	
	DUAL DIGITAL VOLTMETER (+AND- D.1V, 10 BIT, DIFFERENTIAL INPUT)	2DVM 2013	SEN	1	/71	
	DIGITALVOLTMETER (RANGES% DC0.02 TO 20V, 5 MA TO 100 MA,AC 0.0I TO 20 V BOTH POL)	C 76451-A13-A1	SIEMENS	2		
	DIGITAL VOLTMETER (SAME AS TYPE C 76451-A13-A1 WITH DISP_AY)	C 76451-A13-A2	SIEMENS	2		
	ANALCGE EINGAENGE(MULTIPLEXER-ACC, 8 DIFF I/P,+/-10V RANJE,7BITS/10V+SIGN)	00 200-1013	DORNIER	2	/72	
	AN AL CGE EINGAENGE(MULTIPLEXER-ADC, TO ONE ADC,+/-5V RANGE,7BITS/ 5V+SIGN)	00 200-1016	DORNIER	2	/72	
	ANALOGE EINGAENGE(MULTIPLEXER-ADC, 8 DIFF I/P, +10V RANGE,8BITS/10V)	00 200-1019	DORNIER	2	/72	
	ANALCGER EINGANG (ADC, +/-10V RANGE, 7BITS/10V+SIGN)	D0 200-1027	DORNIER	2	/72	
	(SAME FOR +/-5V RANGE, 7BITS/3V +SIGN) (SAME FOR +10V RANGE, 8BITS/1JV)	00 200-1028 00 200-1029		2	/72 /72	
	ANALOGUE TO DIGITAL CONVERTER(8BIT, I/3 Range 0 to +5v cr 0 to -5v,25 usec conv)	7028-1	NUCL. ENTERPRISES	1	/70	
N	DUAL 10 BIT A/D	5304	BI RA SYSTEMS	1		
N	SUCCSESS. APPROX. ADC (WITH SAMPLE AND HOLD, -5V TO +5V, 10-3IT)	1244	BORER	2	06/73	
	DUAL 10 BIT ANALOG TO DIGITAL CONVERTER	3515	KINETIC SYSTEMS	1	03/73	
	DUAL SLOPE ADC (+AND- 0.01/1/10V RANGES, 11BIT RESOLUTION,20MS CONV TIME)	1241	BORER	2	/72	(3)
C	SUCCESS. APPROX. ADC (WITH SAMPLE AND HOLD, -1V TO +1V, 12-3IT)	1243	BORER	2	172	
	ANALCGE EINGAENGE (MULTIPLEXER-ADC, 8 DIFF I/P,+/-10V RANJE,11BITS/10V+SIGN)	DO 200-1003	JORNIER	2	172	
	ANALOGE EINGAENGE(MULTIPLEXER-ADC, 8 DIFF I/P,+/-5v RANGE,11BITS/ 5v+SIGN)	DO 200-1006	JORNIER	2	/72	
	ANALCGE EINGAENGE(MULTIPLEKER-ADC, 8 DIFF I/P, +10 V RANGE, 12BITS/10V)	00 200-1009	DORNIER	2	/72	
	ANALCGER EINGANG (ADC, +/-10V RANGE, 11 BITS/ 10V +SIGN)	DO 200-1024	DORNIER	2	/72	
	(SAME FOR +/-5V RANGE,11BITS/ 5V+SIGN) (SAME FOR +10V RANGE,12BITS/1)V)	00 200-1025 D0 200-1026		2	/72 /72	
М	A/D, 12BIT BCD, 16 WAY MULTIPLEXER, 16X249IT STORE, 100USEC/CHANNEL UPDATE)	500	HYTEC	1	12/73	
	A/D CONVERTER (12BIT,MAX 20 USEC CONVER- SION, + AND-5V, +AND-10V, +10V RANGES)	30	JORWAY	2	/71	(2)
	DUAL 12 BIT ANALOG TO DIGITAL CONVERTER	3520	KINETIC SYSTEMS	1	05/73	
	CAMAC ADC/DAC UNIT (PC CAR) FOR SAMPLE- HOLD 12 BIT ADC AND DAC CIRCUITS)	MC 5200	MICRO CONSULTANTS	1	/72	(6)
	ANALCSUE TO DIGITAL CONVERTER (123IT, 20 MSEC CONVERSION, RANGE -5 V TO +5 V)	7055-1	NUCL. ENTERPRISES	1	/70	
	ANALCEER EINGANGIOUAL SLOPE ADC, +/-10/ RANGE,14BITS/10v+SIGN,0.2SEC CONVERSION)	DO 200-1021	DORNIER	1	/72	
	OCTAL CHARGE DIGITIZER (8X8BIT CHARGE Sensitive Adc, readout in 4x15bit words)	QD 808	E G + G	0		(7)
	MULTI-MODE LINEAR ADC (8BIT,4)MHZ CLOCK, AREA AND PEAK MCDES,NIM LEVELS)	2243A	LRS-LECROY	1	/70	(2)
¢	OCTAL ADC (8 FAST I/P,8BIT/CH, SOMMON GATE, NIM LEVELS, BILINEAR MODE)	2248	LRS-LECROY	1	/71	
	OCTAL ADC (MIN 5 NSEC PULSES, POS OR NEG 8bit/100 PC resolution, 250 USEC CONV)	9040	NUCL. ENTERPRISES	1	/72	(4)

NC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR
	ADC - MEMORY INTERFACE (FOR J CAN 20/21 AND BM 96)	J CAN 20 I	SAIP/SCHLUMBERGER	2	/71	
	15.000 CHANNEL PULSE ADC (20044Z CLOCK)	J CAN 21 C/H	SAIP/SCHLUMBERGER	6	/72	(6)
	1024 CHANNEL PULSE ADS (100 MHZ SLOCK)	J CAN 40	SAIP/SCHLUMBERGER	2	/72	(6)
	QUAD CAMAC SCALER (4X16BIT OR 2X32BIT, 40MHZ)	1004	BORER	1	/72	
	TIME DIGITIZER (4x16BIT,50MHZ CLOCK,WITH CENTRE FINDER, USABLE WITH PRE-AMP 511)	1005	3 O RER	1	/72	
	TIME DIGITIZER (4 NIM STOP CHANNELS, Common start, 200 psecs resolution)	TD104	Ξ G + G	1		(7)
	QUAD 16-BIT SPARK READ-OUT REGISTER (20MHZ RATE,TTL LE√ELS)	SR 1604	GEC-ELLIOTT	1	/71	
	QUAD TIME-TO-DIGITAL CONVERTER(9BIT/CH, 102/510NSEC RANGES,13JSEC CONVERS,NIM)	2226A	LRS-LECROY	1	/70	(2)
	TIME DIGITIZER(4X16BIT,CLOSK RATE 70/85MHZ, WITH CENTER FINDING LOGIC)	TD 2031	SEN	1	/72	
	TIME DIGITIZER (4X16BIT,CLJCK RATE 70/85MHZ.NIM LEVELS)	TD 2041	SEN	1	/72	(4)
	SERIAL TIME DIGITIZER (8X83IT 100MHZ, SER + SEQUENT COUNT MODE SATEL-REG GATE)	STD 2050	SEN	1	/72	
N	DUAL SYNCHRO-DIGITAL CONVERTER (14BIT)	CS 0047	NUCL. ENTERPRISES	2	10/73	
	162 Applogue Output Modulos					
	102 Analogue Output Modules	(DAC)				
	ANALCEER AUSGANG (DAC, 12BIT RESOLUTION,	00 200-1501	DORNIER	2	/71	
	(SAME BUT WITH +AND-10V OUTPUT RANGE) (SAME BUT WITH +AND-5V OUTPUT RANGE)	00 200-1503 D0 200-1505		2 2	/71 /71	
	ANALCSE AUSGAENGE (DAC, 12BIT RESOLUTION,	00 200-1502	DORNIER	2	/71	
	(SAME BUT WITH +AND-10V OUTPUT RANGE) (SAME BUT WITH +AND-5V OUTPUT RANGE)	DO 200-1504 DO 200-1506		2 2	/71 /71	
N	ANALOGER AUSGANG (DAC BBIT RESOLUTION,	00 200-1511	DORNIER	1	12/73	
N	(SAME BUT 12BIT RESOLUTION)	00 200-1521		1	10/73	
Ν	ANALOGER AUSGANG (DAC 8BIT RESOLUTION,	D0 200-1512	DORNIER	1	12/73	
N	(SAME BUT 12BIT RESOLUTION)	DO 200-1522		1	10/73	
Ν	ANALCGER AUSGANG (DAC 8BIT RESOLUTION, +AND-104 OUTPUT RANGE, 5MA)	00 200-1513	DORNIER	1	12/73	
N	(SA ME BUT 12BIT RESOLUTION)	DO 200-1523		1	10/73	
Ν	ANALCGER AUSGANG (DAC 8BIT RESOLUTION, +AND-10 V OUTPUT RANGE, 5MA, 2 OUTPUTS)	DO 200-1514	DORNIER	1	12/73	
N	(SAME BUT 12BIT RESOLUTION)	DO 200-1524		1	10/73	
N	ANALCGER AUSGANG (DAC 8BIT RESOLUTION, +AND-5V OUTPUT RANGE, 5MA)	DO 200-1515	DORNIER	1	12/73	
Ν	(SAME BUT 12BIT RESOLUTION)	00 200-1525		1	10/73	
Ν	ANALCGER AUSGANG (DAC 8BIT RESOLUTION, +AND-5V OUTPUT RANGE, 5MA, 2 SUTPUTS)	00 200-1516	JORNIER	1	12/73	
N	(SAME BUT 12BIT RESOLUTION)	00 200-1526		1	10/73	
N	ANALCGER AUSGANG (DAC 8BIT RESOLUTION, +10V OUTPUT RANGE, 5MA, 4 DUTPUTS)	00 200-1517	JORNIER	1	12/73	
N	(SAME BUT 12BIT RESOLUTION)	30 200-1527	2004750	1	10/73	
N	ANALOGER AUSGANG (DAC 8011 RESOLUTION, +AND-10 V OLTPUT RANGE, 5MA, 4 OUTPUTS)	00 200-1518	JORNIER	1	12/73	
N	(SAME BUT 12BIT RESOLUTION)	00 200-1528	DODUTED	1	10/73	
N AI	+AND-5V OUTPUT RANGE, 5MA, 4 OUTPUTS)	00 200-1519	JURNIER		12773	
N	CAMAC BINARY-TO-BCD CONVERTER	LEM=52/5-8	ETSENMANN	1	10775	
ы	WITH DECIMAL DISPLAY		LISENNANN	1		
	OCTAL DAC (8 CHANNELS,10BIT 5/ 503HMS 3R 2 S CMPL 9BIT+SIGN, +AND-5V, 10 USEC)	DAC 1081	GEC-ELLIOTT	1	04/73	(7)
Ν	DUAL D/A CONVERTER (1) BIT, 1)USEC CONV TIME, +10V, +AND-10V, +AND-5V RANGES)	D/A-10	J O E RGE R	1	09/73	
N	DJAL D/A CONVERTER (12 BIT, 30 USEC CONV TIME, +10V, +AND-10V, +AND-5V RANGES)	D/A-12	J O E RGE R	1	09/73	
	D/A CONVERIER (128IT,5 USE: CONVERSION, O/P RANGES +AND-2.5V/5V/10V AND +5V/10V)	31	JORWAY	1	/71	(2)
	8 CHANNEL 10 BIT D-A CONVERTER	3110	KINETIC SYSTEMS	1	172	
	CAMAC ADC/DAC UNIT (PC CARD FOR SAMPLE- HOLD 12BIT ADC AND DAC CIRCUITS)	MC 5200	MICRO CONSULTANTS	1	/72	(6)

XIV

IC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR	
	DIGITAL TO ANALOGUE CONVERTER	7015	NUCL. ENTERPRISES	1	/70		
	DIGITAL TO ANALOGUE CONVERTER	720	POLON	1	09/73		
	DIGITAL TO ANALCGUE CONVERTER	721	POLON	2	09/73		
	VOLTAGE CALIBRATOR	J ET 10	SAIP/SCHLUMBERGER	1	04/73		
	DUAL DIGITAL-TO-ANALOG CONVERTER (1081T, OUTPUT 0 TO +10V OR -5 TO +5V)	2DAC 2011	SEN	1	/71		
	STROME NERATOR (CURRENT SOURCE)	C 76451-A5-A1	SIEMENS	2			
	DUAL-DIGITAL-ANALOG-CONVERTER (SAME WITH 12 BIT) (SAME WITH 16 BIT)	C 76451-A15-A1 C 76451-A15-A2 C 76451-A15-A3	SIEMENS	1 1 1		(6) (6)	
	164 Analogue Handling and	Processing Modules I	(MX)				
	ELEKTRONISCHER MULTIPLEXER (8 DIFF I/P,	00 200-1033	DORNIER	1	172		
	MAX +OR-10V, DATAWAY SET+INCR ADDRESS) (WITH FRONT PANEL CONNECTOR)	DO 200-1233		1	/72		
	12 INPUT AMALOGUE MULTIPLEXER (RANDOM OR SCAN ACCESS CONTROLLED BY SKIP REGISTER)	MX 2025	SEN	1	/72	(6)	
	15 CHANNEL MULTIPLEXER (ANALOGUE SIGNALS ROUTED TO ADC/DVM,DIRECT + SCAN MODES)	1701	BORER	1	/72	(3)	
	SEE ALSO DCRNIER ADC TYPES		DORNIER				
	RELAISMULTIPLEXER (16 CHANNELS, MAX 200V/	00 200-1035	DORNIER	2	/71		
	(WITH FRONT PANEL CONNECTOR)	00 200-1235		2	/71		
	RELAIMULTIPLEXER (16 CHANNELS, MAX 200V/ 750MA OR 10VA: DATAWAY SETFINCE ADDRESS)	00 200-1036	DORNIER	1	/72		
	(WITH FRONT PANEL CONNECTOR)	00 200-1236		1	172		
	ANALCG MULTIPLEXER (15 CHANNELS, REED RELAYS, MAN AND DATAWAY SEL, EXPANDABLE)	AM	J O E RGE R	2	/72	(6)	
	15 CHANNEL RELAY MULTIPLEX	3530	KINETIC SYSTEMS	2	01/73		
N	MASTER MULTIPLEXER (16 CH, 4 POLE REED) SLAVE MULTIPLEXER (16 CH, & POLE REED)	601 600	NUCL. ENTERPRISES		/70 /70		
	15 CHANNEL RELAY MULTIPLEXER STANDARD LEVEL)	J MX 10	SAIP/SCHLUMBERGER	1	04/73		
	(SAME FOR LOW LEVEL) MULTIPLEXER MANUAL CONTROL	J MX 20 J AX 10		1	04/73 04/73		
	16-CHANNEL FAST MULTIPLEXER (FET SWITCHES FOR ADC 1242 AND 1243)	1704	BORER	1	/72	(4)	
	ELEKTRONISCHER MULTIPLEXER (15 CHANNELS,	00 200-1031	DORNIER	1	172		
	(WITH FRONT PANEL CONNECTOR)	00 200-1231		1	172		
	ELEKTRONISCHER MULTIP.EXER(16 DIFF I/P, MAX +OR-10 V. DATAWAY SET+INCR ADDRESS)	00 200-1034	DORNIER	1	172		
	(WITH FRONT PANEL CONNECTOR)	DO 200-1234		1	172		
	MJLTIPLEXER-SOLID STATE (16 SINGLE-ENDED OR 8 DIFF CHAN, RANDOM OR SEQUENT ACCESS)	9026	NUCL. ENTERPRISES	1	/71		
	MULTIPLEXER (32 CHANNEL, 2 CONTACTS)	C 76451-A4-A1	SIEMENS	2			
	MULTIPLEXER (32 CHANNEL, 4 CONTACTS)	C 76451-A4-A2	SIEMENS	2			
	ELEKTRONISCHER MULTIPLEXER (32 CHANNELS, Max +or-10v, dataway set+incr address)	DO 200-1032	DORNIER	1	172		
	(WITH FRONT PANEL CONNECTOR)	DO 200-1232		1	172		
	ELEKTRONISCHER MULTIPLEXER (32 DIFF I/P, MAX +OR-10V, DATAWAY SET+INCR ADDRESS)	DO 200-1037	DORNIER	2	172		
	(SAME WITH FRONT PANEL CONNECTORS)	00 200-1237		2	172		
N	ELEKTRONISCHER MULTIPLEXER (64 CHANNELS MAX +OR-10V, DATAWAY SET+INCR ADDRESS)	00 200-1061	DORNIER	2	12/73		
Ν	WITH FRONT PANEL CONNECTOR)	00 200-1261		2	12/73		

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TYPE

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165 Analogue Handling and Processing Modules II (LIN. Gates, Ampl., Discriminators etc.)

	SAMPLE-AND-HOLD VERSTAERKER (DUAL DIFF	00 200-1040	DORNIER	2	/72	
	AMPL, #7-10 V RANGE, ZUMA (UI, SUSEC SEITL) (SINGLE AMPL VERSION, BOTH TYPES HAVE HOLD AND TRACK MODES)	DO 200-1041		2	/72	
	PROGRAMMIERBARER VERSTAERKER/ABSCHW (ATTENUATION -600B TO 0DB, 6 STEPS, AMPLIFICATION 0DB TO 50DB, 6 STEPS)	00 200-1052	DORNIER	2	04/73	
N	PROGRAMMIERBARE VERSTAERKER/ASSCHWAECHER	00 200-1053	DORNIER	1	12/73	
	GAIN DDB TO GODB IN 6 STEPS, 2 CHANNELS)			NA		
	DIFFERENTIAL AMPLIFIER (GAIN CONTROLLED FROM DATA#AY)	CS 0014	NUCL. ENTERPRISES	2	172	
	DUAL ATTENUATOR(50 OHMS,DATAWAY CONTROL- LED,RANGE ODB TC 31DB IN 10B STEPS)	9004	NUCL. ENTERPRISES	1	/71	
	ATTENUATOR (O DB TO 60 DB, MANUAL AND DATAWAY CONTROLLED)	J AT 10	SAIP/SCHLUMBERGER	3	/70	
	DIGITAL WINDOW DISCRÌMINATOR (WITH 128X15BIT BUFFER, PARALLEL + SERIAL I/P)	OWD 2046	SEN	1	172	(8)
	17 Other Digital and/or A and Digital, Not Datav	Analogue Modules - way Connected etc.	— Mixed Analogue			
N	NUMERICAL CONTROL SYSTEM Comprising cassette recorer c 503,	C 500	RDT	NA		

 COMPRISING CASSETTE RECORDER C 503,
 NA

 DATA WRITER AND DISPLAY C 504, AND TYPES
 0

 N SERIAL CONTROLLER
 C 502
 0

 DATA RECEIVER FOR MECHANICAL OPERATIONS
 C 501
 0

 (5 DECADE DATA, 3 DECADE INSTRUCTION REG)
 0

2 SYSTEM CONTROL EQUIPMENT — COMPUTER COUPLERS, CONTROLLERS AND RELATED EQUIPMENT

21 Interfaces/Drivers and Controllers — Parallel Mode for 4600 Branch and Other Multi-Crate Bus, Single-Crate Systems, Autonomous Systems

211 Interfaces/Drivers for Multicrate Systems I (4600 Branch Compatible)

EXECUTIVE SUITE ASSEMBLY OF MODULAR CONTROLLERS IN CAMAC CRATE, COVERS SYSTEM COMPLEXITY FROM SINGLE SOURCE-SINGLE CRATE TO MULTI		GEC-ELLIOTT			
SOURCE-MULTI CRATE SYSTEMS, COMPRISING Executive controller (Transforms Standard Crate Into System (Pate)	NX-CTR-2		2	/72	
BRANCH COUPLER (ONE PER BRANCH, MAX 7)	BR-CPR-2		2	/72	
AND SYSTEM INTERFACE SOURCE UNITS, ALSO OPTIONALLY AUTONOMOUS CONTROLLER SOURCE UNITS (ALL INSERTED INTO SYSTEM CRATE)		SEC-ELLIOTT			
AUTONOMOUS CONTROLLER 1 (FOR MULTILEVEL AUTONOMOUS BLOCK TRANSFERS VIA DMA)	SC-ACU-1	GEC-ELLIOTT	1	06/73	
PDP-11 SYSTEM INTERFACE, COMPRISING		SEC-ELLIOTT			
PROGRAM TRANSFER INTERFACE	PTI-11 C/D		3	/72	
UNIBUS TERMINATION UNIT	TRM-11		1	/72	
SYSTEM INTERFACE BUS (LINKS UNIBUS TO	SI-BUS-X11			172	
INTERPHET VECTOR GENERATOR (ADDS AUTON)-	TVG-11		1	172	
MOUS ENTRY OF GL-DERIVED INTERRJPTS)					
DIRECT MEMORY ACCESS INTERFACE (ADDS	DMA-11		1	06/73	
MULTICHANNEL DMA, NEEDS AUTONO40JS CTRL)					
NOVA/SUPERNOVA SYSTEM INTERFACE, COMPR		GEC-ELLIOTT			
PROGRAM TRANSFER INTERFACE	PTI-N C/D		3	172	
I/O BUS TERMINATION UNIT	TRM-N		1	/72	
SYSTEM INTERFACE BUS	SI-BUS-XN			/72	
INTERRUPT VECTOR GENERATOR	IVG-N		1	04/73	
INTERDATA 70-SERIES SYSTEM INTERFACE		SEC-ELLIOTT			
PROGRAM TRANSFER INTERFACE	PTI-70 C/D		3	04/73	
I/O EUS TERMINATION UNIT	TRM-70		1		
SYSTEM INTERFACE BUS	SI-BUS-X70			04/73	
INTERRUPT VECTOR GENERATOR	IVG-70		1	04/73	
HONEYWELL 316/516 SYSTEM INTERFACE COMPR		SEC-FLLIOTT			
PROGRAM TRANSFER INTERFACE	PTI-H16 C/D		3	05/73	
I/O EUS TERMINATION UNIT	TRM-H16		1		
SYSTEM INTERFACE BUS	SI-BUS-XH16			05/73	
GEC 2050/4080 SYSTEM INTERFACE, COMPR		SEC-FULTOTT			
DIRECT TRANSFERS INTERFACE	PTI-2050 C/D		3	05/73	
SYSTEM INTERFACE BUS	SI-BUS-X2050			05/73	
				~	(\/I
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NC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR
	SYSTEM CRATE TEST UNIT (TWJ-COMMAND TEST UNIT FOR CHECKING SYSTEM CRATE SYSTEMS)	SC-TST-1	GEC-ELLIOTT	3	172	
C	MICRCPROGRAMMED BRANCH DRIVER FOR PDP-11 (WITH 256, 512, or 1k words of memory)	1201	BI RA SYSTEMS	NA	/72	(5)
	INTERFACE/SYSTEM CONTROLLER TO DEC PDP9 (PROGR, SEQUENT AND BLOCK TRANSFERS)	2202	BORER	NA	/71	(4)
	INTERFACE/SYSTEM CONTROLLER TO DEC PDP15 (PROGR, SEQUENT AND BLOCK TRANSFERS)	2203	BORER	NA	/71	(4)
	PJP-11 CAMAC CONTROLLER(SEQUENTIAL READ/ WRITE,24 GRADED-L INTERRUPF DIRECTLY)	CA 11-A	DEC	NA	/71	(2)
	PDP-15 CAMAC INTERFACE(18/24BIT, PROGR, SEQUENT ADDR AND BLOCK TRANSFER MODES)	CA 15 A	DEC	NA	/71	(1)
	PDP-9 CAMAC INTERFACE (Somewhat modified ca 15 a)	CA 15 A/PDP-9) E C	NA	/71	
	PDP-11 INTERFACE/BRANCH DRIVER (24 VECTOR ADDRESSES, PROGRAMMED AND MULTIPLE DMA-TRANSFER, ADDRESS SCAN AND -LIST MODE, REPEAT-, LAM- AND STOP MODE)	CA 11-C	DEC	NA	/72	(4)
	PDP-11 BRANCH DRIVER (EUR 460) COMPATI- BLE, PROGRAMMED AND SEQUENT ADJR MODES)	BD-011	E G + G	NA	/71	
	PDP-11 BRANCH DRIVER	KS 0011	KINETIC SYSTEMS	NA	/71	(4)
	INTERFACE AND DRIVER FOR PDP 11 OR PDP 8		NUCL. ENTERPRISES			
	BRANCH INTERFACE	90 31		2	/72	(7)
	FOLLOWING INTERFACE CARDS)	90.30		5	172	(7)
	INTERFACE CARD FOR DEC PDP 8 SERIES	90 34			04/73	(7)
С	INTERFACE CAMAC-PDP 11 (PROGRAMMED,BLOCK TRANSFER AND SEQUENTIAL ADDR 100ES)	ICP 11/ICP 11 A	SAIP/SCHLUMBERGER	NA	/71	(4)
	PDP-11 SYSTEM CONTROLLER	C-CSC-11	∉ENZEL ELEKTRONIK	2	/72	
	NOVA BRANCH DRIVER	1251	BI RA SYSTEMS	NA	04/73	(5)
	INTERFACE/SYSTEM CONTROLLER TO HP2100, 2114, 2115, 2116	2201	30RER	NA	/71	(4)
	INTERFACE FOR VARIAN 6201/L/F COMPUTER (PROGR, SEQUENT AND BLOCK TRANSFERS)	2204	BORER	NA	/72	
N	SYSTEM CONTROLLER FOR SIEMENR 434/3 (TRANSFER OF 16 OR 24 BIT DATAWORDS PARALLEL BRANCH COMMAND CHAININS)	00 200-2921	JORNIER	6	12/73	
N	(SAME BUT WITHOUT COMMAND CHAINING)	00 200-2922		6	12/73	
N	SYSTEM CONTROLLER FOR SIEMENR 404/3 (TRANSFER OF 16 OR 24 BIT DATAHORDS PARALLEL BRANCH BUT NO COMMAND CHAININS)	00 200-2923	JORNIER	6	12/73	
	MICRODATA 800/CIP 2003 BRANCH DRIVER	91	JORWAY	NA	05/73	(7)
	BRANCH DRIVER (24BIT, PROGR, SEQUENT AND BLOCK TRANSFER MODES, MAX 7 CRATES)	5400	LABEN	4		(8)
	H316/DDP516 CAMAC BRANCH HIGHWAY DRIVER (MEETS EUR 4600 SPECS)		MICRO CONSULTANTS	NA		
N	INTERFACE-DRIVER FOR VARIAN 73/5201/620L		NUCL. ENTERPRISES			(8)
	BRANCH INTERFACE	90 31		2	/72	(7)
ч	AND THEFTA CE CARD FOR VARTAN 73/5201/620	50.50		3	112	(9)
н	SERIES COMPUTERS	00 00 99				
	INTERFACE FOR K202 COMPUTER	100	OL ON	3	09/73	
N	INTERFACE CAMAC - T2000 A BASIC BRANCH CONTROL RACK	C COB 10	SAIP/SCHLUMBERGER	NA	/73	
Ν	CAMAC - T2000 BRANCH INTERFACE	T SC 20		NA	173	

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TYPE

212 Interfaces/Drivers for Multicrate Systems II (for other Parallel Mode Control/Data Highway)

DATAWAY CONTROLLER DDP-516(PART OF 7000- SER SYSTEM WITH EXT CONTROL HIGHWAY)	7022-1	NUCL.	ENTERPRISES	4	/70
				10 I	
PROGRAMMED DATAWAY CONTROLLER (PART OF	7025-2	NUCL	ENTERPRISES	2	/70
7000-SER SYSTEM WITH EXT CONTR HIGHWAY)		10020	CHIERINISES	-	//0
SEQUENTIAL COMMAND GENERATOR	7037-1			2	/70
COMMAND GENERATOR	7062-1			2	/71
TRANSFER REGISTER	7063-1			1	170
PROGRAM CONTROL UNIT	0362-2			NA	170
WIRED STORE	7044-1			1	/70
PLUGBOARD STORE	7077-1			3	174
	10/1 1			3	111
DATAWAY CONTROLLER PDP-8 (PART OF 7000-	7048-2	MUCL	ENTERDOTOES	2	170
SER SYSTEM WITH EXT CONTROL HIGHWAY)	1010 2			-	//0
AUXILIARY CONTROLLER	7047-1			4	170
DATA BREAK MODULE (USED WITH 7048)	CS 0009			1	172
	00 0000			- -	116
CRATE CONTROLLER FOR NOVA COMPUTER	CC 20234/8	SEN		2	170
CRATE CONTROLLER BUS TERMINATOR FOR	BT 2022	JEN		1	171
CC 2023A/B (ONE PER SYSTEM)				-	//1
				5.	
IBM 1130 INTERFACE SYSTEM (FOR HIGH	NOV 1300	HO V			
SPEED DATA ACQUISITION, PROCESSING AND	NOT 3000	NOV			
INTERACTIVE GRAPHICS. COMPRISING				18	
INTERFACE CONTROL UNIT	WDV 1002			0	
EXTENSION MODULE (MULTIPLEVER)	WDV 1060			0	
PRIORITY MODILE	NDV 1008			0	
MILTTPLEYER (DATA)	HDV 4133			0	
HULLITELALN (DAIM)	MDA TT22			0	

213 Interfaces/Drivers for Single-Crate Systems (4100 Dataway Compatible)

SINGLE CRATE CONTROLLER TO HP (CERN TYPE 066)	1531	BORER	2	/72	
CRATE CONTROLLER/POP11 UNIBUS INTERFACE NPR CONTROLLER FOR DMA TO POP11 E.G. VIA 1533A CRATE CONTROLLER/INTERFACE	1533A 1542	BORER	2 N A	/72 05/73	(4) (8)
SINGLE CRATE SYSTEM CONTROLLERS(SEE EXECUTIVE SUITE, CLASS .211)		SEC-ELLIOTT			
PDP-11-SERIES CRATE CONTROLLER	1304	BI RA SYSTEMS	2	02/73	
DEDICATED CRATE CONTROLLER FOR PDP-11 (MULTIPLE TRANSFER OR AUTO ADDRESS SCAN)	OC011	E G + G	2		(7)
UNIBUS CRATE CONTROLLER POP-11	3911	KINETIC SYSTEMS	2	/72	
INTERFACE AND DRIVER FOR PDP 11 OR PDP 8		NUCL. ENTERPRISES			
16-BIT CONTROLLER (WITH EITHER OF THE	90 30		3	172	(7)
POP 11 INTERFACE CARD INTERFACE CARD FOR DEC POP 8 SERIES	90 32 90 34			/72 04/73	(7)
AUTONOMOUS CONTROLLER FOR PDP 11	9033	NUCL. ENTERPRISES	2	04/73	(8)
CAMAC CRATE-PDP 11 INTERFACE	J CC 11	SAIP/SCHLUMBERGER	2		(7)
CRATE INTERFACE FOR PDP 8/I	J CPDP 8/I	SAIP/SCHLUMBERGER	3	04/73	
NOVA-SERIES CRATE CONTROLLER	1303	BI RA SYSTEMS	2	02/73	
VARIAN- CAMAC INTERFACE CRAFE CONTROLLER (16BIT SEQUENT+BLOCK TRANSF, 1 3C/CRAFE)	C 300	INFORMATEK	2	/72	
CONTROLEUR DE CHASSIS MULTI 8-CAMAC (24Bit, Progr, simult i/o, interrupt modes)	JCM 8	INTERTECHNIQUE	3	/71	
CONTROLEUR DE CHASSIS MULTI 20 - CAMAC (24Bit, progr, sipult i/o, interrupt modes)	JCM 20	INTERTECHNIQUE	3	10/73	
INTERFACE CARD FOR VARIAN 73/5201/620L SERIES COMPUTERS	CS 0044	NUCL. ENTERPRISES			(8)
INTERFACE-DRIVER FOR VARIAN 73/6201/620L		NUCL. ENTERPRISES			(8)
16-BIT CONTROLLER	9030		3	/72	(7)
CRATE INTERFACE FOR MULTI 5	J CM 8		3	/72	
CRATE CONTROLLER 320	C 72451-A6-A1	SIEMENS	3	/72	
CRATE CONTROLLER 404	C 76451-A7-A1	SIEMENS	0		

214 Controllers for Autonomously Operated Systems (and Related Units)

Ν	DATENPROZESSOR (AUTONOMOUS PROGRAMABLE	00 200-2951	DORNIER	3	12/73	
2 2 7	(SAME WITH 48 REGISTERS) (SAME WITH 48 REGISTERS) (SAME WITH 64, REGISTERS)	00 200-2952 00 200-2953 00 200-2954		3 3 3	12/73 12/73 12/73	
Ν	SPEICHER FUER DATENPROZESSOR	00 200-2961	DORNIER	1	12/73	
NNN	(SAME BUT 768 WORDS OF 16 BITS) (SAME BUT 768 WORDS OF 16 BITS) (SAME BUT 1024 WORDS OF 15 BITS)	DO 200-2962 DO 200-2963 DO 200-2964		1 1 1	12/73 12/73 12/73	
N	SPEICHER FUER DATENPROZESSOR	00 200-2971	DORNIER	1	12/73	
NN	(SAME BUT 2048 WORDS OF 15 BITS) (SAME BUT 3072 WORDS OF 15 BITS)	00 200-2972 D0 200-2973		1	12/73 12/73	
	IN DEPEN DENT PROCESSER	130	POLCN	3	10/73	
	217 Other Parallel Mode Int	erfaces/Drivers/Controll	ers			
	SYSTEM 300 0 CONTROLLER (FOR DISTRIBUTED INTERFACE SYSTEM, PARALLEL MODE)	1552	BORER	2	/72	
	22 Interfaces/Controlle	rs/Drivers for Serial I	Highway			
	SYSTEM 3000 CONTROLLER (FOR DISTRIBUTED INTERFACE SYSTEM, SERIAL MODE)	1551	BORER	2	/72	(7)
Ν	SERIAL EXTENSION UNIT. 8 BIT BYTE SERIAL		JOERGER		08/73	(8)
N	SERIAL DRIVER (TERMINATES BRANCH HIGHWAY AND RETRANSMITS COMMAND SERIALLY)	SD		2		
Ν	SERIAL RECEIVER (RECEIVES SERIA_ DATA, DRIVES TYPE A-1 SYSTEM, OPTICAL ISOL)	SR		2		
	23 Units Related to 460 Highway — Crate Co Branch/Bus Extende	0 Branch or Other P ontrollers, Terminatio	arallel Mode Control/ ons, Lam Graders,	Data		
	DISPLAY DRIVER(CONTROLS 72A DISPLAY, Also crate ctr and branch jriver)	72 A	JORWAY	5	/71	
	231 Crate Controllers (Type	A-1, Other CC Types)				
	TYPE A-1 CRATE CONTROLLER	1301	31 RA SYSTEMS	2	02/73	
	CRATE CONTROLLER /ESONE TYPE A1/ (CONFORMS TO EUR4600 SPECS)	1502	3 O RER	2	/72	
N	CRATE CONTROLLER TYPE CCA-1 ACCORDING TO EUR4600 SPECS WITH CERN OPTIONS	DO 200-2905	DORNIER	2	03/74	
	CAMAC CRATE CONTROLLER TYPE A-1 (CONFORMS TO EUR4600 SPECIFICATIONS)	CC101	EG +G	2	/72	
	ESONE TYPE A-1 CRATE CONTROLLER (CONFORMS TO EUR 4600 SPECS)	CC 2405	GEC-ELLIOTT	2	01/73	
	CRATE CONTROLLER TYPE A-1 (CONFORMS TO EUR4600 SPECS)	CCA-1	JOERGER	2	/72	(5)
	BRANCH CRATE CONTROLLER/TYPE 4-1 (CONFORMS TO EUR 4600 SPECS, 1972)	70 A	JORWAY	2	02/73	(7)
	TYPE A-1 CRATE CONTROLLER	3900	KINETIC SYSTEMS	2	03/73	
	CRATE A CONTROLLER (CONFORMS TO EUR 4600 SPECS)	9016	NUCL. ENTERPRISES	2		(4)
	CRATE CONTROLLER TYPE A (CONFORMS TO EJR4600 SPECS)	C 106	RDT	2	/71	
	CRATE CONTROLLER TYPE A-1 (CONFORMS TO EUR4600 SPECS)	J CRC 51	SAIP/SCHLUMBERGER	2	/72	(1)
	A-1 CRATE CONTROLLER (CONFORMS TO EUR4600 SPECS, INCL CERN SPEC HOLD LINE)	ACC 2034	SEN	2	/72	
	CRATE CONTROLLER A (CONFORMS TO EUR 4500 SPECS)	C 72451-A1446-A2	SIEMENS	2	/70	(1)
С	TYPE A-1 (ESONE) CRATE CONFROLLER	CC-A1	STND ENGINEERING	2	/72	(6)
C	TYPE A1 CONTROLLER WITH TERMINATOR (MEETS 4600 SPECS OF JAN 1972)	CCT-A1	STND ENGINEERING	2		
	CRATE CONTROLLER TYPE D (CONFORMS TO EJR 4100, USED WITH DO 280 COMPUTER SYSTEM)	00 200-2901	DORNIER	2	/71	

XIX

	232 Lam Graders	·				
	LAM GRADER (24 BIT MASK REJISTER, PLUG-IN PATCH BOARD, CERN 064)	LG 2401	SEC-ELLIOTT	1	/72	
С	LAM GRADER (INTERNALLY PATCHABLE, SWITCH SELECTABLE MULTI-CRATE BG-RESPONSE)	LG	JOERGER	1	05/73	(8)
	LAM GRADER-SORTER	75	JORWAY	3	05/73	(7)
	LAM GRADER (DESIGNED TO EUR 4600 SPECS)	064	NUCL. ENTERPRISES	1	/72	(4)
	LAM GRADER (CERN SPECS 064)	C 107	RDT	1	/71	
	LAM GRADER (CERN SPECS 064)	LG 2001	SEN	1	/72	(6)
	233 Terminations (Simple, with	th Indicators)				
	BRANCH HIGHWAY TERMINATOR	6601	31 RA SYSTEMS	1	03/73	
N	CC-11 TERMINATOR	6603	BI RA SYSTEMS	2		
N	BRANCH HIGHWAY TERMINATOR	6602	BI RA SYSTEMS	1		
	TERMINATION UNIT	1591	BORER	2	/71	
	TERMINATOR MODULE (BRANCH HIGHWAY TERMINATOR)	TC024	EG+G	2	/71	
	BRANCH HIGHWAY TERMINATION MODULE(MOUNTS DIRECTLY ON BRANCH HIGHWAY ASSEMBLY)	CD 18107	EMIHUS	NA	/72	
	BRANCH TERMINATION UNIT	BT 6601	GEC-ELLIOTT	2	/71	
	BRANCH TERMINATION UNIT (NON INDICATING)	BT 6503	GEC-ELLIOTT	2	/72	
	BRANCH TERMINATOR	BT	JOERGER	2	/72	
	BRANCH TERMINATION WITH INTEGRAL CABLE	50C	JORWAY	2	/72	
	BRANCH TERMINATOR IN A CONVECTOR	BT-01	KINETIC SYSTEMS	NA	01/73	
	BRANCH TERMINATOR	J BT 20	SAIP/SCHLUMBERGER	2	/71	
	CRATE CONTROLLER BUS TERMINATOR FOR A-1 CRATE CONTROLLER	BT 2042	SEN	1	/72	
C	BRANCH HIGHWAY TERMINATOR	BH T - 0 0 1	STND ENGINEERING	1	/73	
С	BRANCH HIGHWAY TERMINATOR, WITH DISPLAY	BHT-002/D	STND ENGINEERING	2	173	
	BRANCH TERMINATION UNIT (LED DISPLAY WITH MEMORY)	BT 6502	GEC-ELLIOTT	2	/72	
	VISUAL BRANCH TERMINATOR (STORES AND DISPLAYS ON LEDS BRANCH SIGNALS)	VBT	J O E RGE R	2	/72	(6)
	BRANCH TERMINATION WITH BRANCH DISPLAY	51	JORWAY	2	172	
	BRANCH TERMINATION UNIT (WITH INDICATOR)	C 72451-A10-A1	SIEMENS	NA		(3)
	234 Branch Extenders, Bus Ex	tenders				
	DIFFERENTIAL BRANCH EXTENDER (FOR EXTENDING BRANCHES UP TO 3 KM)	DBE 6501	GEC-ELLIOTT	2	/71	
	DIFFERENTIAL MODE BRANCH HIGH#AY EXTENDER (BI-DIRECTIONAL)	55	JORWAY	NA	06/73	(7)
	BRANCH HIGHWAY TRANSCEIVER FOR LONG DISTANCE TRANSMISSION	J BHT 10	SAIP/SCHLUMBERGER	2		(4)
	UNIBUS EXTENDER, TRANSMITTER RECEIVER (FOR DISTANCES UP TO 200 METRE DR MORE)	1594 1595	BORER	2	/72	

NC DESIGNATION + SHORT DATA TYPE MANUFACTURER WIDTH DELIV. NPR

XX

3 TEST EQUIPMENT

31 System Related Test Gear

SYSTEM TEST UNIT SYSTEM CONFIGURAT	(FOR EXECUTIVE SUIT ION, SEE MX-STR-2)	SC-TST-1	GEC-ELLIOTT	3	/72	
311	Computer Simulators					
PDP-11 SIMULATOR		6101	31 RA SYSTEMS	NA	/72	(5)
32	Branch Related Testers	/Controllers and Di	isplays			
321	Branch Testers/Controllers	(Manual, Programmed	()			
TEST MODULE (USED READ/WRITE CAPABI	IN SYSTEM TEST OF LITY)	TM024	E G + G	2	/71	
BRANCH HIGHWAY TE ECT,22 INDIRECT A	ST POINT MODULE(24 DIR- CCESS POINTS FOR TEST)	CD 18104	EMIHUS	NA	/71	(3)
BRANCH HIGHWAY RE (REMOVES INHIBIT	MOVE INHIBIT MODULE FROM BCR/3A/3F/BN/BTA)	GD 18105	EMIHUS	NA	/71	(3)
MANUAL BRANCH DRI SYSTEMS)	VER (FOR TESTING TYPE A	MBD	JOERGER	5	/72	(6)
MANUAL BRANCH CON (COMPRISING TYPES	TROL SET C COB 10 AND T CMB 10)	C CMB 10	SAIP/SCHLUMBERGER	NA	/71	(1)
ADDRESS SCANNER (CRATE OPERATIONS)	MANUAL CONTROL OF	C-AS-20	WENZEL ELEKTRONIK	2	172	

33 Dataway Related Testers and Displays

331 Dataway Controllers/Testers (Manual, Programmed)

	MANUAL CRATE CONTROLLER	1351	31 RA SYSTEMS	2	04/73	
	DATAWAY TEST MODULE (TESTS DATAWAY FOR OPEN LINES AND SHORTS)	DT 086	EG+G	3	/72	
	MANUAL CRATE CONTROLLER	GFK-LEM	EISENMANN	8	/71	
	MANUAL CRATE CONTROLLER	MCC	JOERGER	5	/72	
	MANUAL DATAWAY CONTROLLER	7024-1	NUCL. ENTERPRISES	8	/70	
	MANUAL CRATE CONTROLLER	J CMC 10	SAIP/SCHLUMBERGER	8	/71	(1)
	MANUAL DATAWAY CONTROLLER/DISPLAY SYSTEM INTERFACE TO DATAWAY CONTROL AND DISPLAY CRATE	D AI 10 J DA 10 C AI 10	SAIP/SCHLUMBERGER	1 NA	/71	
	TEST MODULE FOR CRATE CONTROLLER AND Dataway	DTM 2040	SEN	1	/72	
c	MANUAL 24 BIT CRATE CONTROLLER	MCC-240	STND ENGINEERING	2	172	(5)
	DYNAMIC TEST CONTROLLER (GENERATES ALL POSSIBLE CAMAC COMMANDS IN SINGLE CRATE)	TC 2403	GEC-ELLIOTT	3	/71	
	DYNAMIC TEST CONTROLLER (2 SIMULT TRANSF SINGLE, STEP-BY-STEP AND CONTINUOUS MODE)	C 108	TOF	8	/71	(4)
	CONTROLEUR SORTIE DATAWAY (DATAWAY TEST MODULE)		TRANSRACK	1	/70	

NC DESIGNATION + SHORT DATA

TYPE

332 Dataway Displays

CAMAC TEST MODULE/DATAWAY DISPLAY	6102	3 I RA SYSTEMS	2	03/73	
CAMAC DATAWAY DISPLAY (DATAWAY SIGNAL Pattern stored/displayed,2 test modes)	1801	30 RER	1	/71	(1)
CAMAC DATAWAY TEST AND DISPLAY MODULE	LEM-52/16.2	EISENMANN	1		
DATAWAY TEST MODULE(FULL DATAWAY MONITOR WITH INTERNAL STORAGE AND LED DISPLAY)	DTM 3	GEC-ELLIOTT	1	172	
DATAWAY MEMORY (DISPLAY + READABLE REGISTER)	C 340	INFORMATEK	1	172	
DATAWAY DISPLAY (STORES AND DISPLAYS Dataway Signals, Farwaxcizs1s23p1p2)	DD	J O E RGE R	1	/72	(6)
DATAWAY DISPLAY	3290	KINETIC SYSTEMS	1	/72	
DATAWAY DISPLAY	C 76451-A16-A1	SIEMENS	1		(6)
C DATAWAY DISPLAY MODULE	DD-002	STNC ENGINEERING	1	/72	(5)
DATAWAY DISPLAY	C-D1-24	WENZEL ELEKTRONIK	1	/72	
DATAWAY DISPLAY (INDICATES LOGIC	9019	NUCL. ENTERPRISES	NA	/71	(1)
DATAWAY BUFFER (OUTPUTS TO 9019 DATAWAY SIGNALS ACCESSIBLE IN NORMAL STATION)	9018		1	/71	(1)

34 Module Related Test Gear (Module Extenders)

341 Module Extenders

N	CAMAC EXTENDER MODULE		8201	BI RA SYSTEMS	0		
	EXTENSION FRAME (MODULE EXTENDER)		EF 1-1	GEC-ELLIOTT	1	/71	
	MODULE EXTENDER (+AND-6V,+AND-24V FU: Retractable locking device)	SED,	ME	JOERGER	1	172	
	EXTENSER MODULE		11	JORWAY	1	/71	
	EXTENDER CARD		1100	KINETIC SYSTEMS	1	/71	(4)
	EXTENSION UNIT		7007-1	NUCL. ENTERPRISES	1	/70	
	EXTENDER			POLCN	1	04/73	
	EXTENDER		GEX	RDT	1	/72	
	MODULE EXTENDER		ME 2030	SEN	1	/70	
C	EXTENDER (XXX=LENGTH OF CA3LE		577/XXX	TEKDATA	1	/72	(5)
Ν	EXTENDER (XXX=LENGTH)F CABLE IN MM BEYOND RACK, DOUBLE #IDTH)		5813/XXX		2	03/73	
	PROLCNGATEUR POUR TIRDIRS CAMAC (EXTENDER)			TRANSRACK	1	/70	

37 Other Test Gear for CAMAC Equipment

N TRANSIENT GENERATOR (MODULE NOISE SUSCEPT TG JOERGER 1 08/73 IBILITY TESTED BY TRANSIENTS ON DC LINES

4 CRATES, SUPPLIES, COMPONENTS, ACCESSORIES

41 Crates and Related Components/Accessories — Crates with/without Dataway and Supply, Blank Crates, Crate Ventilation Gear

XXII

NC	DESIGNATION + SHORT DATA	TYPE	MANUFACTURER	WIDTH	DELIV.	NPR
	411 Crates with Dataway a	nd Supply				
	CRATE (270 VA, COOLED, MODULAR POWERED BY	1902A	3 O RER	25	/69	
	UP TC 8 REGULATORS 1922 OR 1925+1922) VOLTAGE REGULATOR (FOR +OR-24V/6A,	1922			/69	
	+/-12V/7A,+/-6V/8A/16A24A) VOLTAGE REGULATOR (+AVD-6V, 25A MAX, 270W RATING, USABLE WITH 4X1922)	1925			03/73	
	CRATES WITH DATAWAY AND POWER	1250-0006	DUCKERT	25	/71	
	CAMAC-RAHMEN MIT DATENWEG UND DREHSTROMNETZGERAET (POWERED CRATE)	1250-0021	DUCKERT	25	/72	
	CAMAC-RAHMEN MIT DATENWEG UND 220 V 50 HZ NETZGERAET (POWERED CRATE)	1250-0022	DUCKERT	25	/72	
	POWERED CRATE	MC100	EG+G	25	/71	
	CONVERTS FASTON CONNECTORS TO RECOMMEND- ED FIXED POWER CONNECTOR ON CHOSEN CRATE	/A MP	GEC-ELLIOTT		01/73	
	P3WERED CRATE (+AND-6V/35A,+AND-12V/4A, +AND-24V/8A,200V/0.1A,117V4C, M4X 300H)	CPC/9	3 R ENSON	0		(6)
	POWERED CRATE (+AND-6V/25A,+AND-24V/6A)	CP U/8	SRENSON	24	/71	(2)
N	POWERED CRATE	1530	KINETIC SYSTEMS	NA	/73	
	POWER CRATE (7005-2 CRATE WITH 9022 Power Supply)	9023	NUCL. ENTERPRISES	24	/71	(2)
N	POWERED CRATE (+AND-6V/25A, +4ND-24V/6A, (INCL POWER DESIGN TYPE AE2432 SUPPLY)	NSI-875CC100AEC432	NUCL. SPECIALTIES	25		
	CHASSIS ET TIROIRS AVEC ALIMENTATION (POWERED CRATE)		POLON	25	/71	
	CAMAC POWER SUPPLY (+AND- 6V/25A, +AND- 24V/6A)	AEC-432	POWER DESIGNS	25	/72	
	POWERED CRATE	CCHN-CSAN	RDT	25	/71	
N	POWERED VENTILATED CRATE (+6V/24A, -6V/16A, +AND-24V/3A, MAX +004)	C JAL 41	SAIP/SCHLUMBERGER	25	/73	(8)
	POWERED CRATE(SEE P4 ALJ 13) POWERED CRATE(SEE P6 ALJ 13) POWERED CRATE(SEE P7 ALJ 13)	C4 ALJ 13 D G6 ALJ 13 D G7 ALJ 13 DW	SAPHYMO-SRAT	25 25 25	/71	(1) (1) (1)
	POWER SUPPLY (CAMAC CRATE) POWER SUPPLY (CAMAC CRATE)	CM5125/53/DW/BIP CM5125/53/AW/BIP	SAPHYMO- SRAT	25 25	172	
	POWER CRATE (200W MAX,+61/25A,-51/10A,	PC 2006/8	SEN	25	/70	
	+AND-12 V/3 A, +AND-24 V/3A, 200 V/3.05A) POWER CRATE (200W MAX, +6V/25A, -5V/10A, +AND-24 V/3 A, 200 V/0.05A)	PC 2006/C		25	/71	
	POWERED CRATE (70, VENT, +AND-64/26A,+AND-	C 76455-A2	SIEMENS	25	/71	(3)
	12V/6.5A,+AND-24V/6.5A,200V/0.1A,200W) POWERED CRATE (SAME BUT WITH 117V AC)	C 76455-A1		25	/71	
	POWERED CRATE (+AND-6//25A, +AND-24//6A, OPTIONAL + AND-12//3A,+AND-200//0.1A)	PCS	STND ENGINEERING	25		(5)
	412 Crates with Dataway, v	without Supply				
	CAMAC-RAHMEN MIT DATENWEG	1250-0001		25	/72	
	FASTON CONNECTORS)	VC 0010	SEC-ELLION	24	//0	
	VENTILATED CRATE (STANDARD 25 STATION FASTON CONNECTORS)	VC 0011	GEC-ELLIOTT	25	172	
	VENTILATED CRATE (HEAVY DUTY 25 STATION FASTON CONNECTORS)	VC 0021		25	/72	
	CAMAC CRATE VERCRANTET (EMPTY CRATE WITH WIRED DATAWAY)	2.084.000.6	KNUERR	25	/70	(2)
	UNPOWERED CRATE WITH F.P.C. DATAWAY	9	MB METALS	25	172	
	CRATE WITH F.P.C. DATAWAY AND POWER RAIL ASSEMBLY	TYPES 1,2,5,6	MB METALS	25	172	
	CRATE	7005-2	NUCL. ENTERPRISES	24	/70	
	CRATE WITH DATABAY, NO POWER		POLCN	25	/71	
	UNPOWERED CRATE WITH DATAWAY () (350 MM) () (325 MM)	CM 5125/33/AW CM 5125/33/DW CM 5125/53/AW CM 5125/53/DM	SAPHYMO- SRAT	25 25 25 25	/71	
	UNPOWERED CRATE WITH JATAWAY	UPC 2029	SEN	25	/70	

NC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR
	CRATE (WIRED CRATE)	WCS	STND ENGINEERING	25		(5)
	413 Crates without Dataway,	with Supply				
N	CAMAC COMPATIBLE CRATE (WIRED)	NSI-875 DB-WV	NUCL. SPECIALTIES	25		
N	CAMAC CRATE	NSI-875 CC 100	NUCL. SPECIALTIES	25		
	417 Blank Crates and Other C	Components and Acces	sories			
	CRATE WITH F.P.C. POWER RAIL ASSEMBLY	TYPES 3,4,7,8	MB METALS		/72	
	CRATE (5U, EMPTY, 25 STATIONS) (SAME BUT WITH 24 STATIONS) CRATE (6U, EMPTY, WITH VENTILATION BAFFLE,	MCF/5CAM/S/25 MCF/5CAM/S/24 MCF/6CAM/SV/25	IMHOF-BEDCO	25 24 25	/71 /72 /71	
	25 STATIONS, HARWELL TYPE 7000) (SAME BUT WITH 24 STATIONS)	MCF/6CAM/SV/24		24	/72	
	REMOVACE FANEL, 25 STNS, 44R4ELL 7000)	MCF/6CAM/SVR/25		25	//1	
	CRATE (60 EMPTY, WITH VENTILATION BAFFLE)	IB/9905-5HV1	OSL/IMHOF-BEDCO	25	01/73	
	FAN MOUNTING PLATE (FOR IB/9905-5HV1)	CAM/FM			01/73	
	CAMAC CRATE (EMPTY) CAMAC CRATE (EMPTY,INCL HARDWARE SUPPLY CHASSIS AND VENTILATION PANEL)	2.080.000.6 2.086.000.6	KNUERR	25 25	/70	(2) (2)
	CAMAC COMPATIBLE CRATE	NSI 875 DB/WV	NUCL. SPECIALTIES	25	/70	
	CA MAC CRATE	NSI 875 CC 100	NUCL. SPECIALTIES	25		(5)
	CHASSIS CAMAC (6 UNITES AVEC FENTE	9905-1-05	OSL	25	/71	
	DE VENTILATION, 525 MM PROFONDEUR) (360 MM PROFONDEUR)	9905-2-05		25	/71	
	CHASSIS CAMAC POUR TIROIRS MOJULAIRES, VIDES (EMPTY CRATES)		POLON	25	/71	
	VENTILATED CRATE NO POWER NO DATAWAY (THO FANS)	CCHN	ROT	25	/71	
	(SAME WITH 3 FANS)	CCHNA		25	/72	
	CAMAC SYSTEM BIN (WITH MODULAR SUPPLY)		RO ASSOCIATES	25	/70	
	CRATE, EMPTY	C 76455-A3	SIEMENS	25	172	
	CAMAC CRATE (EMPTY CRATE) CAMAC CRATE (EMPTY CRATE)	C CS	STND ENGINEERING	25 25		
	CHASSIS CAMAC NORMALISE 50	CM 5025 30	TRANSRACK	25	/70	
	(460 MM DEEP) (525 MM DEEP)	CM 5025 40		25		
	CHASSIS CAMAC 50 UTILES (EMPTY CRATE.6)	CM 5125 30	TRANSPACK	25	/70	
	TOTAL, 360MM DEEP, VENTILATION ARDWARE) (460 MM DEEP)	CM 5125 40		25		
	(525 MM DEEP)	CM 5125 50		25		
	CHASSIS CAMAC 5U UTILES (EMPTY CRATE, TOTAL 6U,360 MM DEEP,WITH ONE FAN)	CM 5125 31	I RANSRACK	25	/70	
	(525 MM DEEP)	CM 5125 41 CM 5125 51		25		
	CHASSIS CAMAC 50 UTILES (EMPTY CRATE, J Total, 360MM DEEP, WITH TWO FANS)	CM 5125 32	TRANSRACK	25	/70	
	(460 MM DEEP) (525 MM DEEP)	CM 5125 42 CM 5125 52		25 25		
	CAMAC CRATE	SUCAN	WILLSHER + QUICK	25	/71	(2)
	(5U NON-VENTILATED,380 MM DEEP) (6U VENTILATED,NO FAN,380 MM DEEP)	6UCAM		25		(2)
N	CAMAC CRATE (EMPTY) HEAVY DUTY	OURCAN	WILLSHER + OUTCK	25	/73	(2)
N	6U WITH VENTILATION BAFFLE 5U NON VENTILATED DEPTH OPTIONS 360MM, +60MM, 525MM	9905-5HV 9905-5H		25 25	/73	
	1U COOLING DRAWER (FOR CRATE ONLY, 2 Fans, FITS 6U CRATE)	CDR 1	GEC-ELLIOTT		/72	
	2J CCOLING DRAWER (COOLS GRATE AND GRATE Mounted PS 0003,FAN+CONTROL PANEL INCL)	CDR 2	GEC-ELLIOTT		/72	
	VENTILATION UNIT	CAM/FV	IMHOF-BEDCO		01/73	
	LUFTEREINHEIT (VENTILATION UNIT, COMPLETE WITH 3 FANS AND FILTER)	2.081.000.6	KNUERR		/70	
	(VENTILATION UNIT, NO FAN, NO FILTER)	2.085.000.6				
	FAN UNIT (FOR ALB/10 SUPPLY SYSTEM)	VALB/10	SAPHYMO-SRAT		172	
	CRATE BLOWER UNIT		STND ENGINEERING			(5)

XXIV

NC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER WIDTH	DELIV.	NPR
	VENTILATION UNIT	1UVCAM	WILLSHER + QUICK	/71	(3)
	10 VENTILATION GRILL	1 UG	WILLSHER + QUICK	/72	
	42 Supplies and Related C and Multi-Crate Suppl Supply Ventilation	Components/Acces ies, Blank Supply C	ssories — Single- Chassis, Control Panels,		
	421 Multi-Crate Supplies				
	POWER SUPPLY FLEXIBLE	CPU/1	GRENSON	/71	
	SYSTEM COMPRISING BASIC CRATE(FOR SUPPLY MODULES, INCLUDES REFERENCE, CONTROL AND 2004/0.14) SJPPLY MODULE (+6V/6A) (+12V/34) (+12V/34) (+24V/34) (-2(V/(74))	CFC CFP/6 CFM/6 CFP/12 CFP/12 CFP/24 CFP/24			
	DOWED SUDDIA SYSTEM (DATE)	C(BID 203	SADUYNO- SDAT	17.2	
	MODULE OPTIONS AS FOLLOWS) POWER SUPPLY MODULE 5 V 10 A 5 V 15 A 5 V 40 A 12 V 7 A 12 V 10 A 12 V 25 A 24 V 3 A 24 V 9 A 24 V 15 A	BIP 86 10 BIP 66 15 BIP 06 20 BIP 812 7 BIP 012 10 BIP 012 15 BIP 012 15 BIP 012 45 BIP 024 35 BIP 024 9 BIP 024 15	SAPHTMU- SKA I	112	
	SUPPLY CHASSIS 2KW (RAW SUPPLY FOR REGULATOR MODULES)	AL 8/10	SAPHYMO-SRAT	12/73	(2)
	FAN UNIT WIREC RACK 42 U POWER SUPPLY MODULE 5 V 5 A(REGULATOR) 5 V 10 A 6 V 25 A 12 V 2 A 12 V 5 A 24 V 3 A 24 V 5 A	VALB/10 BC 42 BPR 605 BPR 610 BPR 625 BPR 122 BPR 125 BPR 243 BPR 245			
	422 Single-Crate Supplies				
	COMPACT POWER SUPPLY JNIT (CRATE/PANEL Mount,+ and-6v/25a,+ and-24v/6a, 200/300W)	PS 0003	SEC-ELLIOTT	/71	
	CAMAC POWER UNIT (+6V/15A,-6V/3A,+24V/2A -24V/2A,200V/0.05A,117VAC)	CPU/4	GRENSON		
	CAMAC POWER SUPPLY	CPU/2	GRENSON	/71	
	SAME WITH SWITCHED METERING	CPUZSM		/71	
	POWER SUPPLY (+6V/204,-6V/5A, +AND-12 V/2A,+AND-24 V/3A)	CPU/5	SRENSON	/71	
	POWER SUPPLY (RACK MOJNTIN3,+5V/25A, -6V/15A,+AND-24V/5A,200V/0.1A)	CPU/6	GRENSON	/71	
	POWER SUPPLY (RACK MOJNTING,+5V/25A, -6V/15A,+AND-24V/5A,+AND-12V)	CPU/7	GRENSON	/71	
	POWER SUPPLY (+6V/20A,-6V/5A, +AND-24 V/5A,200 V/0.054)	9001	NUCL. ENTERPRISES	/71	
	POWER UNIT (+6 $V/15A$, -5 $V/3A$, + $AND-24V/2A$, 200 $V/0$, 054)	9022	NUCL. ENTERPRISES	/71	(2)
	POWER SUPPLY (+6V/15A, -6V/+A,+A+D-24V/2A	C Z C-10	POLON	06/73	
	POWER UNIT (+6V/20A, -6V/15A,+2+V/2A, -24V/2A,200V/0.14)	SP 426	OWER ELECTRONICS		
	POWER SUPPLY (+6V/25A, -6V/5A,	C 303	RDT	/71	
	POWER UNIT (FOR SUPPLY MODULES)		RO ASSOCIATES	/71	
	CAMAC SYSTEM POWER SUPPLY NODILE (+AND-12V/72W, CR + 12V/6A DE +24 J/3A)	C 301		/70	
	(6 V/10 A) (6 V/54 AND 24 V/14)	C 210		/70	
	(5 V/5A, +1 2 V/0.4A, -12 V/0.4A)	C 213		/70	
	(12V/4A) (24V/2A)	C 250 C 251		/71	

NC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR
	POWER SUPPLY UNIT (+6V/10A,-6V/2A,+AND-24V/1.5A)	P4 ALJ 13	SAPHYMO-SRAT		/71	
	(+6V/3A, -6V/1.5A, +AND-12V/1.5A, +AND-24V/1.5A)	P6 ALJ 13				
	(+6V/25A,-6V/10A,+AND-12V/3A, +AND-24V/3A,+200V/0.1A,MAX 200W)	P7 ALJ 13				
	SJPPLY (+AND-6V/26A,+AND-12V/5.5A,+AND- 24V/6.5A,200V/0.1A,117V AC, 2)0W MAX)	C 76455-A4	SIEMENS		/72	
	SUPPLY (SAME BUT WITHOUT 117V AC)	C 76455-A5			172	
	POWER SUPPLY AND BLOWER UNIT	1410 S	STND ENGINEERING	811		(5)
ć	POWER SUPPLY (+AND-6V/6A STARED AND +AND-24 V/2A SHARED, METERING OF V AND I)	825	STND ENGINEERING			

Blank Supply Chassis, Other Components/Accessories 427

	POWER SUPPLY CRATE (STANDARD) POWER SUPPLY CRATE (WIRED)	MCF/4/PPC MCF/PPC/WV	IMHOF-BEDCO	NA NA	/71 /71
	NETZTEILCHASSIS (EMPTY SUPPLY CHASSIS)	2.082.000.6	KNUERR		/70
	POWER SUPPLY CRATE (FOR SEPARATE SUPPLY)	CSAN	RDT		/71
	VOLTAGE MONITOR PANEL USING LEDS	MP 2	GEC-ELLIOTT	1	172
	MAINS SWITCH ASSEMBLY	MS 3	GEC-ELLIOTT	NA	/71
	POWER SUPPLY MONITOR PANEL (WITH MAINS Switch, Test points and led indication)	PSMP 1	GEC-ELLIOTT	NA	172
I	POWER INDICATOR	0704	NUCL. ENTERPRISES	NA	/70

43

I

Branch Cables, Connectors etc., Dataway Connectors, Boards etc., Blank Modules, Other Stnd Components

431 Branch Related (Cables, Connectors etc.)

	BRANCI HISHWAY CABLE	8102	BI RA SYSTEMS	02/73
	BRANCH HIGHWAY CABLE	BH001	EG+G	/71
	BRANCH HIGHWAY CABLE	CD 18067-27	EMIHUS	/70
	(1 METER LONG) (2 METERS LONG)	CD 18067/107 CD 18067/207		/71 /71
	BRANCH HIGHWAY CABLE ASSEMBLY (WITH CONNECTORS;27 CM LONG)	CC 66 POL PB-27	EMIHUS	/71
	(XX CH LONG, PVC JACKET)	CC 66 POL PB-XX		
	BRANCY HIGHWAY CABLE (WITH CONNECTORS, 27 CM LONG)	BHC 027	GEC-ELLIOTT	/72
	(SAME, 67 CH LONG)	BHC 067		/72
	(SAME, 107 CM LONG)	BHC 107		/72
	(OTHER LENGTHS TO SPECIAL ORDER)	BHC 207		/72
N	BRANCH HIGHWAY CABLE		j O E RGE R	
	BRANCH CABLE WITH CONVECTOR (1.5 FT TO 75 FT LONG)		JORWAY	/71
	BRANCH HIGHWAY CABLE (66 TWISTED PAIRS)	CL 90	SAIP/SCHLUMBERGER	/71
	BRANCH HISHWAY CABLE ASSEMBLY (COMPLETE	BHC 27	SEMRA-BENNEY	/72
	(SAME, XXX=LENGTH IN CM, 040,100 ETC)	BHC XXX	다섯 만큼 잘 물었다.	/72
	BRANCH HIGHWAY CABLES(COMPLETE WITH Connector, XXX = length in meters)	2000/S/0132/XXX	TEKCATA	/71 (4)
	BRANCH HISHWAY CONNECTOR	WSS0132S00BN000	EMIHUS	/70
	(FREE MEMBER, PIN MOULDING, PXX YVY SELECTS LACKSCEEV)	WSS0132PXX3NYYY		
	HOOD (FOR FREE MEMBER)	WAC 0132 H005		
	BRANCH HIGHWAY CABLE ONLY (Plain PVC Jacket)	66 POL PB	EMIHUS	/71
	EXTENDED BRANCH CABLE (LOW COST TELE- PHONE CABLE FOR LONG BRANCH RJNS)	EBC XXXX	SEC-ELLIOTT	/72
	BRANCH HIGHWAY CABLE (132-WAY)	LIY-172X2X0.088	LEONISCHE	172
Ν	BRANCH HISHWAY CABLE (TRUE 132-4AY WITH Metalised polyester Screen, PVC jacket)	LI2Y(ST)Y66X2X0.18	LEONISCHE	
	CABLE FOR BRANCH HIGHAAY (PVC JACKET)	132 PE 189	PRECICABLE BOUR	/71
	(MEPLAT 20MMX10.8MM, GAINE PVC NOIR)	132 PE 291		/72
	CABLE EXTENSION MODULE (JOINS TWO BRANCH HIG1WAY CABLES)	CD 18106	EMIHUS	/72

XXVI

No Deciditation - Ononi Dala	NC	DESIGNA	TION +	SHORT	DATA
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* ТҮРЕ

MANUFACTURER

(8)

07/73

N BRANCH HIGHWAY TO PDP-11 (COMPLETE WITH 5805/P/0132/XXX TEKDATA CONNECTORS, XXX= LENGTH IN METERS)

432 Dataway Related (Connectors, Boards, Assemblies)

C	DATAWAY MOTHERBOARD	(MULTILAYER PNB)	DM-1	STND ENGINEERING		
	DATAWAY ASSEMBLY (F	FILM WIRE PACKAGING		MB METALS	/71	(3)
	DATAWAY SOCKET (MC WITH 25 CONNECTORS)	DTHERBOARD COMPLETE	CIM	RDT	/70	
	DATAWAY MINI WRAPPI (Motherboard with 2	ING 25 DATANAY CONNECTORS)	J/ DW	SAPHYMO-SRAT	/71	
	CAMAC MULTILAYER (ATAWAY MOTIERBOARD)	CM-8-69	TECH AND TEL	/71	
	DATAWAY CONNECTOR,	EDJE TYPE II	163633	AMP-HOLL AND	/70	
	DATAWAY CONNECTOR, F	LOWSOLDER TERMINATION	R500014800000000	CARR FASTENER	/70	
	MINI WRAP TERMINATI Solder Slot Termina	(ON NATION	R500016800000000		/70 /70	
	DATAWAY CONNECTOR	(MINIWRAP)	EAA 043 D301	EMIHUS	/71	(2)
	CONNECTEUR, FUTS DRC (DATAWAY CONNECTOR, FUTS WRAPPING (WIRE)ITS STRAIGHT FINS) E WRAP PINS) DER DINS)	KF86 254 BED T KF86 254 BEY T	FRB CONNECTRON	/70	
	FUIS A SOUDER (SULL	JER PINSI	KF 86 254 BES 1			
C	SOLDER TAG, B SOLDE	ECTOR (* INSERT A FOR ER PIN, C MINI WRAP)	G03D 086P 28 * BL	ITT CANNON		(6)
	CAMAC-LEISTE (DATAWA	Y CONNECTOR, WIREWRAP)	4.000.000.0	KNUERR	/70	
C	DATAWAY FEMALE CONM	NECTOR, MINI-WRAP BOARD SOLDER NIRE SOLDER	2422 061 64334 2422 061 64354 2422 061 64314	PHILIPS	/71	(5) (5) (5)
C	DATAWAY MALE CONNEC Mounted 86-Way Conne	TOR (MATING THE CRATE NECTOR SOCKET)	2422 060 14314	PHILIPS	172	(5)
	CONNECTEUR 254 DOUE	BLE FACE	254 DF 43 AWV	S O C APE X	/70	
	IDATAMAT CONNECTORS	MOTHERBOARD SOLDER)	254 DF 43 AYV		/70	
		(WIRE SOLDER)	254 DF 43 AZV		/70	
	DATAWAY CONNECTOR	(MINI-WRAP) (WIRE-SOLDER) (FLOW SOLDER)	8606 86 21 15 000 8606 86 21 10 000 8606 86 21 14 000	SOURIAU	/71	
	DATAWAY CONNECTOR SOL DER LUGS .*=4	(*=2 FLOW SOLDER,*=3 MINIWRAP.AU PLATING)	C 288* CSP 221	UECL	/71	
	(FLOW SOLDER .NI + 4	U PLATING)	C 2885 CSP 221			
	(13 MINIWRAP CONTAC	PLATING)	C 2836 CSP 221			
	(*=7 MINIWRAP,*=8 S	SOLDER LUGS,	C 288* CSP 221			
	MOUNTING BRACKETS	FOR ABOVE	C 8523			

433 Module Related (Blank Modules, Patchboards etc.)

BLANK MODJLE KIT (SINGLE WIDT4) (DOU3LE WIDT4) NEW SIMPLIFIED (TRIPLE WIDT4) DESIGN (QUADRUPLE WIDTH)	BM 1 EM 2 BM 3 BM 4	GEC-ELLIOTT	1 2 3 4	01/73	
SINGLE CARD MOUNTING (IT (EMPTY MODULE) DOUBLE CARD MOUNTING (IT TRIPLE CARD MOUNTING (IT QUADRUPLE CARD MOUNTING KIT	BCK/5CAM/CM1 BCK/5CAM/CM2 BCK/5CAM/CM3 BCK/5CAM/CM4	INHOF- BE DCO	1 2 3 4	/71	
DOUBLE ENCLOSED BIN KIT (EMPTY MODULE) TRIPLE ENCLOSED BIN KIT QUADRUPLE ENCLOSED BIN KIT	BCK/5CAM/BM2 BCK/5CAM/BM3 BCK/5CAM/BM4	IMHOF-BEDCO	2 3 4	/71 /71 /71	
SINGLE CARD MOUNTING KIT (EMPLY MODULE,	CAM/N1/A	IMHOF-BEDCO	1	172	
(SAME WITH LONG SCREEN PLATE)	CAM/M1/B		1	172	
DOUBLE CARD MOUNTING (IT (EMPLY MODULE, SHORT SCREEN PLATE)	CAM/M2/A		2	01/73	
(SAME WITH LONG SCREEN PLATE)	CAM/M2/B		2	01/73	
TREBLE CARD MOUNTING <it (empty="" module,<br="">Short Screen plate)</it>	CAM/M3/A		3	01/73	
(SAME WITH LONG SCREEN PLATE)	CAM/N3/B		3	01/73	
QUADRUPLE CARD MOUNTING KIT (EMPTY Module with short screen plate)	CAM/M4/A		4	01/73	
(SAME WITH LONG SCREEN PLATE)	CAM/N4/B		4	01/73	
CAMAC 4 ARD WARE	CH-001	KINETIC SYSTEMS	1	/71	(4)
CAMAC-KASSETTE (ENPTY MODU_E,4IDTH 1/25) (WIDTH 2/25) (WIDTH 3/25) (WIDTH 4/25) (WIDTH 4/25) (HIDTH 5/25)	2,090.001.8 2.090.002.8 2.090.003.8 2.090.004.8 2.090.004.8 2.090.005.8	KNUERR	1 2 3 4 5	/70	(2)
(WLOTH 6/25)	2.090.006.8		6		

XXVII

NC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR
	MODULE KIT (EMPTY MODJLE,1 UNIT WIDTH) (EMPTY MODJLE,2 UNIT WIDTH)	9005-1 9005-2	NUCL. ENTERPRISES	1 2	/71 /71	
	CAMAC COMPATIBLE MODULE (EMPTY MODULE,1 JNIT WIDTH) (2 UNIT 41DTH) (3 JNIT WIDTH)	NSI 875 DM	NUCL. SPECIALTIES	1 2 3	/70	
	CAMAC MODILE (EMPTY MODULE HARDWARE, Spacers establish module width)	NSI 875 CM-100	NUCL. SPECIALTIES			(5)
N	CAMAC MODULE, SHIELDED (EMPTY, 1 WIDTH)	NSI-875-DM/SPH-1	NUCL. SPECIALTIES	1		
N	(SAME, *=2, 3, AND 4 FOR CORRESP WIDTH)	NSI-875-DM/SPH-*	NUCL. SPECIALTIES			
	TIROIR MODULAIRE (W=1/25) (W=2/25) (W=3/25) (H=4/25) (W=5/25) (**=06,08,10 AND 12 FOR CORRESP WIDTH)	9905-1-L 9905-2-L 9905-3-L 9905-4-L 9905-5-L 9905-**-L	JSL	1 2 3 4 5	/71 /71 /71 /71 /71 /71	
	TIROIR NODULAIRE A CARTES BASSULANTES	9905-TCB2	ĴSL	2	/71	
	(SAME, H=3/25)	9905-TCB3		3	/71	
	EMPTY MODULE, 1 UNIT (2 UNITS) (3 UNITS) (4 UNITS)		POLCN	1 2 3 4	/71	
	EMPTY MODULE 1 UNIT	CCA 1	RDT	1	/70	
	3 UNITS 4 UNITS	CCA 3 CCA 4		3 4		
	EMPTY MODULE SCREENED (1 WIDE, ADD TYPE SUFFIX A FOR SHCRT, B FOR LON3 SCREENS) (DITC, *=2,3,4 OR 6 FOR CORRESP WIDTH)	CM1 CM*	SEMRA-BENNEY	1	02/73	
	MODULE HARDWARE (EMPTY MODULE, W=1/25) (N=2/25) (W=3/25) (WIDTHS UP TO 8/25)		STND ENGINEERING	1 2 3		
	TIROIR MODULAIRE (EMPTY MODULE, 4=1/25) (4=2/25) (4=3/25) (4=4/25) (H=4/25) (H=5/25) (**=05,08,10 AND 12 FOR CORRESP HIDTH)	TM 50125 TM 50225 TM 50325 TM 50425 TM 50525 TM 50525 TM 5**25	T RANSRAC K	1 2 3 4 5	/70	
~	CAMAC MODULE (EMPTY,1/25 CARD MODULE) (2/25) (3/25) (4/25)	CAMCAS 1 CAMCAS 2 CAMCAS 3 CAMCAS 4	WILLSHER + QUICK	1 2 3 4	/71 /71	(2) (2) (2) (2)
	CAMAC MODULE (EMPTY,1/25 CARD MODULE) (2/25) (3/25) (4/25)	CAMCAS 1-G CAMCAS 2-G CAMCAS 3-G CAMCAS 4-G	WILLSHER + QUICK	1 2 3 4	/72 /72 /72 /72	
	CAMAC MODULE(EMPTY,1/25 SCREENED MODULE) (2/25) (3/25) (4/25)	CAMMOD 1-G CAMMOD 2-G CAMMOD 3-G CAMMOD 4-G	WILLSHER + QUICK	1 2 3 4	/72 /72 /72 /72	
	CAMAC MODJLE(EMPTY,2/25 SCREENED MODULE) (3/25) (4/25)	CAMMOD 2 CA1MOD 3 CAMMOD 4	WILLSHER + QUICK	2 3 4	/71	(2) (2) (2)
N	EMTY MODULE WITH HINGED CARDS (2/25) (3/25)	9905-CB2 9905-CB3	OSL/WILLSHER+QUICK	2 3	/73 /73	
N	EMPTY MODULE (1/25) (**= T2, T3, T4, T5, T6, T8, T10, AND T12 FOR CORRESPONDING WIDTH)	9905-5T1 9905-5**	D SL/WILL SHE R+QUICK	1	/73 /73	
	TIROIR MODULAIRE POUR COMMANCE	9905-TC-1) SL	1	/71	
	TIROIR MODULAIRE DE COMMANDE (SUPPLY CONTROL MODULE)	TCM 525	TRANSRACK	1	/70	
	MATRIX BOARD (DOUBLE SIDED, FOR PROTO- TYPE WIRING OF 14,16,24 AND 40 PIN DIL) DECODED MATRIX BOARD (FOR PROFOTYPE WIRING, 64 14-PIN SITES,A AND F DECODED)	EB5/1159 D20654	NUCL. ENTERPRISES			
N	BLANK CAMAC MODULE PRINTED CIRCJIT BOARD (GOLD PLATED BOTH SIDES, UNETCHED)	NSI-04071-PC	NUCL. SPECIALTIES	NA		
	CARTE CIRCUIT IMPRIME CAMAC (PRINTED CIRCUIT BOAR) FOR CAMAC MODULE)		TRANSRACK	NA	/70	
	MK-1 KLUGE MODULE (131 MIXED 14, 16, 24 PIN SOCKETS)	8301	BI RA SYSTEMS	2	01/73	
N	MK-5 KLUGE MODULE (HAS 70 14 >IN, 13 AND 2 24 PIN WIRE WRA> SOC(ETS)	8305		2		
	CAMAC-UNIVERSALKARTE (PRINTED CARD MODU- LE WITH 28 14-PIN + 28 16-PIN SOCKETS)	DO 200-2900	JORNIER	2	/71	

XXVIII

NC	DESIGNATION + SHORT DATA	ТҮРЕ	MANUFACTURER	WIDTH	DELIV.	NPR
	CAMAC PROTOTYPE ASSEMBLY BOARDS	MX B1/MX B2	GEC-ELLIOTT	NA	/71	
	(MX B1 HAS 68 SITES, MX B2 HAS 80 SITES) (MX B3 HAS 68 SITES,MX B4 HAS 80 SITES, MX B3/MX B4 INCLUDE 5V CIRCUIT)	MX B3/MX B4		NA	/71	
	GENERAL PURPOSE IC PATCHBOARD (MAX 33 14/16-PIN AND 5 24-PIN DIP,WIRE WRAP)	CAMAC CG 164	SSPK	NA	/70	(2)
	PRINTED CIRCUIT TEST 30ARD	10	JORWAY	NA	/71	
C	KLUGE CARD (FOR CREATING YOUR DWN CAMAC	2000-36	KINETIC SYSTEMS	1	/71	(4)
N	KLUGE CARD	2000		1	/73	
	EXPERIMENTIERPLATTE (PRINTED CIRCUIT BOAR))	4.000.002.0	KNUERR	NA	/70	
	MODULE PRINTED CIRCUIT BOARDS(TAKE 2+,16	CBP 1	RDT	NA	/72	
	(SAME, WITH MINI-WRAP TO JV AND +5V)	CBP 2		NA	/72	
	BLANK MODJLE (COMPLETE WITH PRINTED BOARD	BM 2020/1U	SEN	1	/70	
	(SAME,2U WIDTH)	BM 2020/2U		2	/70	
	EXPERIMENT PLATE	C 72468-A453-A1	SIEMENS	0		
	437 Other Recommended or St	tandard Components/	Access.			
	NIM ADA PTOR	7009-2	NUCL. ENTERPRISES	NA	/70	
	NIM-CAMAC ADAPTOR	CAN	RDT	NA	/71	
	NI M/ CAM AC ADAPT OR	ANC 10	SAIP/SCHLUMBERGER		/72	
	CAMAC NIM ADAPTOR	CNA 2033	SEN	2	/71	
	LAM GRADER CABLE (200M, WITH CONNECTORS) (400M, WITH CONNECTORS)	LGC 20 LGC 40	GEC-ELLIOTT		/72 /72	
0	LAM GRADER CABLE		JOERGER			
N	52 WAY CANNON 20052S HARNESSES LAM GRADER CABLE, XXX= LENGTH IN METERS)	5809/S052/XXX	TEKDATA		08/73	
	52-WAY DOJBLE DENSITY CONNECTOR (FIXE) Member with pins.lam grader connector)	2 DB 52 P	ITT CANNON		/70	
	COAXIAL CONNECTOR	RA 00 C50	LEMO		/70	(4)

INDEX OF MANUFACTURERS

Imhof-Bedco Ltd.

AEG-Telefunken Elisabethenstrasse 3, Postfach 830 D-7900 Ulm, Germany AMP-Holland N.V. Papierstraat 2-4, Postbus 288 S-Hertogenbosch, Netherlands Benney-See Semra-Benney **BF** Vertrieb GmbH Bergwaldstrasse 30, Postfach 76 D-7500 Karlsruhe 41, Germany Berthold/Frieseke - See BF Vertrieb BI RA Systems, Inc. 9617 Acoma Road, S.E. Albuquerque, N. Mex. 87123, USA Borer Electronics AG Postfach 4500 CH-4500 Solothurn 2, Switzerland C Cannon Electric GmbH Bureau Schweitz Brandschenkenstrasse 178 CH-802' Zurich, Switzerland Carr Fastener Co. Ltd. Cambridge House, Nottingham Road Stapleford, Nottinghamshire, England Digital Equipment Corporation (DEC) 146 Main Street Maynard, Mass. 01754, USA Digital Equipment Corporation SA 81, Route de l'Air CH-122' Carouge-Genève, Switzerl. Dornier AG Vertrieb Elektronik, Abt. VC 20 Postfach 317 D-799 Friedrichshafen, Germany Duckert - See Juergen Duckert EG+G Inc. Nuclear Instrumentation Division 500 Midland Road Oak Ridge, Tenn. 37830, USA Eisenmann Elektronische Geräte Blumenstrasse 11 D-7500 Karlsruhe, Germany **EKCO – See Nuclear Enterprises** Elliott - See GEC-Elliott Emihus Microcomponents Ltd. Clive House 12-18 Queens Road Waybridge, Surrey, England Emihus Microcomponents Ltd. Belgian Branch Res. Hera—Appt. No. 64 Passage International, 29 B-1000 Bruxelles, Belgium FRB Connectron 3-5, Rue des Tilleuls F-92600 Asnières, France Frieseke - See BF Vertrieb GEC-Elliott Process Automation Ltd. Camac Group, New Parks Leicester LE3 1UF, England Grenson Electronics Ltd. Long March Industrial Estate High March Road Daventry, Northants NN11 4HQ, England GSPK (Electronics) Ltd. Hookstone Park Harrogate, Yorks HG2 7BU, England Hans Knuerr KG Ampfingstrasse 27 D-8000 München 8, Germany

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DERANDOMIZING CAMAC INPUT MODULE

by

R. Klesse

Institut Max von Laue — Paul Langevin, Grenoble, France Received 22nd January 1973

SUMMARY This CAMAC module is a last-in first-out buffer that can accept randomly-timed data words and transfer them via the Dataway to a computer. It is used when the transfer rate to the computer is not sufficient for the peak data rate, but can handle the mean rate.

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The module described in this paper accepts and buffers a random or bunched sequence of data from an external source and transfers them via the CAMAC Dataway into the computer. The buffering of the data is necessary if the transfer rate to the computer is not sufficient for resolving successive events. The average frequency of occurrence of the



Fig. 1 Block Diagram of Derandomizing Input Module

data must not exceed the transfer rate of the computer channel. The module has been used for neutron time-of-flight measurements. A schematic design of the module is shown in Fig. 1.

The data enter the double width module by a 52-pin Cannon-connector. The data-input gate is controlled by:

- a) Computer command: Enable-Disable;
- b) CAMAC Inhibit signal 1;
- c) External gate-signal (inhibition);
- d) External 'start-stop' pulses.

The transfer into the module may be strobed or 'handshake' controlled. The capacity of the 'Last in first out stack' memory is 16 words of 24 bits. The information can be read out either by a read commend via the Dataway or by a handshake-controlled transfer via a second 52-pin Cannon-connector at the frontpanel. During the read operation via the Dataway, the information is also available at the front panel output-connector (for test equipment such as a multichannel analyser).

A LAM is generated if there are one or more words in the buffer. By a slight modification it is possible to set the LAM when a larger number of words (8 or 16 for example) are buffered. In this way Qscan read-out operations can be performed.

Several modules of this type can be connected together for parallel or serial operation.

In the parallel operation mode for multi-parametric measurements the LAM of several modules can be gated by a rear panel input to provide the desired coincidence condition.

In the serial operation mode a buffer overflow signal can be utilized to start a following Derandomizing CAMAC Input Module which is connected to the same source. This can be useful in the case of pulsed data-sources or in the case of intermittent data transfer to the computer.

The overflow signal is maintained to indicate 'no access possible to the module'. This signal can be used to measure the dead-time of the data-transmission system.

NEWS

ANNOUNCEMENTS BY CAMAC MANUFACTURERS

STANDARD ENGINEERING CORPORATION, Fremont, California, USA, is now the sole manufacturer of all CAMAC products formerly designed and manufactured by Techcal Electronics Services,

Vancouver, B.C., Canada. This allows Standard

Engineering to deliver a complete line of CAMAC products including, crates, power supplies, hardware, instrumentation and small systems complete with CPU.

NEWS

CAMAC AT THE IMEKO CONGRESS

The sixth Congress of the Internationale Meßtechnische Konföderation (IMEKO) was held from 17th to 23rd June 1973 in Dresden, German Democratic Republic. Major topics of the very successful and excellently organized conference were theory, testing, calibration and application of measuring systems and industrial sensors, as well as on-line measurements in processes. A special section was dedicated to "Means and Methods for Instrument-Computer Interfaces". The survey paper of this section was given by T.I. Williams, Purdue University, Indiana, dealing with the problems of on-line computer applications in industrial processes. The importance of standardized hardware and software for industrial computer systems was emphasized in order "to avoid wastage of the intellectual input to systems development". The CAMAC instrumentation system was given as an excellent example of a working standard used internationally. The activity of the Purdue Workshop on standardization of industrial computer languages was described in some detail.

A round table discussion on "Problems and Techniques in data acquisition systems" again drew the attention of many people attending the conference to the CAMAC system. This was backed up by a report from E. Kingham of the Central Electricity Research Laboratories (CERL), Leatherhead, UK on his positive experience with CAMAC instrumentation in data logging and process control.

As one of the section papers, H. Klessmann from the Hahn-Meitner-Institut Berlin presented an introduction to the CAMAC system and pointed out the current work of the ESONE Committee in cooperation with the United States AEC NIM Committee on the Serial Highway and the IML programming language.

The major attendance at this international conference was from the German Democratic Republic and eastern countries. They showed a great interest in CAMAC, and arrangements were made to deal with many requests for information. From private discussions it was apparent that CAMAC instrumentation is already used or about to be used in some universities and research installations in these countries, including applications in nonnuclear areas. However, for those interested in industrial applications of CAMAC there is a lack of convincing working examples and references-the activity of the Aluminium Corporation of America (ALCOA) was received with great interest. Furthermore the lack of information on software support of CAMAC systems still seems to be a major problem.

BULLETIN ANNOUNCEMENTS

PREPARATION OF CONTRIBUTIONS

Authors are requested to follow these instructions when submitting contributions for the Bulletin. Failure to do so may result in contributions being returned to the author, for re-submission in a modified form, and may delay publication.

- 1. English is the preferred language. Contributions in other languages are equally welcome but only the summary will be translated.
- 2. Authors should state their name, business affiliation and postal address on a separate sheet if not included in the contribution.
- 3. The style, layout, use of bibliographic references and so on should follow as closely as possible the appropriate contents of this Bulletin.
- 4. For contributions to the New Products Section, each product description should be on a separate sheet and ANY ONE DESCRIPTION MUST NOT EXCEED 200 WORDS OR 1/4 BULLETIN-PAGE, INCLUDING ILLUSTRATIONS.
- 5. For contributed articles, 1,200-1,600 words are preferred. THEY MUST NOT EXCEED 1,600 WORDS OR 2 BULLETIN-PAGES, INCLUDING ILLUSTRA-TIONS. They should be accompanied by a summary (abstract) suitable for translation into other languages. The summary must not exceed 50 words.
- 6. Contributions that exceed the above maxima will not normally be considered for publication.

- 7. Manuscripts should be typed on alternate lines on only one side of the page.
- 8. Drawings and photographs should be only included if they are essential to the text. Original ink (not pencil) drawings and semimatt prints of photographs, at least twice the final size, should be submitted. The author's name and figure number should be written, lightly in pencil on the back of each illustration. A list of all figure numbers and captions should be included on a separate sheet, even if these are given in the text or on the illustrations themselves.
- 9. Drawings must be such that the line thickness used for alpha-numeric characters and lines should still make these legible when the drawings are reduced, typically, to singlecolumn width.
- 10. When computer print-outs are used to illustrate the text, a good-quality original must be sent to avoid the need for typesetting.
- 11. Articles which are shortened, or adapted, from original papers should identify the original in the references.
- 12. AUTHORS MUST SUBMIT CONTRIBUTIONS BE-FORE THE CLOSING DATES announced elsewhere in this Bulletin.
- 13. Reprints can be ordered at any time, but authors who are likely to require reprints in bulk should request these when submitting a contribution.

SOFTWARE

SOME ASPECTS OF A COMPILER WRITING SYSTEM AND THE IMPLEMENTATION OF THE CAMAC LANGUAGE

by

K. H. Degenhardt, U. Marx-Rehbein and W. Woletz

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Received 27th June 1973

SUMMARY Recent work at the Hahn-Meitner-Institut to automate the writing of compilers for programming languages is presented. The first application of the Compiler Writing System (CWS) will be the implementation of a compiler for the CAMAC language.

INTRODUCTION

The purpose of a compiler writing system (CWS) is to simplify the implementation of compilers. The main components of a CWS are:

- a language for describing the syntax of a programming language;
- a semantic language, i.e. a language in which semantic routines are written.

The term compiler-compiler (CC) is often used because a CWS compiles other compilers. A CWS¹ works as follows:





Suppose a compiler for some language L, e.g. the CAMAC language², is required. The input to the CWS consists of the formal syntax of L written in a metalanguage and a set of semantic routines (semantic metalanguage). The CWS compiles the syntax and the semantics of L into two tables. The syntax table is used by a standard parsing routine to perform the recognition and parsing of programs written in L. The information contained in the semantic table describes the meaning of statements in L. Semantic routines are associated with syntactic constructs. These routines are executed when syntactic constructs are recognized. Generally a compiler for some language L generated as described above will be less efficient in memory and compile time than a compiler written in assembly language. The reasons for using a CWS for the construction of compilers are similar to those for using high-level languages for programming.

AUTOMATICALLY CONSTRUCTED RECOGNIZER

Weak precedence

Generally the notation (metalanguage) used for describing the syntax of programming languages is the Backus-Naur-Form (BNF) or some extension of it. The syntax of a language L can be defined by a set of rules (productions) written in BNF. The symbols (reserved words, delimiters, identifiers, etc.) used in these rules form the alphabet of L.

There are three types of precedence relations $<\cdot, \cdot>$ and \pm between the symbols of a syntax. A language L is a precedence language if at most one relation holds between any pair of symbols and if no two productions of the syntax have identical right parts. A precedence recognizer uses these relations to decide whether to scan a new symbol or to do a reduction and, if so, which reduction. Practically, most programming languages are not precedence languages. Problems arise because very often more than one relation holds between two symbols. Identical right sides are also familiar in programming languages. These conflicts are due to the fact that a precedence parser uses very little context in making decisions (it only uses two adjacent symbols). In order to decrease the number of conflicts, the concept of precedence has been generalized to that of weak precedence⁴. There are only two weak precedence relations, $\leq \cdot$ and $\cdot >$; and the decision which reduction should be performed depends on pattern matching. The concept of weak precedence does not solve all problems, because most programming languages are not weak precedence languages.

Production language

The weak precedence relations can be derived automatically from a weak precedence syntax. Usually the relations are stored in matrix form or in some kind of list. A weak precedence parser using a matrix is expensive in core memory, if it uses a list it is expensive in time. Ichbiah and Morse⁴ have developed an algorithm for automatic translation from a weak precedence matrix to an 'almost optimal' program written in production language (PL)^{5,6}. By this process, which is performed at metacompiletime, the information contained in the matrix could be stored in a very compact manner. The production language is a metalanguage for writing recognizers. A recognizer written in PL consists of a set of productions of the form

L1
$$S_3S_2S_1 \to S_2'S_1' *L2$$
 (1).

The productions specify actions to be performed on symbols of a stack. Production (1) reads as fol-

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lows: compare S_1 , S_2 and S_3 with the top of the stack. If there is a match, the matched symbols S_1 , S_2 , S_3 in the stack are replaced by the symbols S_1' , S_2' . If they do not match the next production in the PLprogram is tried. '*' indicates that the next input symbol is scanned and pushed onto the stack. After successful execution of (1) the production labelled L2 is executed. In practice the PL-program is transformed into tables on which a standard parser acts.

The syntax part of a metacompiler

As already mentioned, most programming languages (e.g. ALGOL 60, CAMAC language) are not weak precedence languages because the weak precedence concept uses very little context. The symbols and their relations are used without regard to the environment of the symbols. We have developed a method of changing a given syntax in order to solve these problems. An important feature of this method is that it does not change the structure of a syntax. The syntax part of our CWS[#] is a program written in FORTRAN and IBM 360-Assembly. It accepts a syntax written in BNF, transforms it, constructs the weak precedence matrix and translates the matrix into a PL-program which is finally transformed into tables. The standard parser which acts on these tables is rather simple and can easily be written in some language convenient for the available computer.

The syntax tables generated for the CAMAC language need 8K bytes (one pass compilation without segmentation). The tables are generated in 5 min on a SIEMENS 4004-55. The program has been successfully tested with other languages, e.g. ALGOL 60.

SEMANTICS

As mentioned, one of the components of a compiler-compiler is a semantic metalanguage which permits the description of the source language (e.g. CAMAC language).

Each PL-Statement in the syntax language may include a command which is a jump to a semantic statement. This semantic statement will be executed each time that production (PL statement) is matched⁷.

The actions to be performed by a semantic statement are the following:

- Checking the semantic correctness (e.g. whether an identifier is a CAMAC c-name or not);
- Generating code (In the case of the CAMAC language IML-statements (Macros) are generated);
- Changing the state of the translator (e.g. if a CAMAC equivalence statement is matched).

The semantic part of the CWS is a program written in FORTRAN and IBM 360-Assembly. It accepts semantics written in the metalanguage and translates them into semantic routines.

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NEWS

CAMAC IN WARSAW

Dr. Roman Trechcinski reports that an International Symposium and Exhibition on Nuclear Electronics was held in Warsaw from 5th-10th April 1973. Nine papers dealing with CAMAC systems were presented and four of them were concerned with the Vector System, which is similar to CAMAC and developed in the USSR.

CAMAC systems were demonstrated by laboratories in Czechoslakia, Hungary, Roumania and Poland and two complete measuring systems working with computers type K202 (Poland) and 1001-TPAI (Hungary) were also exhibited. Laboratories from the USSR demonstrated instruments that were compatible with the Vector System.

Both the papers and the demonstrations aroused a great deal of interest from those attending the symposium.

PROPOSAL FOR A POWER FAILURE SIGNAL FROM THE CAMAC POWER SUPPLY TO THE CONTROL STATION

IDEAS AND TECHNIQUES

by

C. Eck*, F. Iselin and J.-P. Vanuxem

NP Division, CERN, Geneva, Switzerland * Institut für Physik, Universität Mainz, Germany

Received 14th May 1973

SUMMARY A Power Failure feature is recommended to provide the controller with an early warning signal that the mains supply has failed. This allows action to be taken to save the contents of registers in the CAMAC crate while the d.c. supply voltages are still within tolerances.

INTRODUCTION

1

In most CAMAC systems data integrity is of prime importance, and therefore it should be possible to save the contents of all CAMAC registers in case of a power loss in the crate. This proposal describes the use of a single additional signal, the PF signal, to initiate this saving procedure. In CAMAC systems with dedicated crate controllers it is also possible to restore the contents of these registers automatically when power comes up again.

DEFINITION OF THE PF SIGNAL

The PF signal is an anticipatory TTL-level signal derived, for example, from failure of the mains input to the power supply. After PF has been asserted (low level) there must be at least 5 ms before any output voltage on the power supply lines (measured on the Dataway) goes below its tolerance range, as defined in table X of EUR 4100e (1972), under full load conditions. This figure of 5 ms is small enough to deal with most existing CAMAC power supplies, which could then easily be modified to provide the PF signal, and large enough to guarantee that, for most CAMAC systems, the controller (or computer) has time to save all relevant data contained in the CAMAC crate when a power failure occurs.

When the voltages on all output power supply lines come up again within their tolerances, the PF signal is negated. Care should be taken to avoid 'hunting' problems.



It is proposed that the PF line, coming from the power supply block of the crate, goes to pin L24 of the control station connector.

Currents and voltages on this line must be those of a normal L-line, see tables V and VII of EUR 4100, even if this particular L is transferred without a LAM status register.

TRANSFER OF THE PF INFORMATION TO THE SYSTEM CONTROLLER

Depending on whether the crate controller is a Crate Controller Type A or whether it is dedicated to a specific computer, and in this latter case depending also on the type of computer used, different ways of transmitting the PF information are suggested.

Crate Controller Type A The PF contact (L24 at the control station) could simply be wired to any GL-line inside the crate controller, but preferably to GL24 (indicating that the PF-signal has top priority). In Crate Controllers Type A-1, conforming to Appendix 1 of EUR 4600e, a pull-up is provided on the GL24 line, but an internal connection from L24 to GL24 is not specified. No automatic power-up procedure is possible.

Dedicated crate controller (specific to a defined computer) The PF signal could generate an interrupt to the computer in a way similar to CCA. In some applications where the computer has a special power failure line (as in the case of the PDP-11), there can be a simple connection of L24 to this line, and the computer will trap to a power failure subroutine as soon as the signal is asserted. In such applications, there can also be circuitry so that negating the PF signal starts an automatic power-up procedure to restore the values which were in the CAMAC registers before the power failure occurred.

CONCLUSION

The PF signal offers much better system reliability to CAMAC users. It is felt that the effort to make the PF line available is small compared with the advantages that it can provide.

IDEAS AND TECHNIQUES

MODULE DESCRIPTOR

(2)

by O. Ph. Nicolaysen CERN, NP Division, Electronics Development II, Geneva, Switzerland

Received March 1973, revised form July 1973

SUMMARY The revised CAMAC specification recommends an address for accessing a module descriptor word, but does not define the contents of the descriptor. This paper reviews the sources of information about the characteristics of a CAMAC module, and proposes a 16-bit descriptor word.

SOME GENERAL REFLECTIONS

The Module Descriptor introduced by CERN (named RMC = Read Module Characteristic), has assigned bit-fields for the CERN type number of the module and the number of registers. The RMC is addressed by $F(6) \cdot A(x)$, and is included on all commercially produced modules based on CERN designs. It has not otherwise gained widespread use, possibly because it does not provide information that is sufficiently universal or directly useful for software interpretation.

When the new command $N \cdot F(1) \cdot A(15)$ was assigned to the Module Descriptor in EUR 4100e (1972) very few manufacturers started to use it. No guide on its usage was given, no standard significance was defined, and there was always the possibility of later changes. To include the Module Descriptor costs money; leaving it out means at least lower module prices or better economy for manufacturers, arguments not to be neglected.

MODULE CHARACTERISTICS IN SYSTEM APPLICATIONS

The Module Descriptor should provide information about characteristics pertinent to system operation (Dataway signals, commands, data formats, etc.). Information about characteristics related to external connections to the module are less important in this context (input or output levels, accuracy, speed of operation, connectors used, etc.). Usually in setting up a system one needs anyhow to know interconnection characteristics at the time of selecting the modules.

X and Q: Sources of information about Module Characteristics

Much information about a module can be obtained simply by addressing the module with all combinations of F and A and watching the Q-response. Modules designed and/or produced after August 1972 should also give a signal on the X line for all commands accepted.

This provides the following information immediately

• The number of registers for each function F(y)[addressed by $A(x)_{x=0} \rightarrow F(y)_{y=0}$.]

- If LAM is used, and possibly how many L sources [F(1) · A(12 to 14), F(8), F(10), F(11), etc.].
- If non-standard functions are used. Possibly one may also know if reserved functions are used ille-gally (if X-response is generated for these).

Early modules in which A and F are not fully decoded do not give this information. They can be recognised because they do not generate X. However, if such modules are modified to generate the X signal when the station is addressed (X = N) as indicated in EUR 4100e (1972), the described method no longer works. Imprecise working of the X-response causes erroneous information on module characteristics.

Information not obtained through Q and X

Information which cannot always be obtained with certainty through the above method are:

- Is Q used and in which mode?
- How many LAM sources, and what generates LAM?
- Are B, I, C, Z, P1 to P5 used and how?
- How many registers? Normally one would know this from the X-response, but not with certainty; the same register may both be overwritten by F(16) and read out by F(0).
- How many bits per register?
- Module width.
- What type of module? Binary, BCD, 2's complement register content? Range, Resolution, Accuracy? Frequency of operation? I/O signal levels and Polarity? Connector used? Any manual controls?

Some of this information about the module can be provided by the Module Descriptor, but certainly not all, not even coded. So we have to select what to have in and what to leave out.

THE MODULE DESCRIPTOR

A Module Descriptor which includes the 4-decimal classification code described in Ref. 1 provides, together with the Q- and X-response, most of the characteristics of a module which are related to the Dataway, and a few other as well.

Most new mini-computers have 16-bit words, and many 12-bit computers are in use. So we settle for a 16-bit Module Descriptor with the 'essentials' in the 12 least-significant bits.



This leaves 4 bits for other purposes. The Q-response modes provided by the module are given by bits 12 to 14, where

 $Q_1 = address scan mode;$ $Q_2 = repeat mode;$ $Q_3 = stop mode.$

Bit 15 (and bit 11) should be reserved for other uses. With this, it is possible to discover all Dataway related characteristics except those concerning use of



ISOLATOR STAGE FOR THE CAMAC BRANCH HIGHWAY SYSTEM

by W. Tebra

FOM-Instituut voor Atoom- en Molecuulfysica, Amsterdam, The Netherlands Received 5th June 1973

SUMMARY Interference from spurious common-mode signals and high-tension breakdowns in experiments can cause serious trouble in CAMAC systems. A light-coupled isolator stage in the branch highway is then helpful. Such a highway isolator has been used since January 1972, and drives several crates located at up to 100 m from the computer.

INTRODUCTION

In our laboratory on-line data acquisition and control of atomic collision experiments is performed with a PDP-15 computer and CA-15 CAMAC interface. The experiments are scattered throughout the laboratory, at distances up to about 100 m from the computer.

Breakdowns in the high-tension equipment of the experiments are a regular phenomenon. They not only interfere with the data but also sometimes destroy the integrated circuits. To protect the computer and its peripherals, and to decrease the common mode interference, we interposed a light-coupled isolator stage between the highway bus of the CA-15 and the cable (Fig. 1). This considerably improves the low frequency common mode rejection and the protection against damage proved to be good.



Fig. 1 Lay-out of the CAMAC Connection with Isolator Stage.

An ac-voltage of 500 V rms (50 Hz) between the highway cable and interface now introduces no spu-

rious signals. Direct discharges of 2 Joule by 3kV from a capacitor introduce an interference of 1.5V in the interface. Discharges of 10 Joule by 10kV are not harmful to the cricuits but they cause erroneous signals.

THE ISOLATOR STAGE

The isolator stage itself can withstand 2500 V, but we limited the possible maximum voltage over the stage to about 300 V by means of a non-linear resistor.

For the highway signals we used 91 isolators of Monsanto type MCD2. We chose the MCD2 because of its fast response. It is possible to transfer signals at up to 10MHz through the isolator stage. There are 48 isolators for the bidirectional BRW lines, 29 for the computer-crate direction, i.e. BTA, BG, BCR, BN, BA, BF, BZ and BX lines, and 14 for the other direction, i.e. the BD, BTB, BQ and BX lines. After the light-coupled isolator we use symmetrical line drivers and receivers. These units present normal CAMAC ports to the isolator and crate controller. Because the signals pass through several gates the delay for them is not necessarily the same. We have observed a time difference of about 50 ns with selected photocouplers.

ACKNOWLEDGEMENTS

This work is part of the research program of the Stichting voor Fundamenteel Onderzoek der Materie (Foundation for Fundamental Research on Matter) and was made possible by financial support from the Nederlandse Organisatie voor Zuiver-Wetenschappelijk Onderzoek (Netherlands Organization for the Advancement of Pure Research).

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I, C, P1 and P2 buslines, P3 to P5 patch contacts, and perhaps some uncertainties in the number of LAM sources if a LAM Request Register is used.

REFERENCE

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ACTIVITIES OF THE CAMAC WORKING GROUPS

The ESONE Committee in Europe and the USAEC NIM Committee in America have both authorised different working groups to investigate specific aspects of CAMAC. The European and American working parties are performing their activities in close collaboration.

ESONE-CAMAC WORKING GROUPS

Dataway Working Group

Chairman: H. Klessmann, HMI Berlin

The attention of the ESONE Dataway Working Group has been concentrated on the CAMAC Serial Highway, a means for interconnection of up to 62 CAMAC crates via serial transmission lines. It allows bit- or byte-serial data transfers for applications where long distance transmission or simple interconnection between CAMAC crates is required. (See R. C. M. Barnes 'The CAMAC Serial Highway'. this issue, p. 5.) This system will find wide-spread interest, especially in process control and other nonnuclear applications where CAMAC is now increasingly being employed.

The proposal from the NIM-CAMAC Dataway Working Group (NDWG) on the Serial Highway was again reviewed in detail by the ESONE Dataway Working Group (EDWG) at its meeting in Rome in May 1973 (with representatives from NDWG, K. Dawson, University of Alberta and L. Paffrath, Kitt Peak Nat. Observatory) and in Copenhagen in June 1973 (with representative from NDWG, R. Martin, Nat. Acc. Lab.). Due to this good communication and excellent co-operation between ESONE and NIM, general agreement was achieved on all main features of the Serial Highway and on a typical Serial Crate Controller, at the recent NDWG meeting in Vancouver in July 1973, with H. Klessmann, HMI Berlin and A. Peatfield, Daresbury Nuclear Physics Lab., as representatives from ESONE.

As a result, a detailed description of the basic mechanisms of the Serial Highway is now being prepared which, after final review by EDWG in October, will be available in November and presented in December to the ESONE Annual General Assembly in Luxembourg as a joint effort by the ESONE and NIM Committees. From this preliminary description the ESONE and NIM Dataway Working Groups will prepare a formal specification of the Serial Highway, having the same technical content except where it is necessary to correct for errors and ommissions. Therefore it is essential that persons implementing the description should be in close touch with the EDWG and NDWG to avoid possible incompatibilities with other implementations and with the final specifications, due to any ambiguities or ommissions in the preliminary description.

Another important current and future activity of EDWG is to prepare general guidelines and recommendations for methods of block transfer in CA-MAC systems. Decisions on this topic may influence the recommendations for future use of the Reserved Branch Highway lines. These lines are about to be released for private use, with certain restrictions on signal levels, etc. The design of Crate Controller Type A-1 will not be modified by this in any way.

The EDWG will continue to give interpretations of the CAMAC Specifications EUR 4100e (1972) and EUR 4600e (1972) to assist designers in the implementation of compatible CAMAC modules and systems. All these activities are carried through in close co-operation with other Working Groups, especially the ESONE Software and NIM Dataway Working Groups. Currently there are 24 members from many European research installations actively engaged on this work. The Working Groups have set up two Sub-Groups for investigating two specific problems, the Serial Highway and methods of Block Transfer. Any problems related to current activities or to the CAMAC Specifications can be addressed to the ESONE Dataway Working Group by writing to the Chairman or the Joint Secretaries or the corresponding ESONE Committee Member.

Software Working Group

Chairman: I.N. Hooton, Harwell

The Software Working Group is continuing its development of the intermediate language IML in association with the NIM-CAMAC Software Working Group. The fundamental semantic definitions are now relatively stable and a draft of a syntax for use with generally available Macro-Assemblers is being prepared. This work is being well supported by individual members testing the proposals in practical implementations.

The Group continues to monitor the software implications of the Serial Highway proposals from the Dataway Working Group. It is also taking an active part in the consideration of standardised block transfers mechanisms for both serial and parallel highway systems.

Analogue Signals Working Group

Chairman: T. Friese, HMI Berlin

During the ESONE Analogue Signals Working Group Session at Geel (July 1973), the previous proposals for a combined specification were revised and extended to give clear proposed specifications for bipolar pulse signals and bipolar steady signals which have both been considered to some extent before. Therefore the introduction of the two new classes 1 NPB and 5 NPB is not new in principle. The Analogue Signals Working Group hopes these will be readily agreed by the NIM-Analogue Signals Working Group also.

The table gives a summary on the most important characteristics for the four analogue signal classes for use between units which conform to the CA-MAC specification EUR 4100 (1972). In the case of bipolar signals, where only one polarity conveys the significant amplitude information, this polarity will be negative for class 1 NPB and positive for class 5 NPB. To avoid expensive signal distributors for IV signals, a high impedance feedthrough (bridging) input is now proposed so that one 'Class 1' output can drive up to three or more inputs connected in serial.

Character-	Class	Output	Inp	out
istics			Terminated	Unterminated
Working Voltage Range	5PB 5NPB	0V to $+5V-5V$ to $+5V$	0 V to +2.5 V −2.5 V to +2.5 V	0 V to $+5$ V -5 V to $+5$ V
	1NB	0 V to $-1 Vacross a 50 \Omega load$	0V to -1V	
	1NPB	-1V to $+1Vacross a50\Omega load$	-1V to $+1V$	
Impedance	5PB 5NPB	50Ω±5%	50Ω±5%	$>$ 5000 Ω
	1NB 1NPB	50 $\Omega\pm$ 10%†	$50\Omega \pm 5\%^{\Delta}$	>5000Ω*
Absolute Maximum	5PB 5NPB	-7.5V to +7.5V	-4V to $+4V$	-15V to +15V
Range	1NB 1NPB	-3V to $+3V$	-4V to $+4V$	-15V to +15V*

AMPLITUDE ANALOGUE SIGNALS

[†] The output impedance of a current or voltage source may also be used.

* For feedthrough (bridging) inputs only.

 $\Delta \quad 50\Omega \pm 10\% \text{ for } 1 \text{ ns} \leq t_r \leq 3 \text{ ns.}$

Information Working Group

Chairman: H. Meyer, CBNM, J.R.C., Euratom, Geel

In July 1973 the number of subscribed copies of the *CAMAC Bulletin* exceeded the '1000' mark. New subscribers are, to an increasing extent, CAMAC users in other than nuclear application-areas. This trend is also supported by the facts that a significant number of copies of the Bulletin are distributed as a result of enquiries from new potential users of CA-MAC and that more papers on new applications are becoming available for publication.

A CAMAC Bibliography, available as a Supplement of this Bulletin issue presents an overall review of CAMAC developments and applications (see p. 30).

A classification of software for CAMAC applications is under consideration and it is expected that the Bulletin will contain a Software Product Guide sometime in 1974.

NIM-CAMAC WORKING GROUPS

General

L. Costrell, Chairman NIM Committee, NBS, Washington DC

The NIM-CAMAC Working Groups correspond closely to the ESONE Working Groups and the corresponding groups collaborate effectively. All four NIM-CAMAC Working Groups met July 10-13 at the TRIUMF accelerator laboratory at the University of British Columbia in Vancouver, Canada, with the CAMAC Serial Highway as the principal order of business. The Dataway and Software Groups have been meeting three times per year with the Serial Systems Sub-Group holding additional meetings as necessary. The Analogue Signals Working Group and the Mechanical and Power Supplies Working Group meet about twice yearly. The Working Groups have met last in Berkeley and San Francisco, California in conjunction with the 1973 Nuclear Science Symposium. ESONE representatives have also been present and participate.

Dataway Working Group

Chairman: F.A. Kirsten, Lawrence Berkeley Laboratory

This NIM-CAMAC Group (NDWG) has been cooperating with its ESONE-CAMAC counterpart (EDWG) in the development of the Serial Highway. It has set up a Serial Systems Sub-Group (Chairman D. R. Machen, Los Alamos Scientific Laboratory) that has prepared a detailed description of the Highway in cooperation with EDWG to enable construction of prototype systems. Formal specifications will follow. A Systems Compatibility Sub-Group has been set up (Chairman S. R. Smith, National Accelerator Laboratory) to study the problems associated with interfacing the Serial Highway to other data handling systems.

Software Working Group

Chairman: R.F. Thomas Jr., Los Alamos Scientific Laboratory

The NIM-CAMAC Software Group (NSWG) has defined a set of FORTRAN compatible sub-routines for CAMAC applications. This has been published in the CAMAC Tutorial Issue of the IEEE Transactions on Nuclear Science, April 1973. Recent work has included study of error recovery procedures and message format for the CAMAC Serial Highway System. The Working Group has investigated the problem of the multiplicity of block transfer modes with a view to recommending a limited useful set.

The CAMAC Intermediate Language (IML) has been studied in depth and it is hoped that NIM and ESONE endorsement will be forthcoming soon. Future work will include continued studies of block transfers and IML, to be followed by further work on higher level languages for CAMAC.

Liaison has been established with the Purdue Workshop on Standardisation of Industrial Computer Languages. The NSWG anticipates collaboration with respect to FORTRAN sub-routines and higher level languages.

Mechanical and Power Supplies Working Group

Chairman: D.A. Mack, Lawrence Berkeley Laboratory

The NMWG has been surveying the field for a suitable connector for the Serial Highway ports. Discussions are underway with ESONE regarding designation of a preferred connector for that purpose. The Working Group has also encouraged ma-

nufacturers to produce Dataway connectors of lower insertion force.

A number of manufacturers are now producing power supplies, Type CP-1, based on the description in Appendix E of AEC Report TID-25877 (also issued as Supplement to *CAMAC Bulletin* No. 6). This has provided ready power supply interchangeability.

A Dataway circuit-board tester has been developed and tested under the auspices of the NMWG. The tester checks for both open and short circuits on essentially all of the approximately 2100 connections on the Dataway. Details of the test unit can be obtained from Lee J. Wagner, Lawrence Berkeley Laboratory, University of California, Berkeley, California 94720.

Analogue Signals Working Group

Chairman: D.I. Porat, Stanford Linear Accelerator Center, Stanford

This Working Group (NAWG) and the ESONE counterpart (EAWG) have been collaborating on extension of the CAMAC Specifications of Amplitude Analogue Signals to cover both slow and fast signals. Agreement on a final version appears to be close at hand.

ESONE ANNOUNCEMENTS

NEW COMMITTEE MEMBERS

Since the last Bulletin Issue, the ESONE Committee has been pleased to welcome the following laboratories as full members of the Committee:

- Istitutul de Fizica Atomica, Bucaresti, Roumania, whose representative will be Mr. M. Patratescu, Cas Postala No. 35, Bucaresti, Roumania.
- Centre de Recherches Nucleaires, Strasbourg, France.

Laboratoire d'Électronique et d'Instrumentation Nucleaire du Centre Universitaire du Haut Rhin, Mulhouse, France.

Laboratoire des Applications Électroniques de l'École d'Ingénieurs Physiciens, Strasbourg, France.

These three laboratories will have one representative who has not yet been nominated.

Availability of Translations of CAMAC Specifications

The reference texts of the CAMAC specification contained in EURATOM Reports EUR 4100e (1972), EUR 4600e (1972), EUR 5100e (1972) are in English and are being translated into French (f), German (d) and Italian (i). In December 1973 at least preprints of these texts are likely to be available as follows:

4100 d, f. 4600 f, i 5100 d, f, i

BULLETIN ANNOUNCEMENTS

AVAILABILITY OF CAMAC BIBLIOGRAPHY

All Bulletin subscribers will receive, with this Issue, a copy of the Supplement to Bulletin No. 8 "CAMAC Bibliography".

Additional copies of the Supplement are available and can be obtained from:

Commission des Communautés Européennes, DG XIII–CID,

29, rue Aldringer, Luxembourg

and the price per copy, which will also cover postal charges, is 30 BFr or equivalent in any other currency.

NEW PRODUCTS

DATA MODULES (I/O Transfers and Processing)

Digital Serial Input Modules

Hex 24-bit 100 MHz Scaler

The Kinetic Systems Model 3615 is a single-width CAMAC module containing six 24-bit scalers. The scalers accept fast terminated input signals with frequencies from d.c. to greater than 100 MHz. Overflow latches are provided which can be set either after the 16th bit or the 24th. The scalers can be cleared by dataway command or by an unterminated fast-logic signal at the front panel. They also can be inhibited by either means.

Ref. Kinetic Systems

Digital Parallel Input Modules

3x16-bit Input Gate

The Input Gate Type 1063 is a single-width CAMAC module designed to enable up to 48 messages to be communicated to a system controller/computer. For ease of handling the 48 inputs are divided into three groups of 16.

Complete electrical isolation is provided by optocouplers between the incoming messages and the CAMAC system itself. The couplers can be powered from external sources or from the module.

The module is intended for applications in almost any industrial automation system requiring the cyclic acquisition of digital data.

Ref. Borer Electronics AG

Model J007 Input Gate

The Jorway Model J007 Input Gate is designed for applications where data from many sources is to be read onto the dataway. The 24-bit input gate can be selected by a p.c. board switch to have either lowtrue or high-true input characteristics. A binary 6-bit output from the module allows selection of up to 64 input sources. Strobe signals are generated by dataway commands for use in programing external devices such as A to D converters. A LAM signal is generated on the dataway from the external sources to signify that the data is ready to be taken. All signals for external sources are available from a 36-pin edge-connector located above the normal dataway connector. Options are also available for either a front-panel or rear-panel 2DB52P connector.

Ref. Jorway Corporation

Balanced Line Input/Output Registers

The Kinetic Systems Models 3030 and 3430 are single-width CAMAC modules that provide for input and output using balanced lines. They both provide 16-bit data paths. The Model 3030 provides 16 differential drivers while the Model 3430 provides 16 differential receivers. The receiver module also has 7 differential drivers for transmitting an address allowing up to 128 external data sources. A LAM is provided in each module which can be set and sensed by an external device thereby allowing for synchronization of data transfers.

Ref. Kinetic Systems

Digital Output Modules

Relay Driver

This single-width CAMAC module, Type JRD10, contains 16 reed-relays driven from the dataway. The contact of each relay is available on the front panel. A switch on the front panel selects one of three modes of operation:

- 16 contacts 'permanent';

8 contacts 'permanent', 8 contacts 'short';
16 contacts 'short'.

'Permanent' \equiv contact set until register content changes.

'Short' \equiv contact closure of 1 sec. duration. The contact ratings are 0.5A max., 50V max., 10W max.

Ref. SAIP Schlumberger

Digital I/O, Peripheral and Instrumentation Interfacing Modules

CS0042 Magnetic Tape Deck Interface

This single-width module incorporates the command, status, and data registers necessary to interface such tape decks as the DEC TU10 and Racal T7000. The interface may also be used for connecting cassette tape recorders such as the Racal P70, into a system as an economic alternative to paper tape. Write data can be optionally loaded as 6, 8, 12, or 16-bit words into a 16-bit register whose output is provided with gates that are enabled in a stepped sequence determined by links so that data may be written onto tape in either 7 or 9-track format.

Demands for data transfer may be made by LAM requests or via a front panel trigger pulse which can be used to trigger an Autonomous Controller type 9033 into transferring data via a DMA channel of a computer. Power consumption + 6V at 1.2Amp.

Ref. Nuclear Enterprises

Teletype Driver

This single-width CAMAC module, Type JTY10, connects a teletype ASR33, KSR33, etc. to a CAMAC crate.

The ASC II code is loaded from the W-lines (Write) and parallel to serial transcoding is automatically performed. The serial word is transferred to the teletype. The end of transfer generates a LAM.

The teletype sends a character and the serial code is converted to a parallel one in the module. The end of this conversion generates a LAM. The character is read from the R-lines (Read). In both cases, the Q response depends on the state of the module.

Two transfer speeds of 110 and 300 bauds are selected by a switch on the front panel. Other characteristics which can be chosen by internal straps are:

- Bit number of data (5-6-7 or 8);
- Bit number of stops (1 or 2);
- Parity control or not;
- Parity type (even or odd).

The output is between 24 V and an open collector (PNP transistor) and 20mA is available.

The input signal comes from a contact in the teletype that gives a logical 'l' in the module when the contact is open and a logical 'O' when closed.

Ref. SAIP Schlumberger

Model J154 Motor Controller

This single-width module is designed for use in controlling externally connected stepping-motor or servo controllers. The number of increments to be generated is written via the dataway into a 15-bit counter. A self contained oscillator clocks the counter down to zero while increment pulses are issued for external stepping motors. During counting, a contact closure occurs which may be used for servo-control. Included are pulse outputs and contacts for determining motor direction. Commands are also implemented for use in turn-on, turn-off, and reset of external devices. The progressing count-down of the 15-bit counter can be read on the dataway R lines at any time. An additional 8 bits of external status information can also be read. Connection options are available for either front or rear panel.

Ref. Jorway Corporation

Digital Data Handling and Processing Modules

Digital Window Discriminator



The DWD2046 is a compact singlewidth, second-generation CAMAC module, developed primarily as a sophisticated buffer-memory to reduce latency overhead in data acquisition systems. The unit has a digital window and coincidence logic capability, and will accept serial or parallel inputs. The buffer memory is a 16-bit shift register with 128 locations. A built-in DCH logic provides direct memory access transfers of the contents.

The unit has many applications in simple and multi-parametric coincidences PHA (pulse height analysis) systems, in multi-channel scaling, in Sampling Analysis and Fourier Analysers.

Designed for specific use in the SEN Spectrum Analyser, the DWD de-randomises event processing, and a speed of more than 400 kcs is achieved with this system. However the unit is fully compatible with any ADC, and handles NIM/TTL levels.

Ref. SEN Electronique

Analogue Modules

Recorder Driver

This single-width CAMAC module, Type JXY10, is a digital-to-analogue converter allowing X-Y recorders to be driven by a CAMAC System. It can drive two recorders simultaneously.

An output on the front panel enables control of the pen-lift. Two 10-bit registers X and Y are loaded from the write lines (W1 to W10) and for each register a D-A converter delivers X and Y analogue signals needed by the recorder. A third register of 4 bits sets the mode of operation:

- X and Y are totally separated and independently loaded:
- Each new loading of Y increments 1 in the X register;
- Each new loading of X increments 1 in the Y register;
- Pen-lift contact always open, closed, or closed for a period that can be adjusted at each Y loading.

The X and Y outputs are 0 to +10V or -5V to +5V, 10mA. The pen-lift contact rating is 0.5A max., 50V max., 10W max.

Ref. SAIP Schlumberger

SYSTEM CONTROL

(Computer Couplers, Controllers and Related Equipment)

Interfaces/Drivers and Controllers

LABEN Branch Driver

LABEN, a Division of MONTEDEL, has recently developed, in co-operation with EURATOM of Ispra, a Branch Driver (model 5400) which allows CAMAC modules to be connected to the LABEN 70



and LABEN 701 digital computers. The unit is designed to control, via the CCA, up to 7 crates. Data transfer can be performed under program control and in program interrupt (or DMA mode) in either single- or block-transfer mode.

Special operating procedures have been studied to provide the highest level of control flexibility. Particular attention has been given to the LAM PATTERN read-in facility in order to easily identify the module that has generated the LAM signal.

Ref. LABEN

CS0044 Varian Interface Card

This unit is designed to plug into the interface-card option slot of the 9030 Controller and interfaces the Controller directly to the Varian 73, 620I or 620L series computers. Connection is made to the machine via a multi-way twisted-pair cable terminated in a 132-way plug.

Combined with the 9030 to form a CAMAC interface to the Varian series, the unit is capable of 24-bit program transfer operation and will interface a single crate in its basic form. It may be extended for multi-crate systems by connection of a Branch Interface, Type 9031, module within the master crate.

Ref. Nuclear Enterprises

NPR Controller for DMA with a PDP-11

The Non-Processor Request Controller Type 1542 provides a simple, inexpensive means of performing fast block transfers to or from a PDP-11 Computer. Designed as a plug-in circuit card which fits inside the computer, the Controller makes direct connection with the Unibus and can therefore be used as a general purpose device or to enhance the capability of a CAMAC interface such as the Borer Type 1533A. The Controller itself does not limit the transfer rate and effectively provides direct memory access although requiring two Unibus cycles per transfer instead of one as for conventional DMA.

Three modes of operation are possible namely: Move, Histogram and Listing modes.

In the Move mode, CAMAC sub-addresses and memory addresses can be simultaneously scanned until a predetermined number of words have been transferred. The Histogram mode operates with a chosen single CAMAC sub-address (e.g. an ADC) and uses the data obtained to define memory addresses so that the respective contents are incremented by one, as appropriate for each transfer. Lastly, the Listing mode can be used to increment the memory address for each data word transferred.

All test and control operations associated with the transfer of a data block are performed instantly by hardware and use of the Unibus is limited to the movement of data only.

Ref. Borer Electronics AG

9033 Autonomous Controller

This is a double-width CAMAC module designed to interface the DMA facility of the PDP-11 Unibus to the CAMAC system. It is used in conjunction with the 9030/9032 PDP-11 interface modules.

Four separate DMA channel facilities are included in the module. Each DMA transfer can be triggered by an external pulse or level applied to one of its four trigger inputs. Two basic modes of operation are possible on each channel. Either block transfer of data or direct increment of data held in memory can be performed. The module contains four wordcount registers so that block transfers can be made on each channel independent of the others. Power consumption, +6V at 2A.

Ref. Nuclear Enterprises

Units Related to 4600 Branch or Other Parallel Mode Control/Data Highway

LAM Grader

The Model LG, LAM Grader, when used in conjunction with a Type A-1 Crate Controller will sort and select Interrupt requests both from the Dataway and from external sources. It accepts 23 'L' inputs from the controller and four external interrupts that are stored in the module. These Interrupt signals are internally patched according to the user's priority and sent back to the controller as graded 'L' signals (GL). These GL signals may also be masked under computer control by updating a masking register which will inhibit unwanted interrupts.

Three of the four external interrupts accepted by the module are triggered by a CAMAC logic pulse and the other is initiated by a front panel pushbutton. In response to these interrupts an output signal is generated indicating that the interrupt has been set in the module and will remain there until the bit is reset by function F10 or Z.

To allow proper use of the Graded L Command 'BG', additional GL inhibiting is provided. In response to a BG Command each crate can supply interrupt information on the BRW lines in multiples of three. This allows a seven-crate system to present its interrupt condition at one time, three interrupts from each of the seven crates and three additional that can be assigned to any crate. This gives the Branch Driver a composite picture of the systems interrupt-profile. If more detailed 'L' information is required, the Branch Driver will then command a controller to read all the GL's from that crate onto the BRW lines. To allow this gating in response to BG, a multiposition switch can select the bits to be used in that crate's BG response.

Indicators are provided to show when the module is addressed, either by command (N28+N30) or if a Graded L operation (BG) is taking place. An indicator is also provided to show if any GL requests are present.

Functions Used: F10, F16. Size: Single width. First Shipment: 6/73.

Ref. Joerger Enterprises

Branch Highway Serial Extension

This system allows the standard Branch Highway to be operated over long distances. It consists of a Serial Driver module and at least one Serial Receiver module. These CAMAC modules are connected over a serial highway containing 16 twisted-pairs, 8 for send and 8 for receive. The Serial Driver is connected to a standard Branch Driver. It accepts the CAMAC command, serializes it, transmits it to the Serial Receiver(s) which reconstructs the command and drives a standard Type A-1 system of one or more crates. The Serial Receiver also retransmits the serial data for use by other Serial Receivers. When the command is completed, the Serial Receiver transmits the response back to the Serial Driver which reconstructs the response and sends it to the Branch Driver. The complete CAMAC command is transmitted including the spare lines (BV). The timing (BTA, BTB) is reconstructed in each unit. To the Branch Driver, the input port of the Serial Driver will respond exactly like a Type A-1 system except that the cycle time will be longer. A complete CAMAC cycle will take approximately 1200 µsec.

The Branch Demand, BD, returns on a separate line to facilitate demand handling. Initialize, BZ, also uses a separate line to allow the system to be initialized by the driver, although both the Serial Driver and Receiver Initialize when their power is turned on. The remaining seven send and receive lines are used for data transmission.

This system provides a reliable, isolated long-distance link between CAMAC crates, primarily intended for control applications where speed is not an important factor. The system is asynchronous and therefore eliminates skew errors. The transmit and receive sections are in one MOS package. A data word contains a Start bit, two Stop bits, eight Data bits, and a Parity bit. Error checking is provided in both units. To avoid ground loops between stations, the inputs are all optically isolated and this could also be useful when stations are close together in a poor electrical environment and could simplify many system problems. The system has been designed around EUR 4600e and can handle up to seven crates. These crates may all be attached to one Serial Receiver or a system could contain seven Serial Receivers each driving one crate or any combination. Both the Serial Receiver and Driver provide a 100 ohm termination for the Branch highway. They are double-width CAMAC modules that use the Dataway only for power.

First Shipment: 7/73.

Ref. Joerger Enterprises

TEST EQUIPMENT

Dataway Related Testers and Displays

Manual Input Register

The Manual Input Register, Type 1041 is a singlewidth CAMAC module that facilitates the reading of a 16-bit data word (such as a parameter) composed manually by use of switches on the front panel. The status of the switches is read directly onto the Dataway by a Read command: no intermediate memory is included.

A push-button switch and a coaxial input provide alternative means for generating a LAM. The L-signal can be disabled when necessary and in any case disappears whenever the module is addressed.

A small measure of hardware programming is included so that the LAM can be cleared either by a normal Reset LAM command alone, or additionally in conjunction with a Read command. The choice is made with a single-wire link on the circuit board of the instrument.

Ref. Borer Electronics AG

CRATES, SUPPLIES, COMPONENTS, ACCESSORIES

Crates and Related Components/Accessories

CAMAC Crate With Power Supply

This crate, Type CJAL41, has a power unit designed to supply CAMAC modules. It delivers 400 W on ± 6 V and ± 24 V. The crate is equipped with floating edge-connectors and a wire-wrapped twisted-pair dataway for low cross-talk between lines. The crosstalk is down by a factor 5 to 10 compared to other CAMAC powered crates with dataways not having twisted-pairs, when the interference created on one wire by a standard CAMAC signal transmitted on the second wire of the same pair is measured. The specification of the power is as follows:

- Input: $220V \pm 10\%/50$ Hz
- Output: +24V/ 3A
 - -24V/3A
 - + 6V/24A
 - 6V/16A
- Maximum power: 400 W (maximum currents simultaneously supplied for all voltages)
- Stability: $\pm 10\%$ mains variation: 10^{-3} temperature variation : $10^{-4}/^{\circ}C$ 100% load variation : 10^{-3}
- Security: against overvoltage, overheat and supply failure.
- Ventilation: Air-blown by means of 3 fans at the front part of the crate and 3 other fans at the rear.

Ref. SAIP Schlumberger

Recommended or Standard Components/Accessories

CAMAC - PDP-11 Interface Harness

The latest item in the TEKDATA range of CAMAC interconnection products is a CAMAC to PDP-11 Unibus interface harness.

The harness connects a PDP-11 to CAMAC equipment directly without needing junction boxes or DEC Unibus harnesses.

TEKDATA's standard CAMAC 68, twisted-pair, multi-layer, ribbon cable is used (2 spare twisted pairs are available for use in the event of wire breakage in use) with overall screen and PVC sheath. Three options are available for screening: tinned copper mesh, tinned copper braid and stainless steel braid. These items are very flexible and manufactured to a high-quality level.

When ordering, the following code should be used 5805 P M-XXX. Replace P by S for 132-way socket; M refers to tinned copper mesh screen replace by B or S for tinned copper braid or stainless steel braid respectively; XXX = length in meters.

Ref. TEKDATA Ltd.



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HOW TO CONTACT CAMAC WORKING GROUPS

Everybody who is interested in further information on the activities of the CAMAC Working Groups or who would like to obtain advice for the application of CAMAC specifications is invited to contact the appropriate chairman or secretary of the existing working groups. The corresponding addresses are given below.

ESONE-CAMAC WORKING GROUPS

ESONE-CAMAC Dataway Working Group (EDWG)

- Chairman: H. Klessmann, Hahn-Meitner-Institut für Kernforschung, Berlin GmbH, 1 Berlin 39, Glienickerstr. 100, Germany.
- Secretaries: R. C. M. Barnes and I. N. Hooton, both of Electronics and Applied Physics Div., Building 347.2, AERE Harwell, Didcot, Berks. OX11 ORA, England.

ESONE-CAMAC Software Working Group (ESWG) *Chairman:* I.N. Hooton, see above.

Secretary: H. Halling, Hernforschungsanlage Jülich GmbH, Zentrallabor für Elektronik/NE, 517 Jülich, Postfach 365, Germany.

ESONE-CAMAC Analogue Signals Working Group (EAWG)

Chairman: Th. Friese, Hahn-Meitner-Institut für Kernforschung Berlin GmbH, 1 Berlin 39, Glienickerstr. 100, Germany.

ESONE-CAMAC Mechanics Working Group (EMWG)

- Chairman: F.H. Hale, Electronics and Applied Physics Div., Building 347.2, AERE Harwell,
 - Didcot, Berks. OX11 ORA, England.

ESONE-CAMAC Information Working Group (EIWG)

Chairman: H. Meyer, CBNM Euratom, Steenweg naar Retie, 2440 Geel, Belgium.

NIM-CAMAC WORKING GROUPS

NIM-CAMAC Dataway Working Group (NDWG)

- *Chairman:* F.A. Kirsten, Lawrence Berkeley Laboratory, University of California, Berkeley, Ca. 94720, U.S.A.
- Secretary: S.J. Rudnick, Argonne National Laboratory, P.O. Box X, Oak Ridge, Tennessee 37830, U.S.A.

Serial Systems Sub-group

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PAPER ABSTRACTS TRANSLATIONS

Modularity and CAMAC H. Bisby

Summarv

The instrumentation associated with nuclear sciences has always taken advantage of new data-processing techniques. The early introduction of the modular concept and its continuous development led to the CAMAC Standard. The modular concept is described and the advantages of CAMAC are examined.

Zusammenfassung

Die Kernwissenschaft hat neue Datenverarbeitungstechni-ken stets für ihre Instrumentierung genutzt. Die frühzeitige Einführung des modularen Konzepts und seine ständige Weiterentwicklung haben zu dem CAMAC-Standard geführt. Das modulare Konzept wird beschrieben und die Vorzüge des CAMAC-Systems werden behandelt.

Résumé

L'instrumentation liée aux sciences nucléaires a toujours bénéficié des nouvelles techniques de traitement des données. L'introduction, dès le début, du concept modu-laire et son développement ininterrompu ont abouti au Standard CAMAC. Description du concept modulaire et examen des avantages du CAMAC.

Riassunto

La strumentazione delle scienze nucleari ha sempre sfruttato i vantaggi connessi alle nuove tecniche di trattamento dei dati. L'introduzione del concetto modulare e la sua continua evoluzione hanno condotto allo standard CAMAC. Nel documento viene descritta la concezione modulare e i vantaggi del CAMAC.

Samenvatting

Bij de instrumentatie in verband met de kernwetenschappen In de instrumentatie in verband met de kernwetenschappen is steeds geprofiteerd van nieuwe technieken op het gebied van de verwerking van gegevens. De vroegtijdige invoering van het modulaire concept en de voortdurende ontwikkeling daarvan, heeft geleid tot de CAMAC-standaard. Er wordt een beschrijving gegeven van het modulaire concept en nader ingegaan op de voordelen die CAMAC biedt.

Резюме

Ядерная аппаратура всегда пользовалась новыми достимсениями обработки данных. Давно применяемая идея блочной системы и её дальнейшее развитие привели к стандарту САМАС. Описана концепция блочных систем и рассмотрены преимущества системы САМАС.

The CAMAC Serial Highway - A Preview R.C.M. Barnes

Summary

Advance information is given on a new CAMAC serial highway, com-plementing the existing parallel Branch Highway (EUR 4600a).This serial highway can be used, either alone or in conjunction with modems, over longer distances and in noisy environments. It can be connected to standard communications interfaces available on most computers.

Zusammenfassung

Der Bericht enthält erste Angaben über einen neuen seriellen CAMAC-Highway, der den vorhandenen parallelen Branch Highway (EUR 4600e) ergänzt. Dieser serielle Highway kann allein oder in Verbindung mit Modems für die Daten-übertragung über grössere Entfernungen und bei hohem Geräuschpegel benutzt werden. Die Verbindung mit den bei den meisten Rechnern vorhandenen Standardanschlüs-sen für die Datenübertragung ist möglich sen für die Datenübertragung ist möglich.

Résumé

Informations préliminaires sur une nouvelle interconnexion de branche série qui complète l'interconnexion de branche parallèle déjà existante (EUR 4600e). Cette interconnexion série peut être utilisée soit seule, soit en association avec des modems, sur de plus longues distances et dans des milieux perturbés. Elle peut être reliée aux interfaces de communica-tion standards qui existent dans la plupart des ordinateurs.

Riassunto

Vengono fornite anticipatamente informazioni su una nuova interconnessione serie CAMAC che si aggiunge al collegamento del ramo principale già esistente (EUR 4600e) Tale interconnessione serie puo' essere utilizzata da sola o insieme a modem su lunghe distanze e in ambienti rumorosi.

Puo' essere collegata a interfacce standard di comunicazione disponibili nella maggioranza dei calcolatori.

Samenvatting

Samenvatting Voorafgaande informatie wordt hier verstrekt over de nieuwe CAMAC-hoofdlijn voor seriebewerking welke een aanvulling vormt op de bestaande vertakkingshoofdlijn voor parallelbewerking (EUR 4600e). Deze hoofdlijn voor seriebewerking kan hetzij op zichzelf, hetzij in combinatie met modems worden gebruikt over grotere afstanden en in luidruchtige omgevingen. De lijn kan worden aangesloten op standaard-interfaces voor communicatie die op de meeste computers aanwezig zijn.

Резюме

Предварительные информации о новой, последовательной магистрали САМАС, которая дополняет существующую магистраль ветви (EUR 4600). Последовательная магистраль может работать или самостоятельно или совместно с модемами на большие расстояния и в присутствии помех. Может быть подключена к стандартным интерфейсам связи доступным в большенстве Э́ВМ.

A Data Acquisition System Based on CAMAC and Supported by BASIC and FORTRAN D. A. LePatourel, R. R. Johnson, D. Marquardt, D. Gurd

Summary

Summary A 12 k minicomputer has been used with CAMAC and NIM equipment in an intermediate-energy nuclear scattering data acquisition system. The system is programmed in BASIC or FORTRAN, with sub-routines for input/output via CAMAC. The version with BASIC is most useful to experimenters, except where higher data rates require the use of FOR– TRAN.

Zusammenfassung

Ein 12k-Kleinrechner wird zusammen mit CAMAC- und NIM-Geräten in einem Datenerfassungssystem für Kern-streu-Experimente im mittleren Energiebereich eingesetzt. Das System wird in BASIC oder FORTRAN — mit Unter-programmen für Ein- und Ausgabe über CAMAC — pro-grammiert. Die Variante in BASIC ist für die Experimenta-toren sehr zweckdienlich; für höhere Datenübertragungs-raten muß jedoch FORTRAN benutzt werden.

Résumé

Résumé Un miniordinateur de 12k, associé à des éléments CAMAC et NIM, a été utilisé dans un système d'acquisition de données pour expériences de diffusion de particules nucléaires en moyenne énergie. Le système est programmé en BASIC et en FORTRAN, avec des sous-programmes d'entrée/sortie par CAMAC. La version BASIC est la plus utile aux expérimentateurs, sauf dans les cas où le taux élevé de données à acquérir nécessite l'utilisation du FORTRAN.

Riassunto

Un mini calcolatore da 12 k è stato usato con apparecchia-ture CAMAC e NIM in un sistema di acquisizione di dati sulla diffusione nucleare a media energia. Il sistema è programmato in BASIC o FORTRAN con sub-routine per l'ingresso/uscita tramite il CAMAC. La versione BASIC è estremamente utile per gli sperimentatori, salvo quanto dato il maggiore flusso di dati è necessario impiegare il FORTRAN.

Samenvatting

Samenvatting In combinatie met CAMAC en NIM-uitrusting is gebruik gemaakt van een 12k-minicomputer bij een verwervings-systeem voor gegevens over nucleaire verstrooiings-doorsneden bij intermediaire energie. Het systeem is geprogrammeerd in BASIC of FORTRAN, met subpro-gramma's voor in- en uitvoer via CAMAC. De versie met BASIC is bijzonder nuttig voor experimentele doeleinden, behalve indien het gebruik van FORTRAN vereist is voor grotere gegevenssnelheden.

Резюме

В системе сбора данных для эксперимента ядерного рассеяния в области средних энергии применено миником-путер с памятью 12 к совместно с аппаратурой САМАС и NIM. Программы ввода и вывода данных через САМАС написано на языках Базик и фортран. Версия на Базике является более удобной для экспериментаторов за исключением случаев большой скорости передачи.

CAMAC Applications in the Central Electricity Research Laboratories E. G. Kingham and R. E. Martin

Summary

The paper reviews various applications of CAMAC in a multi-discipline research laboratory. Two autonomous systems are used for data logging and supervision. Other autonomous systems control and collect data from an electron-beam analyser and X-ray diffractometer. A computer-based system is used for data acquisition and processing.

Zusammenfassung

Lusammentassung Es wird über verschiedene CAMAC-Anwendungen in einem multidisziplinären Forschungslaboratorium berichtet. Für die Datenabfrage und die Überwachung werden zwei autonome Systeme benutzt. Weitere autonome Systeme dienen zur Steuerung und Datenaufnahme von einem Elektronenstrahl-Analysator und einem Röntgendiffrak-tometer. Für die Datenerfassung und -verarbeitung wird ein rechnergeführtes System benutzt.

Résumé

Cet article passe en revue diverses applications CAMAC dans un laboratoire de recherches pluridisciplinaire. Deux systèmes autonomes sont utilisés pour l'acquisition des données et la surveillance. D'autres systèmes autonomes contrôlent et collectent les données fournies par un analy-seur à balayage électronique et par un diffractomètre à rayons X. Un système avec ordinateur est utilisé pour l'acquisition et le traitement des données.

Riassunto

Vengono passate in rassegna varie applicazioni CAMAC in un laboratorio di ricerche multidisciplinari. Vengono usati due sistemi autonomi per la catalogazione e la supervisione dei dati. Altri sistemi autonomi controllano e raccolgono i dati da un analizzatore a elettroni e da un diffractometro a raggi X. L'acquisizione dei dati e il trattamento vengono effettuati tramite un sistema con calcolatore.

Samenvatting

Samenvatting In dit document wordt een overzicht gegeven van ver-schillende toepassingen van CAMAC in een onderzoek-laboratorium voor uiteenlopende wetenschappelijke ge-bieden. Voor datalogging en supervisie wordt gebruik gemaakt van twee autonome systemen. Andere autonome systemen dienen voor het controleren en verzamelen van gegevens van een elektronenbundelanalysator en een rönt-gendiffractiemeter. Voor het verkrijgen en het verwerken van de gegevens wordt gebruik gemaakt van een op een computer gebaseerd systeem.

Резюме

Расмотрено разные применения САМАС-а в многопро-фильной научной лаборатории. Две автономиые системы использовано для сбора данных и контроля. Другие автономные системы собирают данные и управляют анализатором пучка нейтронов и Х-лучевым спектро-метром. Базированые на ЭВМ системы, применено для сбора и обработки данных.

CAMAC Branch Driver for Laben Computers L. Stanchi

Summary

A branch driver for use with Laben 70 and 701 computers is described. It contains features for fast handling of special LAM's, for address scans over an unknown number of registers, and for direct transfer of data between modules.

Zusammenfassung

Eine zentrale Steuerung für den Einsatz mit Laben-Rechnern 70 und 701 wird beschrieben. Sie ist für schnelle Verar-beitung spezieller Anforderungen, sequentielle Adressierung über eine unbekannte Anzahl von Registern sowie für direkte Datenübertragung zwischen Moduln ausgelegt.

Résumé

Description d'une commande de branche pour ordinateurs LABEN 70 et 701. Cette commande contient des dispositifs pour le traitement rapide de LAM spéciaux, pour des scruta-tions d'adresses sur un nombre de registres inconnu et pour le transfert direct de données de tiroir à tiroir.

Riassunto

Viene descritto un elemento di comando di ramo da im-piegare con i calcolatori LABEN 70 e 701. Esso è concepito in particolare per il trattamento rapido di LAM speciali, per la scansione di indirizzi su un numero incognito di registri e per il trasferimento diretto di dati fra moduli.

Samenvatting

In dit document wordt een beschrijving gegeven van branchbekrachtiging voor gebruik in combinatie met Laben 70 en 701 computers. Deze vertoont speciale kenmerken voor een snelle verwerking van bijzonder LAM's, voor adresaftasting bij een onbekend aantal registers, en voor rechtstreekse overdracht van gegevens tussen modules. tussen modules.

Резюме

Описан контроллер ветви для ЭВМ Laben 70 и 701 в котором возможна быстрая обработка специальных заявок LAM, сканирование адресов при заранее неиз-вестном количестве регистров как и прямая передача между модулями.

Developments in Hardware and Software for the **7025** Programmed Dataway Controller L. D. Ward and R. C. M. Barnes

Summary

Many successful CAMAC systems use the Harwell/Nuclear Enterprises 7025 programmed Dataway Controller. The programs have mostly been written in machine code and held in 256-word read-only stores. New developments described in this paper provide assembly-level program-ming facilities and a 2730-word read-write store for programs and data.

Zusammenfassung

Viele erfolgreiche CAMAC-Systeme arbeiten mit der programmierten Datenwegsteuerung 7025 von Harwell/ Nuclear Enterprises. Die überwiegend in Maschinencode geschriebenen Programme sind in Festspeicher mit 256-Worten eingegeben. Als neue Entwicklungen werden die Programmierung in Assemblersprache und ein 2730-Wort-Lese-Schreib-Speicher für Programme und Daten be-schrieben. schrieben.

Résumé

Un grand nombre de systèmes CAMAC donnant toute satisfaction utilisent le contrôleur de châssis programmé Harwell/Nuclear Enterprises 7025. La plupart des pro-grammes ont été écrits en code-machine et stockés en mémoires mortes de 256 mots. Cet article décrit de nou-veaux perfectionnements, procurant des possibilités de programmation au niveau de l'assemblage ainsi qu'une mémoire lecture-écriture de 2730 mots pour les programmes et les données. et les données.

Riassunto

In molti sistemi si usa con successo il modulo di controllo programmato Harwell/Nuclear Enterprise 7025. I programmi sono scritti generalmente in codice macchina e memorizzati in memorie a 256 parole per sola lettura. I recenti sviluppi descritti nel documento riguardano dispositivi di program-mazione a livello assembler e una memoria per lettura e scrittura a 2730 parole per programmi e dati.

Samenvatting

Samenvatting Bij een groot aantal succesvol werkende CAMAC-systemen wordt gebruik gemaakt van de Harwell/Nuclear Enterprises 7025 Programmed Dataway Controller. De programma's zijn voor het merendeel gesteld in machinetaal en opge-slagen in uitsluitend uitleesbare geheugens van 256 woor-den. De nieuwe ontwikkelingen die in dit document zijn beschreven resulteren in programmeringsvoorzieningen op assembleerniveau en een 2730-woorden lees/schrijfge-heugen voor de programmen en de gegevens.

Резюме

Во многих системах САМАС успешно применяются програмные контроллеры типа Harwell 7025. Чаще всего программы создаются в машинном коде и сохраняются в постоянной памяти ёмкостью до 256 слов. Описанные новые разработки касаются языка ассемблера как и применения памяти 2370 слов для хранения программы и доших и данных.

A Serial Crate Controller

F. Buschbeck and E. Neuwirth

Summary

This paper describes a serial CAMAC crate controller for smaller systems. Each byte is a unique message, thus avoiding problems of message synchronisation. There is a full-duplex link from each crate controller to synchronisation the computer.

Zusammenfassung

Es wird ein serieller CAMAC-Cratecontroller für Anwen-dung in kleineren Systemen beschrieben. Jedes Byte ist ein
eindeutiger Befehl, Probleme der Satzsynchronisation fallen dadurch weg. Jeder Cratecontroller soll über eine eigene full-duplex Leitung an den Rechner angeschlossen werden.

Résumé

Le présent article contient une description d'un contrôleur de châssis série destiné à des petits systèmes. Chaque byte est un message unique, ce qui élimine les problèmes de synchronisation des messages. Un circuit «full-duplex» relie chaque contrôleur de châssis à l'ordinateur.

Riassunto

Si descrive un modulo di controllo serie per piccoli sistemi. Ciascun byte è un unico messaggio per cui si evitano i problemi di sincronizzazione dei messaggi. Ciascun modulo di controllo è collegato al calcolatore mediante un collegamento duplex completo.

Samenvatting

In dit document wordt een beschrijving gegeven van een serie-CAMAC cratecontrollen voor toepassing in kleinere systemen. Elke byte is een duidelijk enkel bevel waardoor problemen in verband met synchronisatie van mededelingen worden voorkomen. Elke cratecontroller beschikt over een eigen full-duplexverbinding met de computer.

Резюме

Описан контроллер последовательного типа для крейта САМАС в небольших системах. Каждый байт является отдельным сведением, что упрощает синхронизацию. К каждому контроллеру крейта присоединяется полную, дуплексную линию связи.

Derandomising CAMAC Input Module **R. Klesse**

Summary

This CAMAC module is a last-in first-out buffer that can accept randomly-timed data words and transfer them via the Dataway to a computer. It is used when the transfer rate to the computer is not sufficient for the peak data rate, but can handle the mean rate.

Zusammenfassung

Dieser CAMAC-Modul ist eine «last in — first out» -Puffereinheit, die eine Zufallsfolge von Daten aufnehmen und über den Datenweg zu einem Rechner übertragen kann. Er wird eingesetzt, wenn die Übertragungsfrequenz zum Rechner nicht für die gewünschte Doppelimpulsauflösung der Ereignisse ausreicht, wenn aber der mittleren Über-tragungsgeschwindigkeit (jedoch) entsprochen werden kann. kann.

Résumé

Ce module CAMAC est une mémoire tampon « dernier entré — premier sorti » qui accepte les données arrivant à des instants aléatoires et les transfère à un ordinateur via l'Interconnexion. Il est utilisé lorsque la vitesse de transfert à l'ordinateur est insuffisante pour absorber le débit maximal de données, alors que le débit moyen peut être traité.

Riassunto

Questo modulo CAMAC è un disaccoppiatore che riceve dati in successione casuale e li trasferisce al calcolatore tramite l'Interconnessione in modo tale che l'ultimo entrato viene trasferito prima. Esso viene impiegato quando la cadenza di trasferimento al calcolatore è insufficiente per la cadenza di picco ma puo' trattare la cadenza media.

Samenvatting

Deze CAMAC moduul is een (laatst-in-eerst-uit) buffer-geheugen dat willekeurig in de tijd komende gegevens-woorden kan opnemen en via de Dataway overbrengen naar de computer. Hiervan wordt gebruik gemaakt wanneer de overbrengingssnelheid van de computer niet voldoende is voor de pieksnelheid van de gegevenstoevoer doch deze de gemiddelde snelheid hiervan kan verwerken.

Резюме

Описанный блок САМАС является буфером, который принимает случайно распределенные слова данных и передает их через магистраль к ЭВМ начиная с последнего событья. Блок применяется в случаях когда частота передачи к ЭВМ не достигает максимальной частоты пиреозграница даницах однако пелетов достаточной прихождения данных однако является достаточной, учитывая среднее значение этой частоты.

Some Aspects of a Compiler Writing System and the Implementation of the CAMAC Language K. H. Degenhardt, U. Marx-Rehbein, W. Woletz

Summary

Recent work at the Hahn-Meitner-Institut to automate the writing of compilers for programming languages is presented. The first application of the Compiler Writing System (CWS) will be the implementation of a compiler for the CAMAC language.

Zusammenfassung

Neuere Arbeiten im Hahn-Meitner-Institut zur Automati-sierung des Schreibens von Kompilern für Programmier-sprachen werden beschrieben. Als erste Anwendung des Compiler Writing System (CWS) soll ein Kompiler für die CAMAC-Sprache erstellt werden.

Résumé

Présentation des travaux récents effectués au Hahn-Meitner-Institut, en vue de l'automatisation de l'écriture des compilateurs utilisés pour les langages de programma-tion. La première application du « Compiler Writing System » (CWS) sera la mise en œuvre d'un compilateur pour langage CAMAC.

Riassunto

Vengono presentate le recenti attività svolte presso l'Hahn Meitner- Institut per automatizzare la scrittura dei compi-latori di linguaggi di programmazione. La prima applicazione del Compiler Writing System (CWS) sarà la preparazione di un compilatore per il linguaggio CAMAC.

Samenvatting

In dit document wordt ingegaan op recente werkzaamheden bij het Hahn-Meitner-Institut met het oog op een geauto-matiseerde samenstelling van compilators voor program-meringstalen. De eerste toepassing van het Compiler Writing System (CWS) is de uitvoering van een compilator voor de CAMAC-taal.

Резюме

Представлены, ведущиеся в Институте Hahn-Meitner, последние разработки в области автоматизации создания компайлеров для языков программирования. Первым применением системы писания компайлеров (CWS) будет язык САМАС.

Proposal for a Power Failure Signal from the CAMAC Power Supply to the Control Station C. Eck, F. Iselin, J.-P. Vanuxem

Summary

A Power Failure feature is recommended to provide the controller with an early warning signal that the mains supply has failed. This allows action to be taken to save the contents of registers in the CAMAC crate while the d.c. supply voltages are still within tolerances.

Zusammenfassung

Ein « Power Failure » (PF) Signal wird empfohlen, das ein Zusammenbrechen der Netzspannung frühzeitig anzeigt. Dies Signal ermöglicht das Auslesen aller Register eines CAMAC-Rahmens, bevor eine der Gleichspannungen unter den erlaubten Grenzwert fällt.

Résumé

Un dispostif « Défaut d'alimentation » est recommandé : il permet de donner, dès le début, au contrôleur, un signal lui indiquant la défaillance du circuit d'alimentation principal, ce qui permet d'intervenir pour préserver le contenu des registres du châssis CAMAC, avant que les tensions d'alimentation ne soient hors tolérances.

Riassunto

Si raccomanda un indicatore di guasti per informare il modulo di controllo tramite un segnale immediato che la rete di alimentazione è interrotta. E' possibile così prendere provvedimenti per salvare il contenuto dei registri nel contenitore CAMAC quando le tensioni continue di alimen-tazione sono ancora entro le tolleranze prescritte.

Samenvatting

In dit document wordt de toepassing aanbevolen van een voorziening in geval van het uitvallen van de voedings-stroom zodat bij de besturing tijdig een signaal wordt ontvangen dat de stroomtoevoer is onderbroken. Hierdoor kunnen maatregelen worden genomen om de inhoud van de registers in het CAMAC-crate te behouden zolang de voltages van de voedingsgelijkstroom nog binnen de toelaatbare grenzen blijven.

Резюме

Рекомендуется применение сигнала «Неисправность питания », который предупреждает о ожидаемом отсутствии питания. Это позволяет сохранить содержание регистров крейта САМАС пока питающие напряжения еще находится в пределах толеранции.

Module Descriptor O. Ph. Nicolaysen

Summary

The revised CAMAC specification recommends an address for accessing a module descriptor word, but does not define the contents of the descrip-tor. This paper reviews the sources of information about the characteristics of a CAMAC module, and proposes a 16-bit descriptor word.

Zusammenfassung

Die überarbeitete CAMAC-Spezifikation empfiehlt eine Adresse für den Zugriff auf ein Modul-Deskriptorwort, ohne jedoch den Inhalt des Deskriptors zu definieren. Der Bericht legt dar, wie Informationen über die Charakteristiken eines CAMAC-Moduls erlangt werden können, ein 16-Bit-Deskriptorwort wird vorgeschlagen.

Résumé

Les spécifications CAMAC révisées recommandent une adresse qui permet l'accès à un mot descripteur du tiroir mais elle ne précise pas le contenu du descripteur. Le présent article passe en revue les sources d'information relatives aux caractéristiques d'un tiroir CAMAC et propose un mot descripteur de 16 bits.

Riassunto

Nelle caratteristiche rivedute del CAMAC si raccomanda un indirizzo per poter accedere ad un descrittore di modulo, senza definire però il contenuto del descrittore. Il presente documento passa in rassegna le fonti di informazione in merito alle caratteristiche del modulo CAMAC e propone un descrittore a 16 bit.

Samenvatting

In de herziene CAMAC-specificatie wordt een adres aanbevolen voor het toegankelijk maken van een module beschrijvingswoord, maar wordt de inhoud van de descriptor niet gedefinieerd. In dit document wordt een overzicht gegeven van de bronnen van informatie over de karak-teristieken van een CAMAC-module en wordt een 16-bit beschrijvingswoord voorgesteld.

Резюме

Модифицированные спецификации САМАС рекомендуют адрес для дескриптора блока но не определяет содержания этого слова. Рассмотрены источники информации харак-терные для блоков САМАС и предложено 16-битовое слово дескриптора.

Isolator Stage for the CAMAC Branch Highway System W. Tebra

Summary

Interference from spurious common-mode signals and high-tension breakdowns in experiments can cause serious trouble in CAMAC systems. A light-coupled isolator stage in the branch highway is then helpful. Such a highway isolator has been used since January 1972, and drives several crates located at up to 100 m from the computer.

Zusammenfassung

Gleichtakt-Störsignale und Unterbrechungen der Hoch-spannungsversorgung bei Experimenten können zu ernsten Störungen in CAMAC-Systemen führen. Die Probleme können durch eine Isolator-Stufe im Branch Highway überwunden werden. Ein solcher Isolator ist seit Januar 1972 im Einsatz; er steuert mehrere Rahmen, die bis zu 100 m vom Rechner entfernt sind.

Résumé

Au cours d'expériences, des signaux parasites en mode commun et des coupures de hautes tensions peuvent provoquer de graves perturbations dans les systèmes CAMAC. Un étage d'isolement optoélectronique placé sur l'interconnexion de branche est alors très utile. Un tel isolateur a été utilisé depuis janvier 1972; il commande divers châssis situés jusqu'à 100 m de l'ordinateur.

Riassunto

Interferenze da segnali spuri di modo comune e scariche ad alta tensione in esperimenti possono provocare gravi disturbi ai sistemi CAMAC. A tale scopo è utile installare uno stadio d'isolamento accoppiato a luce nel collegamento del ramo principale. Tale isolatore sul ramo è in uso dal gennaio 1972 e aziona vari contenitori situati fino a 100 metri di distanza dal calcolatore.

Samenvatting

Interferentie afkomstig van storende gemeenschappelijke-modussignalen en hoogspanningstoringen kunnen in CAMAC-systemen ernstige moeilijkheden veroorzaken. Een licht-gekoppelde isolatorfase in de hoofdlijnvertakking kan in een dergelijk geval nutig zijn. Van een dergelijke hoofd-lijnisolator wordt sinds januari 1972 gebruik gemaakt en bekrachtigt verschillende crates tot op een afstand van 100 m van de computer m van de computer.

Резюме

Помехи от паразитных сигналов и высоковольтных разряжении в эксперименте могут быть причиной серёзных ошибок в системах САМАС. Полезным является применение в ветви изолирующей степени со световом сцеплением. Такие степени используется с января 1972 г. при управлении несколькими крейтами расположенными на расстоянии до 100 м от ЭВМ.

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